

## **Lecture 5: Eigenvalues and Eigenvectors**

CEDC102: Linear Algebra

Manara University

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- Eigenvalues and Eigenvectors
- Diagonalization and Powers of A



Introduction Eigenvalues and Eigenvectors

• Eigenvalue problem:

If A is an  $n \times n$  matrix, do there exist <u>nonzero vectors</u> x in  $R^n$  such that Ax is a scalar multiple of x?

- Eigenvalue and eigenvector:
  - A: an  $n \times n$  matrix
  - $\lambda$ : a scalar
  - **x**: <u>a nonzero vector</u> in  $\mathbb{R}^n$

Eigenvalue  $Ax = \lambda x$ Eigenvector

Geometrical Interpretation:





جَامعة المَـنارة • Ex : (Verifying eigenvalues and eigenvectors)

$$A = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}, \quad X_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad X_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$Ax_{1} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 2x_{1}$$
  
**Eigenvector**  
**Eigenvalue**  

$$Ax_{2} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = (-1)x_{2}$$
  
**Eigenvector**

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## • Theorem: (The eigenspace of A corresponding to $\lambda$ )

If A is an  $n \times n$  matrix with an eigenvalue  $\lambda$ , then the set of <u>all eigenvectors of  $\lambda$ </u> together with <u>the zero vector</u> is a subspace of  $R^n$ . This subspace is called the eigenspace of  $\lambda$ .

 $(0, y) \uparrow (0, y) (x, y)$ 

(-x, y)

-x.0

• Ex 2: (An example of eigenspaces in the plane)

Find the eigenvalues and corresponding eigenspaces of

$$A = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

Sol:

If 
$$\mathbf{v} = (x, y)$$
, then  $A\mathbf{v} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -x \\ y \end{bmatrix}$ 

For a vector on the x-axis  

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} -x \\ 0 \end{bmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix} \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ y \end{bmatrix}$$

Geometrically, multiplying a vector (x, y) in  $R^2$  by the matrix A corresponds to a reflection in the y-axis.

The eigenspace corresponding to  $\lambda_1 = -1$  is the *x*-axis.

The eigenspace corresponding to  $\lambda_2 = 1$  is the *y*-axis.



- Theorem : (Finding eigenvalues and eigenvectors of a matrix  $A \in M_{n \times n}$ ) Let A is an  $n \times n$  matrix.
  - (1) An eigenvalue of A is a scalar  $\lambda$  such that  $\det(\lambda I A) = 0$
  - (2) The eigenvectors of A corresponding to  $\lambda$  are the nonzero solutions of  $(\lambda I A)\mathbf{x} = \mathbf{0}$
- Note:

 $A\mathbf{x} = \lambda \mathbf{x} \Rightarrow (\lambda I - A)\mathbf{x} = \mathbf{0}$  (homogeneous system)

If  $(\lambda I - A)\mathbf{x} = \mathbf{0}$  has nonzero solutions iff  $det(\lambda I - A) = 0$ 

• Characteristic polynomial of  $A \in M_{n \times n}$ :

$$\det(\lambda I - A) = \left| (\lambda I - A) \right| = \lambda^n + c_{n-1}\lambda^{n-1} + \dots + c_1\lambda + c_0$$



- Characteristic polynomial of  $A \in M_n$ :  $\det(\lambda I - A) = |(\lambda I - A)| = p_A(\lambda) = \lambda^n + c_{n-1}\lambda^{n-1} + \dots + c_1\lambda + c_0$
- Properties of the characteristic polynomial:

$$\lambda = 0 \implies \det(-A) = c_0 \implies c_0 = (-1)^n \det(A)$$
  
 $c_{n-1} = -\operatorname{tr}(A)$ 

• Properties of the eigenvalues:

 $det(A) = \lambda_1 \lambda_2 \cdots \lambda_n$  $tr(A) = a_{11} + a_{22} + \cdots + a_{nn} = \lambda_1 + \lambda_2 + \cdots + \lambda_n$ 

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• Characteristic equation of A:  $det(\lambda I - A) = 0$ 

• Ex : (Finding eigenvalues and eigenvectors)

$$A = \begin{bmatrix} 2 & -12 \\ 1 & -5 \end{bmatrix}$$

## Sol:

Characteristic equation:

$$det(\lambda I - A) = \begin{vmatrix} \lambda - 2 & 12 \\ -1 & \lambda + 5 \end{vmatrix} = \lambda^2 + 3\lambda + 2 = (\lambda + 1)(\lambda + 2) = 0$$
  
$$\Rightarrow \lambda = -1, -2$$

Eigenvalues:  $\lambda_1 = -1$ ,  $\lambda_2 = -2$ 

$$(1) \lambda_{1} = -1 \Rightarrow (\lambda_{1}I - A)\mathbf{x} = \begin{bmatrix} -3 & 12 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} -3 & 12 \\ -1 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & -4 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 4t \\ t \end{bmatrix} = t \begin{bmatrix} 4 \\ 1 \end{bmatrix}, \ t \neq 0$$
$$(2) \lambda_{2} = -2 \Rightarrow (\lambda_{2}I - A)\mathbf{x} = \begin{bmatrix} -4 & 12 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} -4 & 12 \\ -1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} -4 & 12 \\ -1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 3t \\ t \end{bmatrix} = t \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \ t \neq 0$$
Check:  $A\mathbf{x} = \lambda \mathbf{x}$ 



• Ex : (Finding eigenvalues and eigenvectors)

Find the eigenvalues and corresponding eigenvectors for the matrix A. What is the dimension of the eigenspace of each eigenvalue?

$$A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

Sol:

Characteristic equation:

$$\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 2 & -1 & 0 \\ 0 & \lambda - 2 & 0 \\ 0 & 0 & \lambda - 2 \end{vmatrix} = (\lambda - 2)^3 = 0$$
 Eigenvalue:  $\lambda = 2$ 



$$(\lambda I - A)\mathbf{x} = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \implies \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} s \\ 0 \\ t \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad s \text{ and } t \text{ not both zero}$$
$$\begin{cases} s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} s, t \in R \\ \text{has two linearly independent eigenvectors} \end{cases} \quad \text{the eigenspace of } A \text{ corresponding to } \lambda = 2$$

Thus, the dimension of its eigenspace is 2.



## • Notes:

- (1) If an eigenvalue  $\lambda_1$  occurs as a multiple root (k times) for the characteristic polynomial, then  $\lambda_1$  has multiplicity k.
- (2) The multiplicity of an eigenvalue is greater than or equal to the dimension of its eigenspace.



• Ex : Find the eigenvalues of the matrix A and find a basis for each of the corresponding eigenspaces.  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 5 & -10 \\ 1 & 0 & 2 & 0 \\ 1 & 0 & 0 & 3 \end{bmatrix}$ 

## Sol:

Characteristic equation:

$$\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 1 & 0 & 0 & 0 \\ 0 & \lambda - 1 & -5 & 10 \\ -1 & 0 & \lambda - 2 & 0 \\ -1 & 0 & 0 & \lambda - 3 \end{vmatrix} = (\lambda - 1)^2 (\lambda - 2)(\lambda - 3) = 0$$

Eigenvalues:  $\lambda_1 = 1$ ,  $\lambda_2 = 2$ ,  $\lambda_3 = 3$ 

$$(1) \ \lambda_{1} = 1 \Rightarrow (\lambda_{1}I - A)\mathbf{x} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -5 & 10 \\ -1 & 0 & -1 & 0 \\ -1 & 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \\ X_{4} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -5 & 10 \\ -1 & 0 & -1 & 0 \\ -1 & 0 & 0 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \end{bmatrix} = \begin{bmatrix} -2t \\ s \\ 2t \\ t \end{bmatrix} = s \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 2 \\ 1 \end{bmatrix}; s, t \neq 0$$

 $\Rightarrow \left\{ \begin{bmatrix} 0\\1\\0\\2 \end{bmatrix}, \begin{bmatrix} -2\\0\\2\\2 \end{bmatrix} \right\}$  is a basis for the eigenspace of *A* corresponding to  $\lambda = 1$ 

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$$(2) \lambda_{2} = 2 \Rightarrow (\lambda_{2}I - A)\mathbf{x} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -5 & 10 \\ -1 & 0 & 0 & 0 \\ -1 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -5 & 10 \\ -1 & 0 & 0 & 0 \\ -1 & 0 & 0 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -5 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{bmatrix} = \begin{bmatrix} 0 \\ 5t \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} 0 \\ 51 \\ 0 \end{bmatrix}; \ t \neq 0$$
$$\Rightarrow \left\{ \begin{bmatrix} 0 \\ 5 \\ 1 \\ 0 \end{bmatrix} \right\} \text{ is a basis for the eigenspace of } A \text{ corresponding to } \lambda = 0$$

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$$(3) \lambda_{3} = 3 \Rightarrow (\lambda_{3}I - A)\mathbf{x} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & -5 & 10 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & -5 & 10 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{bmatrix} = \begin{bmatrix} 0 \\ -5t \\ 0 \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ -5 \\ 0 \\ 1 \end{bmatrix}; \ t \neq 0$$
$$\Rightarrow \left\{ \begin{bmatrix} 0 \\ -5 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis for the eigenspace of } A \text{ corresponding to } \lambda = 3 \end{bmatrix}$$



# • Theorem : (Eigenvalues of triangular matrices)

If A is an  $n \times n$  triangular matrix, then its eigenvalues are the entries on its main diagonal.

• Ex: (Finding eigenvalues for diagonal and triangular matrices)

Sol:

(a) 
$$|\lambda I - A| = \begin{vmatrix} \lambda - 2 & 0 & 0 \\ 1 & \lambda - 1 & 0 \\ -5 & -3 & \lambda + 3 \end{vmatrix} = (\lambda - 2)(\lambda - 1)(\lambda + 3)$$
  
 $\lambda_1 = 2, \lambda_2 = 1, \lambda_3 = -3$ 

b) 
$$\lambda_1 = -1, \lambda_2 = 2, \lambda_3 = 0, \lambda_4 = -4, \lambda_5 = 3$$

Theorem : (Eigenvalues and Invertibility)

A square matrix A is invertible iff  $\lambda = 0$  is not an eigenvalue of A

• Eigenvalues and eigenvectors of linear transformations:

A number  $\lambda$  is an eigenvalue of a linear transformation  $T: V \to V$  when there is a nonzero vector x such that  $T(x) = \lambda x$ . The vector x is an eigenvector of T corresponding to  $\lambda$ , and the set of all eigenvectors of  $\lambda$  (with the zero vector) is the eigenspace of  $\lambda$ .

• Ex : (Finding eigenvalues and eigenspaces) Find the eigenvalues and corresponding eigenspaces  $A = \begin{bmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & -2 \end{bmatrix}$ Sol:

$$\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 1 & -3 & 0 \\ -3 & \lambda - 1 & 0 \\ 0 & 0 & \lambda + 2 \end{vmatrix} = (\lambda + 2)^2 (\lambda - 4)$$

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Eigenvalues:  $\lambda_1 = 4, \lambda_2 = -2$ 

The eigenspaces for these two eigenvalues are as follows:  $B_1 = \{(1, 1, 0)\}$  Basis for  $\lambda_1 = 4$  $B_2 = \{(1, -1, 0), (0, 0, 1)\}$  Basis for  $\lambda_2 = -2$ 



### Notes:

(1) If  $T: R^3 \to R^3$  is the linear transformation whose standard matrix is A, and B' is a basis for  $R^3$  made up of the three linearly independent eigenvectors corresponding to the eigenvalues of A, then the matrix A' for T relative to the basis B' is diagonal.





(2) The main diagonal entries of the matrix A' are the eigenvalues of A.



## Diagonalization

Diagonalization problem:

For a square matrix A, does there exist an invertible matrix P such that  $P^{-1}AP$  is diagonal?

## • Diagonalizable matrix:

A square matrix A is called diagonalizable if there exists an invertible matrix P such that  $P^{-1}AP$  is a diagonal matrix. (*P* diagonalizes *A*)

## • Note:

If there exists an invertible matrix *P* such that  $B = P^{-1}AP$ , then two square matrices *A* and *B* are called similar. and the transformation from *A* to  $P^{-1}AP$  is called a similarity transformation



Property that is preserved by a similarity transformation is called similarity invariant. Table below lists the most important similarity invariants

Property	Description
Determinant	A and $P^{-1}AP$ have the same determinant
Invertibility	A is invertible if and only if $P^{-1}AP$ is invertible
Rank	A and P-1AP have the same rank
Nullity	A and P-1AP have the same nullity
Trace	A and P-1AP have the same trace
Characteristic polynomial	A and P-1AP have the same characteristic polynomial
Eigenvalues	A and $P^{-1}AP$ have the same eigenvalues
Eigenspace dimension	A and $P^{-1}AP$ have the same dimension for the same $\lambda$



• Ex : (A diagonalizable matrix)

$$A = \begin{bmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

Sol: Characteristic equation:

$$\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 1 & -3 & 0 \\ -3 & \lambda - 1 & 0 \\ 0 & 0 & \lambda + 2 \end{vmatrix} = (\lambda - 4)(\lambda + 2)^2 = 0$$
  
Eigenvalues:  $\lambda_1 = 4, \lambda_2 = -2, \lambda_3 = -2$   
(1)  $\lambda_1 = 4 \Rightarrow$  Eigenvector:  $p_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ 

$$(2) \lambda_{2} = -2 \Rightarrow \text{Eigenvectors:} \ p_{2} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \ p_{3} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$
$$P = \begin{bmatrix} p_{1} & p_{2} & p_{3} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \implies P^{-1}AP = \begin{bmatrix} 4 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$
$$\textbf{Notes:}$$
$$(1) P = \begin{bmatrix} p_{2} & p_{1} & p_{3} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \implies P^{-1}AP = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$
$$(2) P = \begin{bmatrix} p_{2} & p_{3} & p_{1} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \implies P^{-1}AP = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$



• Theorem : (Condition for diagonalization)

An  $n \times n$  matrix A is diagonalizable if and only if it has n linearly independent eigenvectors.

• Note:

If *n* linearly independent vectors do not exist, then an  $n \times n$  matrix A is not diagonalizable.

• Ex : (A matrix that is not diagonalizable)

 $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ 

Sol: Characteristic equation:

$$\left|\lambda I - A\right| = \begin{vmatrix}\lambda - 1 & -2\\0 & \lambda - 1\end{vmatrix} = (\lambda - 1)^2 = 0$$
 Eigenvalue:  $\lambda_1 = 1$ 

$$\lambda I - A = I - A = \begin{bmatrix} 0 & -2 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \implies \text{Eigenvector: } p_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

A does not have two (n=2) L. I. eigenvectors, so A is not diagonalizable

- Steps for diagonalizing an  $n \times n$  square matrix:
  - Step 1: Find *n* linearly independent eigenvectors  $p_1, p_2, \dots p_n$  for *A* with corresponding eigenvalues  $\lambda_1, \lambda_2, \dots \lambda_n$

Step 2: Let 
$$P = \begin{bmatrix} p_1 \mid p_2 \mid \cdots \mid p_n \end{bmatrix}$$
  
Step 3: Let  $P^{-1}AP = D = \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix}$ , where  $Ap_i = \lambda_i p_i$ ,  $i = 1, 2, \dots, n$ 



## • Note:

The order of the eigenvalues used to form P will determine the order in which the eigenvalues appear on the main diagonal of D.

• Ex : (Diagonalizing a matrix)

Find a matrix P such that is  $P^{-1}AP$  diagonal  $A = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix}$ 

Sol: Characteristic equation:

 $\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 1 & 1 & 1 \\ -1 & \lambda - 3 & -1 \\ 3 & -1 & \lambda + 1 \end{vmatrix} = (\lambda - 2)(\lambda + 2)(\lambda - 3) = 0$ Eigenvalues:  $\lambda_1 = 2, \lambda_2 = -2, \lambda_3 = 3$ 

$$(1) \lambda_{1} = 2 \qquad \Rightarrow \lambda_{1}I - A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & -1 & -1 & -1 \\ 3 & -1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \text{Eigenvector: } P_{1} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$
$$(2) \lambda_{2} = -2 \Rightarrow \lambda_{2}I - A = \begin{bmatrix} -3 & 1 & 1 \\ -1 & -5 & -1 \\ 3 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1/4 \\ 0 & 1 & 1/4 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\Rightarrow \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} (1/4)t \\ t \\ t \end{bmatrix} = \frac{1}{4}t \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} \Rightarrow \text{Eigenvector: } P_{2} = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$$

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$$(3) \lambda_{3} = 3 \implies \lambda_{3}I - A = \begin{bmatrix} 2 & 1 & 1 \\ -1 & 0 & -1 \\ 3 & -1 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\implies \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} -t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \implies \text{Eigenvector: } P_{3} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$
$$\text{Let } P = \begin{bmatrix} p_{1} & p_{2} & p_{3} \end{bmatrix} = \begin{bmatrix} -1 & 1 & -1 \\ 0 & -1 & 1 \\ 1 & 4 & 1 \end{bmatrix}$$
$$\implies P^{-1}AP = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$



• Notes: k is a positive integer

$$(1) D = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_n \end{bmatrix} \implies D^k = \begin{bmatrix} d_1^k & 0 & \cdots & 0 \\ 0 & d_2^k & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_n^k \end{bmatrix}$$

(2)  $D = P^{-1}AP \implies D^k = (P^{-1}AP)^k = P^{-1}A^kP \implies A^k = PD^kP^{-1}$ 

• Ex : (Powers of a Matrix)

Find  $A^6$ , where

$$A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$$

Sol:

Eigenvalues: 
$$\lambda_1 = 1$$
,  $\lambda_2 = 2$  double  $p_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ ,  $p_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $p_3 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$ 

$$P = \begin{bmatrix} -1 & 0 & -2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}, P^{-1} = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \end{bmatrix}, D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$A^{6} = PD^{6}P^{-1} = \begin{bmatrix} -1 & 0 & -2 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2^{6} & 0 & 0 \\ 0 & 2^{6} & 0 \\ 0 & 0 & 1^{6} \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -62 & 0 & -126 \\ 63 & 64 & 63 \\ 63 & 0 & 127 \end{bmatrix}$$



- Theorem : (Sufficient conditions for diagonalization)
   If an *n*×*n* matrix *A* has *n* distinct eigenvalues, then the corresponding eigenvectors are linearly independent and *A* is diagonalizable.
- Ex : (Determining whether a matrix is diagonalizable)

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & -3 \end{bmatrix}$$

Sol:

Because A is a triangular matrix, its eigenvalues are the main diagonal entries.  $\lambda_1 = 1, \lambda_2 = 0, \lambda_3 = -3$ 

These three values are distinct, so A is diagonalizable.



If  $\lambda_0$  is an eigenvalue of an  $n \ge n$  matrix A, then the dimension of the eigenspace corresponding to  $\lambda_0$  is called the geometric multiplicity of  $\lambda_0$ , and the number of times that  $\lambda - \lambda_0$  appears as a factor in the characteristic polynomial of A is called the algebraic multiplicity of  $\lambda_0$ 

Theorem : (Geometric and Algebraic Multiplicity)

If A is a square matrix, then:

- (a) For every eigenvalue of A, the geometric multiplicity is less than or equal to the algebraic multiplicity.
- (b) A is diagonalizable if and only if the geometric multiplicity of every eigenvalue is equal to the algebraic multiplicity



- Theorem : (Eigenvalues and Eigenvectors of Matrix Powers)
- If k is a positive integer,  $\lambda$  is an eigenvalue of a matrix A, and x is a corresponding eigenvector, then  $\lambda^k$  is an eigenvalue of  $A^k$  and x is a corresponding eigenvector

 $A = \begin{vmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{vmatrix}$ 

• Ex : Find the eigenvalues and corresponding eigenvectors of  $A^7$ 

## Sol:

The eigenvalues of A are  $\lambda_1 = 2, \lambda_2 = -2, \lambda_3 = 3$ 

The eigenvalues of  $A^7$  are  $\lambda_1 = 2^7 = 128$ ,  $\lambda_2 = (-2)^7 = -128$ ,  $\lambda_3 = 3^7 = 2187$ 

The Eigenvectors of 
$$A^7$$
 are:  $p_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ ,  $p_2 = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$ ,  $p_3 = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$