

CECC507: Signals and Systems Lecture Notes 6: Fourier Analysis for Continuous Time Signals and Systems: Part B



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Fourier Analysis for Continuous Time Signals and Systems



Chapter 4

Fourier Analysis for Continuous Time Signals and Systems

Introduction

2 Analysis of Periodic Continuous-Time Signals

3 Analysis of Non-Periodic Continuous-Time Signals

4 Energy and Power in the Frequency Domain

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Properties of Fourier transform

Linearity of the Fourier transform: $\mathcal{F}\{\alpha_1 x(t) + \alpha_2 y(t)\} = \alpha_1 \mathcal{F}\{x(t)\} + \alpha_2 \mathcal{F}\{y(t)\}$ Duality property: $x(t) \xleftarrow{\mathcal{F}} X(\omega) \implies X(t) \xleftarrow{\mathcal{F}} 2\pi x(-\omega)$ Duality property (using *f*): $x(t) \xleftarrow{\mathcal{F}} X(f) \implies X(t) \xleftarrow{\mathcal{F}} x(-f)$

• Example 1: Fourier transform of the sinc function $F\left\{\frac{1}{2\pi}\Pi\left(\frac{t}{2\pi}\right)\right\} = \operatorname{sinc}(\omega) \Rightarrow$ $F\left\{\operatorname{sinc}(t)\right\} = \Pi\left(\frac{-\omega}{2\pi}\right) = \Pi\left(\frac{\omega}{2\pi}\right)$ $F\left\{\operatorname{sinc}(t)\right\} = \Pi(f)$



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- Example 2: Transform of a constant-amplitude signal $F\{\delta(t)\} = 1$, all $\omega \Rightarrow F\{1\} = 2\pi\delta(-\omega) = 2\pi\delta(\omega)$, $F\{1\} = \delta(f)$ (duality)
- Example 3: Fourier transform of the unit-step function



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Symmetry of the Fourier transform

 $x(t): \text{ real, } \operatorname{Im}\{x(t)\} = 0 \Longrightarrow X^*(\omega) = X(-\omega)$ $\tilde{x}(t): \text{ imag, } \operatorname{Re}\{\tilde{x}(t)\} = 0 \Longrightarrow X^*(\omega) = -X(-\omega)$

Transforms of even and odd signals

 If the real-valued signal x(t) is an even function of time, the resulting Fourier transform X(ω) is real-valued for all ω.

x(-t) = x(t), for all $t \implies \text{Im}\{X(\omega)\} = 0$, for all ω

• If the real-valued signal x(t) has odd-symmetry, the resulting Fourier transform $X(\omega)$ is purely imaginary.

x(-t) = -x(t), for all $t \Rightarrow \operatorname{Re}\{X(\omega)\} = 0$, for all ω

Time shifting
$$x(t) \xleftarrow{\mathcal{F}} X(\omega) \Rightarrow x(t-\tau) \xleftarrow{\mathcal{F}} X(\omega) e^{-j\omega\tau}$$

Frequency shifting $x(t) \xleftarrow{\mathcal{F}} X(\omega) \Rightarrow x(t)e^{j\omega_0 t} \xleftarrow{\mathcal{F}} X(\omega-\omega_0)$
Modulation property $x(t) \xleftarrow{\mathcal{F}} X(\omega) \Rightarrow$
 $x(t) \cos(\omega_0 t) \xleftarrow{\mathcal{F}} \frac{1}{2} [X(\omega-\omega_0) + X(\omega+\omega_0)]$
 $x(t) \sin(\omega_0 t) \xleftarrow{\mathcal{F}} \frac{1}{2} [X(\omega-\omega_0)e^{-j\pi/2} + X(\omega+\omega_0)e^{j\pi/2}]$

Example 4: Modulated pulse

$$x(t) = \begin{cases} \cos(2\pi f_0 t), & |t| < \tau \\ 0, & |t| > \tau \end{cases}$$

Using p(t), the signal x(t) can be expressed as $x(t) = p(t)\cos(2\pi f_0 t)$



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Time and frequency scaling

$$x(t) \xleftarrow{\mathcal{F}} X(\omega) \implies x(at) \xleftarrow{\mathcal{F}} \frac{1}{|a|} X(\frac{\omega}{a})$$

The parameter *a* is any non-zero and real-valued constant.

Differentiation in the time domain

$$x(t) \longleftrightarrow X(\omega) \Rightarrow \frac{d^n}{dt^n} [x(t)] \longleftrightarrow (j\omega)^n X(\omega), \quad \frac{d^n}{dt^n} [x(t)] \longleftrightarrow (j2\pi f)^n X(f)$$

• Example 5: Triangular pulse revisited

$$x(t) = A\Lambda(t/\tau)$$

$$w(t) = \frac{dx(t)}{dt} = \frac{A}{\tau} \left[\Pi\left(\frac{t+\tau/2}{\tau}\right) - \Pi\left(\frac{t-\tau/2}{\tau}\right) \right]$$

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 $-\tau$

w(t)

au

 τ

$$W(f) = A \operatorname{sinc}(f\tau) e^{j2\pi f(\tau/2)} - A \operatorname{sinc}(f\tau) e^{-j2\pi f(\tau/2)} = 2jA \operatorname{sinc}(f\tau) \operatorname{sin}(\pi f\tau)$$
$$W(f) = (j2\pi f) X(f) \Rightarrow X(f) = \frac{W(f)}{j2\pi f} = \frac{2jA \operatorname{sinc}(f\tau) \operatorname{sin}(\pi f\tau)}{j2\pi f} = A\tau \operatorname{sinc}^2(f\tau)$$

Differentiation in the frequency domain

$$x(t) \stackrel{\mathcal{F}}{\longleftrightarrow} X(\omega) \implies (-jt)^n x(t) \stackrel{\mathcal{F}}{\longleftrightarrow} \frac{d^n}{d\omega^n} [X(\omega)]$$

Convolution property $x_1(t) \xleftarrow{\mathcal{F}} X_1(\omega)$ and $x_2(t) \xleftarrow{\mathcal{F}} X_2(\omega)$ $\Rightarrow x_1(t) * x_2(t) \xleftarrow{\mathcal{F}} X_1(\omega) X_2(\omega)$

Multiplication of two signals $x_1(t) \xleftarrow{\mathcal{F}} X_1(\omega)$ and $x_2(t) \xleftarrow{\mathcal{F}} X_2(\omega)$ $\Rightarrow x_1(t)x_2(t) \xleftarrow{\mathcal{F}} \frac{1}{2\pi} X_1(\omega) * X_2(\omega), \quad x_1(t)x_2(t) \xleftarrow{\mathcal{F}} X_1(f) * X_2(f)$

$$Integration \ x(t) \longleftrightarrow X(\omega) \implies \int_{-\infty}^{t} x(\tau) d\tau \longleftrightarrow \frac{X(\omega)}{j\omega} + \pi X(0) \delta(\omega)$$

Applying Fourier transform to periodic signals

Example 6: Fourier transform of complex exponential signal
X(\overline)

$$F\{1\} = 2\pi\delta(\omega) \implies F(e^{j\omega_0 t}) = 2\pi\delta(\omega - \omega_0)$$

• Example 7: Fourier transform of sinusoidal signal $x(t) = \cos(\omega_0 t)$ $T\{1\} = 2\pi\delta(\omega) \Rightarrow T\{\cos(\omega_0 t)\} = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$

 $x(t) = e^{j\omega_0 t}$

 The idea can be generalized to apply to any periodic continuous-time signal that has an EFS representation:

wo

$$\tilde{x}(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_k t} \Rightarrow X(\omega) = \int_{-\infty}^{\infty} \tilde{x}(t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} \left[\sum_{k=-\infty}^{\infty} c_k e^{jk\omega_k t}\right] e^{-j\omega t} dt$$

$$X(\omega) = \sum_{k=-\infty}^{\infty} c_k \left[\int_{-\infty}^{\infty} e^{jk\omega_k t} e^{-j\omega t} dt\right] = \sum_{k=-\infty}^{-1} c_k \left[2\pi\delta(\omega - k\omega_0)\right]$$

$$= \sum_{k=-\infty}^{\infty} c_k \left[2\pi\delta(\omega - k\omega_0)\right]$$

$$EFS \text{ coefficients for a signal Fourier transform obtained}$$
Example 8: Fourier transform of periodic pulse train
Determine the FT of the periodic pulse train with duty cycle $d = d'T_0$

$$c_k = d \operatorname{sinc} (kd) \quad X(\omega) = \sum_{k=-\infty}^{\infty} 2\pi d \operatorname{sinc} (kd) \delta(\omega - k\omega_0)$$

$$\omega_0 = 1/T_0 \text{ is the fundamental radian frequency.}$$

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4. Energy and Power in the Frequency Domain Parseval's theorem

• For a periodic power signal $\tilde{x}(t)$ with period T_0 and EFS coefficients $\{c_k\}$:

$$\frac{1}{T_0} \int_{t_0}^{t_0 + T_0} \left| \tilde{x}(t) \right|^2 dt = \sum_{k = -\infty}^{\infty} |c_k|^2$$

For a non-periodic energy signal x(t) with a Fourier transform X(f):

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} |X(f)|^2 df$$

Energy and power spectral density

$$S_x(f) = \sum_{k=-\infty}^{\infty} |c_k|^2 \delta(f - kf_0)$$
 power spectral density of the signal $x(t)$

$$\int_{-\infty}^{\infty} S_x(f) df = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) d\omega = \sum_{k=-\infty}^{\infty} |c_k|^2$$

$$P_x \text{ in } (-f_0, f_0) = \int_{-f_0}^{f_0} S_x(f) df$$

$$G_x(f) = |X(f)|^2 \quad \text{energy spectral density of the signal } x(t)$$

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} G_x(f) df = \frac{1}{2\pi} \int_{-\infty}^{\infty} G_x(\omega) d\omega$$

Example 9: Power spectral density of a periodic pulse train
 Determine the power spectral density for *x*(*t*). Also find the total power, the dc power, the power in the first three harmonics, and the power above 1 Hz.

$$c_k = \frac{1}{3}\operatorname{sinc}(k/3)$$
 $S_x(f) = \sum_{k=-\infty}^{\infty} \left|\frac{1}{3}\operatorname{sinc}(k/3)\right|^2 \delta(f - k/3)$

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The total power in the signal
$$x(t)$$
: $\frac{1}{T_0} \int_{t_0}^{t_0+T_0} |\tilde{x}(t)|^2 dt = \frac{1}{3} \int_{-0.5}^{0.5} (1)^2 dt = \frac{1}{3}$

$$P_{1} = |c_{-1}|^{2} + |c_{1}|^{2} = \frac{3}{2\pi^{2}} \approx 0.1520, \quad P_{2} = |c_{-2}|^{2} + |c_{2}|^{2} = \frac{3}{8\pi^{2}} \approx 0.0380, \quad P_{3} = 0$$

The third harmonic is at frequency f = 1 Hz. Thus, the power above 1 Hz:

 $P_{hf} = P_x - P_{dc} - P_1 - P_2 - P_3 = 0.3333 - 0.1111 - 0.1520 - 0.0380 - 0 = 0.0322$

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Example 10: Energy spectral density of the sinc function

Determine the energy spectral density of x(t) = sinc(10t). Afterwards, compute the total energy, and the energy in the sinc pulse at frequencies up to 3 Hz.



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Autocorrelation

For an energy signal x(t) the autocorrelation function is defined as

$$r_{xx}(\tau) = \int_{-\infty}^{\infty} x(t) x(t+\tau) dt$$

• For a periodic power signal $\tilde{x}(t)$ with period T_0 , the corresponding definition of the autocorrelation function is:

$$\tilde{r}_{xx}(\tau) = \frac{1}{T_0} \int_{-T_0/2}^{T_0/2} \tilde{x}(t) \tilde{x}(t+\tau) dt$$

- The energy spectral density is the FT of the autocorrelation function: $F\{r_{xx}(\tau)\} = G_x(f)$
- The power spectral density is the FT of the autocorrelation function: $F{\tilde{r}_{rr}(\tau)} = S_r(f)$



Example 11: Power spectral density of a sinusoidal signal revisited

$$\widetilde{x}(t) = 5\cos(200\pi t)$$

$$\widetilde{r}_{xx}(\tau) = \frac{1}{0.01} \int_{-0.005}^{0.005} 25\cos(200\pi t)\cos(200[t+\tau])dt = \frac{25}{2}\cos(200\pi\tau)$$

$$S_x(f) = F\{\widetilde{r}_{xx}(\tau)\} = \frac{25}{4}\delta(f+100) + \frac{25}{4}\delta(f-100)$$

Properties of the autocorrelation function

- $r_{xx}(0) \ge |r_{xx}(\tau)|$ for all τ
- $r_{xx}(-\tau) = r_{xx}(\tau)$ for all τ , that is, the autocorrelation function has even symmetry.
- If the signal x(t) is periodic with period T, then its autocorrelation function $\tilde{r}_{xx}(\tau)$ is also periodic with the same period.



- 5. Transfer Function Concept
- In time-domain analysis of systems we have relied on two distinct description forms for CTLTI systems:
 - 1. A linear constant-coefficient differential equation that describes the relationship between the input and the output signals.
 - 2. An impulse response which can be used with the convolution operation for determining the response of the system to an arbitrary input signal.
- The concept of Transfer function will be introduced as the third method for describing the characteristics of a system.

$$H(\omega) = F\{h(t)\} = \int_{-\infty}^{\infty} h(t)e^{-j\omega t}dt$$



- The transfer function concept is valid for LTI systems only.
- In general, $H(\omega)$ is a complex function of ω , $H(\omega) = |H(\omega)|e^{j\Theta(\omega)}$.
- Example 12: Transfer function for the simple *RC* circuit



• ω_c represents the frequency at which the magnitude of the transfer function is 3 decibels below its peak value at $\omega = 0$, $20 \log_{10} \frac{|H(\omega_c)|}{|H(0)|} = 20 \log_{10} \frac{1}{\sqrt{2}} \approx -3 \text{dB}$



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 $|H(\omega)|$

 $1/\sqrt{2}$



Example 13: Transfer function from the differential equation

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 26y(t) = x(t)$$
$$(j\omega)^2 Y(\omega) + 2(j\omega) Y(\omega) + 26Y(\omega) = X(\omega)$$
$$[(26 - \omega^2) + j2\omega] Y(\omega) = X(\omega) \Rightarrow H(\omega) = \frac{1}{(26 - \omega^2) + j2\omega}$$

6. CTLTI Systems with Periodic Input Signals

$$\tilde{x}(t) = a_0 + \sum_{k=1}^{\infty} a_k \cos(k\omega_0 t) + \sum_{k=1}^{\infty} b_k \sin(k\omega_0 t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$$

Response of a CTLTI system to complex exponential signal

$$\tilde{x}(t) = e^{j\omega_0 t}$$

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$$y(t) = h(t) * \tilde{x}(t) = \int_{-\infty}^{\infty} h(\tau) \tilde{x}(t-\tau) d\tau = \int_{-\infty}^{\infty} h(\tau) e^{j\omega_0(t-\tau)} d\tau$$
$$= e^{j\omega_0 t} \int_{-\infty}^{\infty} h(\tau) e^{-j\omega_0 \tau} d\tau = e^{j\omega_0 t} H(\omega_0) = |H(\omega_0)| e^{j[\omega_0 t + \Theta(\omega_0)]}$$

• That is, $e^{j\omega t}$ is an eigenfunction of a LTI system and $H(\omega)$ is the corresponding eigenvalue. We refer to H as the frequency response of the system.

Response of a CTLTI system to sinusoidal signal

$$\begin{split} \widetilde{x}(t) &= \cos(\omega_0 t) = \frac{1}{2}e^{j\omega_0 t} + \frac{1}{2}e^{-j\omega_0 t} \\ y(t) &= \frac{1}{2}e^{j\omega_0 t}H(\omega_0) + \frac{1}{2}e^{-j\omega_0 t}H(-\omega_0) \\ &= \frac{1}{2}e^{j\omega_0 t}\left|H(\omega_0)\right|e^{j\Theta(\omega_0)} + \frac{1}{2}e^{-j\omega_0 t}\left|H(-\omega_0)\right|e^{-j\Theta(\omega_0)} \\ \end{split}$$
If the impulse response $h(t)$ is real-valued:

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$$\begin{split} &|H(-\omega_0)| = |H(\omega_0)|, \quad \Theta(-\omega_0) = -\Theta(\omega_0) \\ &y(t) = \frac{1}{2} |H(\omega_0)| e^{j[\omega_0 t + \Theta(\omega_0)]} + \frac{1}{2} |H(\omega_0)| e^{-j[\omega_0 t + \Theta(\omega_0)]} = |H(\omega_0)| \cos(\omega_0 t + \Theta(\omega_0)) \end{split}$$

Response of a CTLTI system to periodic input signal

$$\tilde{x}(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$$

$$T\{\tilde{x}(t)\} = T\left\{\sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}\right\} = \sum_{k=-\infty}^{\infty} T\left\{c_k e^{jk\omega_0 t}\right\} = \sum_{k=-\infty}^{\infty} c_k T\left\{e^{jk\omega_0 t}\right\} = \sum_{k=-\infty}^{\infty} c_k H(k\omega_0) e^{jk\omega_0 t}$$

7. CTLTI Systems with Non-Periodic Input Signals

$$y(t) = h(t) * x(t) \Rightarrow Y(\omega) = H(\omega)X(\omega)$$
$$|Y(\omega)| = |H(\omega)||X(\omega)|, \quad \measuredangle Y(\omega) = \measuredangle X(\omega) + \Theta(\omega)$$

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$$H(f) = \frac{1}{1 + j(f/f_c)}, \quad X(f) = \operatorname{sinc}(f)$$
$$Y(f) = \frac{1}{1 + j(f/80)} \operatorname{sinc}(f),$$
$$|Y(f)| = \frac{1}{\sqrt{1 + (f/80)^2}} |\operatorname{sinc}(f)|,$$
$$\measuredangle Y(f) = -\operatorname{tan}^{-1}(f/80) + \measuredangle[\operatorname{sinc}(f)]$$

