

An harmonic excitation can be described either by means of a sine function:  $p(t)=p_0 \sin \Omega t$ , or by means of a cosine function:  $p(t)=p_0 \cos \Omega t$ .

**Equation of Motion (E.o.M.):** 

$$n\ddot{u} + c\dot{u} + ku = p(t) = \begin{cases} p_0 \cos \Omega t \\ p_0 \sin \Omega t \end{cases}$$

The complete response (solution) will be the sum of the transient (homogenous) and steady-state (particular)components.

$$u(t) = \underbrace{e^{-\xi\omega t} \left(A\cos\omega_{D}t + B\sin\omega_{D}t\right)}_{\text{transient}} + \underbrace{C\cos\Omega t + D\sin\Omega t}_{\text{steady state}}$$
  
Find *C* & *D*, for the cosine and sine functions of harmonic excitation



$$m\ddot{u} + ku = p_0 \cos \Omega t \qquad \qquad \ddot{u} + \omega_n^2 u = (p_0 / m) \cos \Omega t \qquad \qquad \ddot{u} + \omega_n^2 u = \omega_n^2 u_{st} \cos \Omega t$$

A steady-state response (A particular solution) can be

$$(\omega_n^2 - \Omega^2)C = \omega_n^2 u_{st} \qquad C = \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)} \qquad C = \frac{u_{st}}{(1 - r^2)} \quad \text{where} \quad r = \frac{\Omega}{\omega_n}$$

The transient response (The homogeneous solution) is

$$u_h(t) = A \cos \omega_n t + B \sin \omega_n t$$

The complete solution is(A homogeneous solution) is

$$u(t) = A\cos\omega_n t + B\sin\omega_n t + \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)}\cos\Omega t$$

#### **Undamped harmonic vibrations**

$$u(t) = A\cos\omega_n t + B\sin\omega_n t + \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)}\cos\Omega t$$

By means of the initial conditions given by , *l* 

$$u(0) = u_0 \& \dot{u}(0) = \dot{u}_0$$

the constants *A* and *B* can be calculated as follows:

$$A = u_0 - \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)} \& B = \frac{\dot{u_0}}{\omega_n}$$
$$u(t) = \left(u_0 - \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)}\right) \cos \omega_n t + \left(\frac{\dot{u_0}}{\omega_n}\right) \sin \omega_n t + \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)} \cos \Omega t$$

For two null initial conditions the complete solution is,

$$u(t) = \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)} \left(\cos \Omega t - \cos \omega_n t\right)$$





#### **Undamped harmonic vibrations**

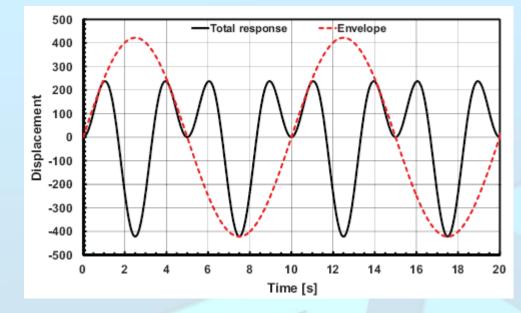
$$u(t) = \frac{\omega_n^2 u_{st}}{(\omega_n^2 - \Omega^2)} \left( \cos \Omega t - \cos \omega_n t \right)$$

Using the trigonometric identity

$$\cos\alpha - \cos\beta = -2\sin\frac{\alpha - \beta}{2}\sin\frac{\alpha + \beta}{2}$$

$$u(t) = \frac{2\omega_n^2 u_{st}}{(\Omega^2 - \omega_n^2)} \sin\left(\frac{\Omega - \omega_n}{2}t\right) \sin\left(\frac{\Omega + \omega_n}{2}t\right)$$

Case 1: Natural frequency SDoF 0.2 Hz, excitation frequency 0.4 Hz.  $\Omega / \omega_n = 2$ 

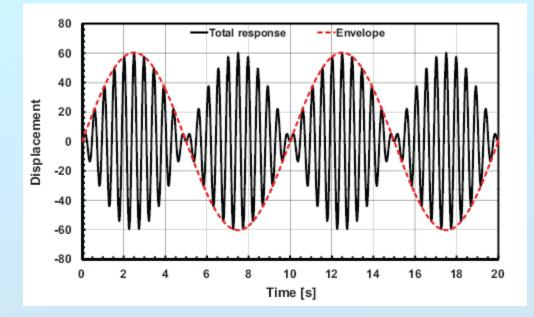






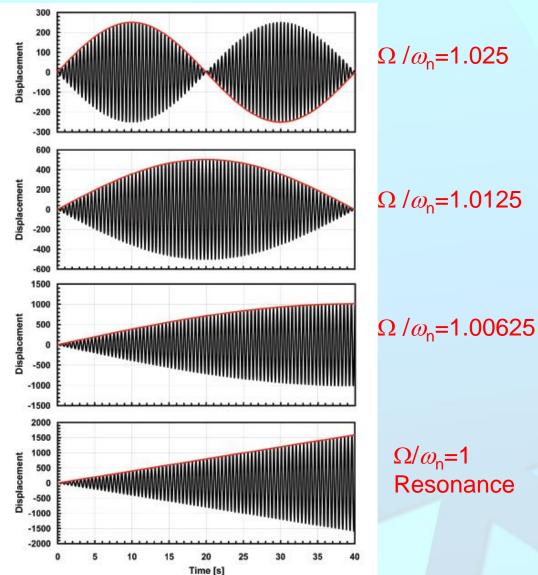
$$u(t) = \frac{2\omega_n^2 u_{st}}{(\Omega^2 - \omega_n^2)} \sin\left(\frac{\Omega - \omega_n}{2}t\right) \sin\left(\frac{\Omega + \omega_n}{2}t\right)$$

Case 2: Natural frequency SDoF 2.0 Hz, excitation frequency 2.2 Hz.  $\Omega / \omega_n = 1.1$ 



A beat is always present, but is more evident when the natural frequency of the SDoF system and the excitation frequency are close







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Resonant excitation ( $\Omega = \omega_n$ )  $\ddot{u} + \omega^2 u = \omega^2 u \cos \Omega t$ 

 $\ddot{u} + \omega_n^2 u = \omega_n^2 u_{st} \cos \Omega t \qquad \qquad \ddot{u} + \omega_n^2 u = \omega_n^2 u_{st} \cos \omega_n t$ 

A steady-state response (A particular solution) could not be  $u_p(t) = C \cos \omega_n t$ 

Another possible choice is  $u_p(t) = Ct \sin \omega_n t$  $\dot{u}_p(t) = C \sin \omega_n t + Ct \omega_n \cos \omega_n t$  $\ddot{u}_p(t) = 2C \omega_n \cos \omega_n t - Ct \omega_n^2 \sin \omega_n t$ 

Substituting into the E. o. M.

 $2C \omega_n \cos \omega_n t - Ct \omega_n^2 \sin \omega_n t + Ct \omega_n^2 \sin \omega_n t = \omega_n^2 u_{st} \cos \omega_n t \qquad 2C = \omega_n u_{st}$ So the particular solution is  $u_p(t) = \left(\frac{\omega_n u_{st}}{2}\right) t \sin \omega_n t$ 



The transient response (The homogeneous solution) is

 $u_h(t) = A \cos \omega_n t + B \sin \omega_n t$ 

The complete solution is(A homogeneous solution) is

$$u(t) = A\cos\omega_n t + B\sin\omega_n t + \left(\frac{\omega_n u_{st}}{2}\right)t\sin\omega_n t$$

By means of the initial conditions given by,  $u(0) = u_0 \& \dot{u}(0) = \dot{u}_0$ 

the constants A and B can be calculated as follows:

$$A = u_0 \& B = \dot{u}_0 / \omega_n$$

$$u(t) = u_0 \cos \omega_n t + \left(\frac{\dot{u_0}}{\omega_n}\right) \sin \omega_n t + \left(\frac{\omega_n u_{st}}{2}\right) t \sin \omega_n t$$

For two null initial conditions the homogeneous part of the solution falls away and the complete solution reduces to the particular solution,

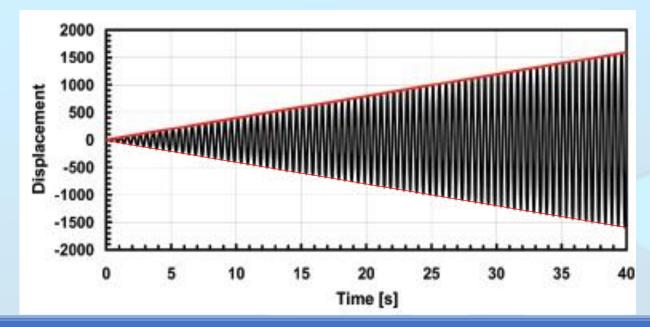
$$u(t) = \left(\frac{\omega_n u_{st}}{2}\right) t \sin \omega_n t$$

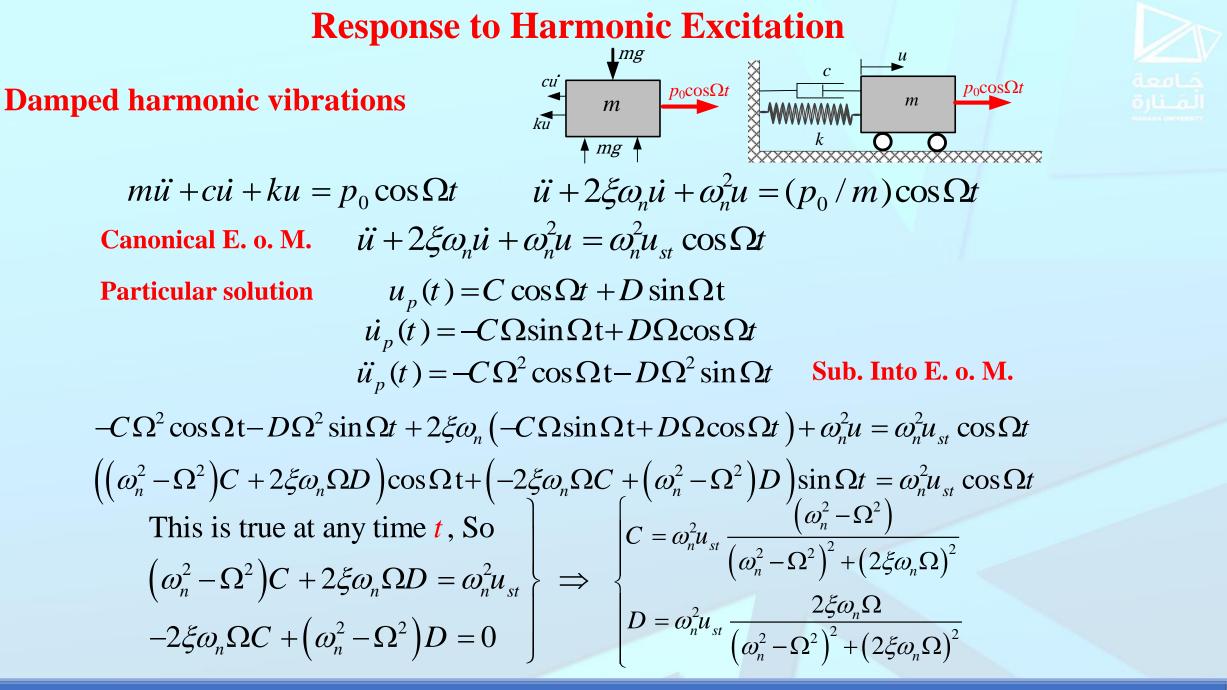


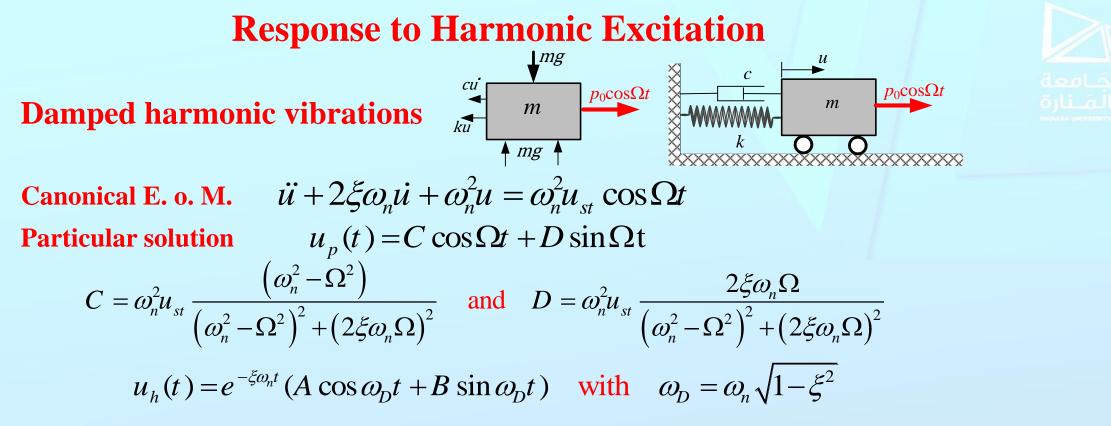
$$u(t) = \left(\frac{\omega_n u_{st}}{2}\right) t \sin \omega_n t$$

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This is a sinusoidal vibration with increasing amplitude:  $C = (\omega_n u_{st}/2)t$ . The amplitude grows linearly with time and when:  $t \to \infty$ ,  $C \to \infty$ . After infinite time the amplitude of the vibration is infinite as well.





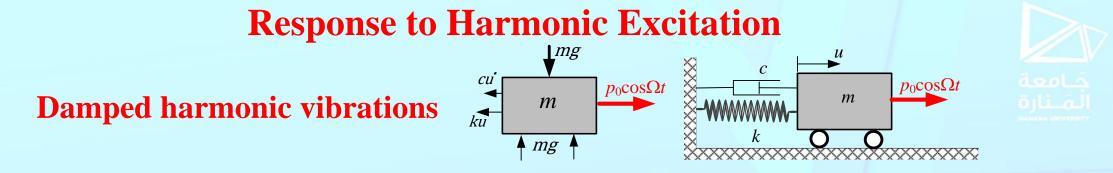


By means of the initial conditions the constants A and B, can be determined

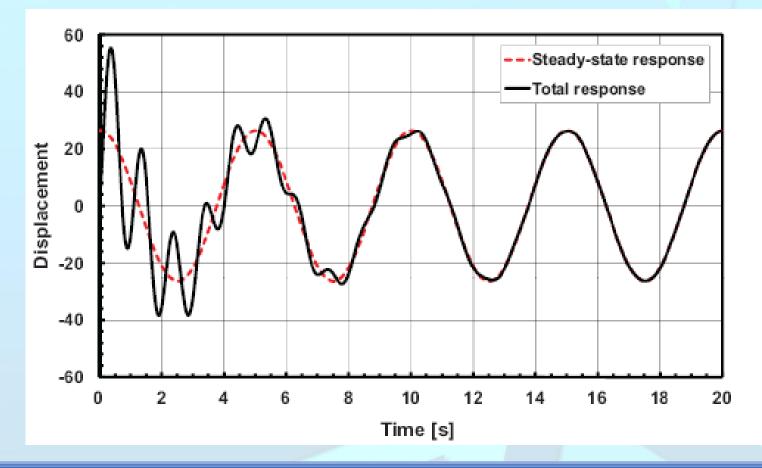
#### **Denominations:**

- Homogeneous part of the solution: "transient"
- Particular part of the solution: "steady-state"

Visualization of the solution is illustrated in the next example

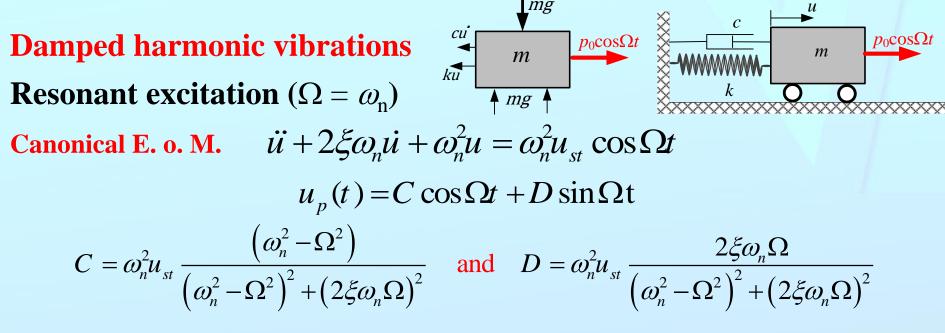


Example 1:  $\omega_n = 2\pi$  [rad/sec],  $\Omega = 0.4\pi$  [rad/sec],  $\xi = 5\%$ ,  $u_{st} = 25$ mm,  $u_0 = 0$ ,  $\dot{u}_0 = u_{st}\omega_n$ 



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By substituting ( $\Omega = \omega_n$ ) in the two expressions constants *C* and *D*, becomes:

$$C = 0$$
 and  $D = \frac{u_{st}}{2\xi}$ 

This means that if damping is present, the resonant excitation is not a special case any more, and the complete solution of the differential equation is:

$$u(t) = e^{-\xi \omega_n t} \left( A \cos \omega_D t + B \sin \omega_D t \right) + \frac{u_{st}}{2\xi} \sin \omega_n t$$





Damped harmonic vibrations Resonant excitation  $(\Omega = \omega_n)$ Canonical E. o. M.  $\ddot{u} + 2\xi\omega_n\dot{u} + \omega_n^2u = \omega_n^2u_{st}\cos\Omega t$   $u_p(t) = C\cos\Omega t + D\sin\Omega t$  $C = \omega_n^2u_{st}\frac{(\omega_n^2 - \Omega^2)}{(\omega_n^2 - \Omega^2)^2 + (2\xi\omega_n\Omega)^2}$  and  $D = \omega_n^2u_{st}\frac{2\xi\omega_n\Omega}{(\omega_n^2 - \Omega^2)^2 + (2\xi\omega_n\Omega)^2}$ 

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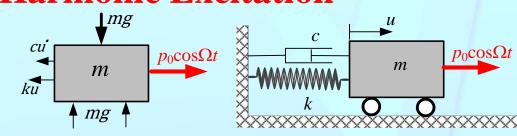
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$$u(t) = e^{-\xi \omega_n t} \left(A \cos \omega_D t + B \sin \omega_D t\right) + \frac{u_{st}}{2\xi} \sin \omega_n t$$





**Damped harmonic vibrations Resonant excitation**  $(\Omega = \omega_n)$ 



$$u(t) = e^{-\xi\omega_n t} (A\cos\omega_D t + B\sin\omega_D t) + \frac{u_{st}}{2\xi}\sin\omega_n t$$

By means of the initial conditions the constants A and B, can be determined. For example in the special case,  $u_0 = 0$  &  $\dot{u}_0 = 0$ , A & B, are

$$A = 0 \quad \text{and} \quad B = -\frac{u_{st}}{2\xi\sqrt{1-\xi^2}}$$
$$u(t) = \frac{u_{st}}{2\xi} \left(\sin\omega_n t - \frac{e^{-\xi\omega_n t}}{\sqrt{1-\xi^2}}\sin\omega_D t\right)$$

After a certain time, the homogeneous part of the solution vanishes and what remains is a sinusoidal oscillation of the maximum limited amplitude:  $(u_{max}=u_{st}/2\xi)$ 

For small damping ratios ( $\xi < 0.2$ ),  $\omega_n \approx \omega_D$  and  $(1 - \xi)^{1/2} \approx 1$ , hence u(t) becomes:

$$u(t) = u_{\max} \left( 1 - e^{-\xi \omega_n t} \right) \sin \omega_n t$$

#### **Dynamic Amplification Factor**

The steady-state displacement of a system due to harmonic excitation is the dominant part of its response. This steady-state response is given by

Where  $C = \omega_n^2 u_{st} \frac{\left(\omega_n^2 - \Omega^2\right)}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}$  and  $D = \omega_n^2 u_{st} \frac{2\xi\omega_n\Omega}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}$ 

By means of the trigonometric identity:

$$a\cos\alpha + b\sin\alpha = (a^2 + b^2)^{1/2}\cos(\alpha - \beta)$$
 with  $\tan\beta = b/a$ 

The steady-state response can be transformed as follows

$$u_p(t) = u_{\max} \cos(\Omega t - \varphi)$$

It is a cosine vibration with the maximum dynamic amplitude  $u_{max}$ , given by

$$u_{\rm max} = (C^2 + D^2)^{1/2}$$

and the phase angle  $\varphi$  obtained from:

$$\tan \varphi = D/C$$



Dynamic Amplification Factor

Substitution of C and D, in  $u_{max}$  expression gives

$$u_{\max} = \sqrt{\left[\omega_n^2 u_{st} \frac{\left(\omega_n^2 - \Omega^2\right)}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}\right]^2 + \left[\omega_n^2 u_{st} \frac{2\xi\omega_n\Omega}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}\right]^2}$$

$$u_{\max} = \omega_n^2 u_{st} \sqrt{\left[\frac{\left(\omega_n^2 - \Omega^2\right)}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}\right]^2 + \left[\frac{2\xi\omega_n\Omega}{\left(\omega_n^2 - \Omega^2\right)^2 + \left(2\xi\omega_n\Omega\right)^2}\right]^2}$$

$$u_{\max} = \omega_n^2 u_{st} \sqrt{\frac{\left[ \left( \omega_n^2 - \Omega^2 \right)^2 + \left( 2\xi \omega_n \Omega \right)^2 \right]^2}{\left[ \left( \omega_n^2 - \Omega^2 \right)^2 + \left( 2\xi \omega_n \Omega \right)^2 \right]^2}}$$
$$u_{\max} = \omega_n^2 u_{st} \frac{1}{\sqrt{\left( \omega_n^2 - \Omega^2 \right)^2 + \left( 2\xi \omega_n \Omega \right)^2}}}$$
$$DAF = \frac{u_{\max}}{u_{st}} = \frac{1}{\sqrt{\left( 1 - \left( \Omega / \omega_n \right)^2 \right)^2 + \left( 2\xi \left( \Omega / \omega_n \right) \right)^2}}}$$



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#### **Dynamic Amplification Factor**

Substitution of C and D, in  $\tan \varphi$  expression gives

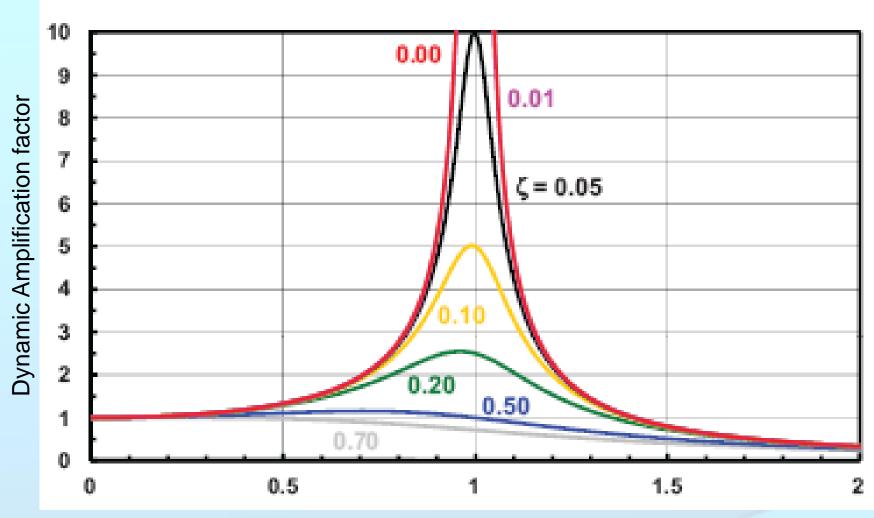
$$\tan \varphi = \frac{D}{C} = \frac{2\xi \omega_n \Omega}{\left(\omega_n^2 - \Omega^2\right)} = \frac{2\xi \left(\Omega / \omega_n\right)}{1 - \left(\Omega / \omega_n\right)^2}$$

Defining the ratio  $r = \Omega/\omega_n$ , the two expressions simplify to

$$DAF = \frac{u_{max}}{u_{st}} = \frac{1}{\sqrt{\left(1 - r^2\right)^2 + \left(2\xi r\right)^2}}$$
$$\tan \varphi = \frac{2\xi r}{1 - r^2}$$







Frequency ratio  $\Omega/\omega_n$ 



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180 0.00 0.01 0.20 0.50  $\zeta = 0.05$ 0.70 Phase angle 90 0 0.5 1.5 0  $\mathbf{2}$ 1

Frequency ratio  $\Omega/\omega_n$ 



Ex. 1. An undamped oscillator is driven by an harmonic loading. If the static displacement is  $u_{st}$ = 0.05m, determine the displacement response amplitude for the following frequency ratios: r= 0.2, 0.9, 1.1, 1.8 & 3.0.





Ex. 2 An undamped system consisting of a 10 kg mass and a spring of stiffness k = 4 kN/m is acted upon by a harmonic force of magnitude  $P_0=0.5$ kN. The displacement amplitude of the steady-state response was observed to be 11 cm. Determine the frequency of the excitation force.





Ex. 3. An undamped system having a mass of 50 kg is excited by a harmonic force with magnitude  $P_0=100$  N and an operating frequency of 10 Hz. The displacement amplitude of the steady-state response was observed to be 3.2 mm. Determine the spring constant *k* of the system.





Ex. 4. An undamped system having a mass of 10 kg and a spring of constant of k=8 N/mm is excited by a harmonic force with magnitude  $F_0=200$  N and an operating frequency of 35 rad/sec. If the initial displacement is 21 mm and the initial velocity is 175mm/sec, determine the total displacement, velocity and acceleration of the mass at (a) t=2 sec, (b) t=4 sec and (c) t=6 sec.

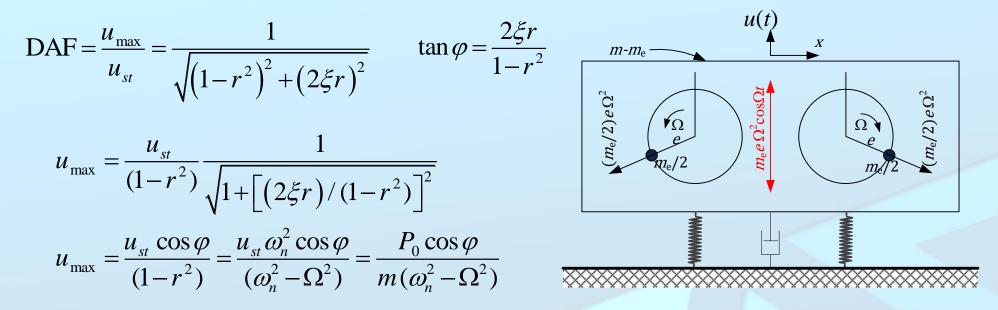




Ex. 5. A portable eccentric mass shaker is sometimes used to evaluate the *in situ* dynamic properties of a structure, using two different frequencies and measuring the displacement amplitudes as well as the phase angles. Such a test was carried out on a single story building and the following responses were recorded:



(1) at  $\Omega_1$ =18.30 rad/s,  $P_{o1}$ =837 kN,  $u_{max1}$ = 1.39mm &  $\varphi_1$ =8°; (2) at  $\Omega_2$ =60.99 rad/s,  $P_{o2}$ = 9300 kN,  $u_{max2}$ = 3.32mm &  $\varphi_2$ =174.29°. Compute the natural frequency  $\omega_n$  & the damping ratio  $\xi$  for the structure



Ex.6. An undamped spring-mass system having a mass of 4.5 kg and a spring of constant of k=3.5 N/mm is excited by a harmonic force with magnitude  $F_0=100$  N and an operating frequency of 18 rad/sec. If the initial displacement is 15 mm and the initial velocity is 150 mm/sec, determine



(a) The frequency ratio

(b) The amplitude o the forced response

(c) The displacement of the mass at t=2 sec

Ex.7. A Structure having a mass of 100 kg and a translational stiffness of 40000 N/m is excited by a harmonic force with magnitude  $F_0$ =500 N and an operating frequency of 2.5 Hz. The damping ratio for the structure is 0.10. For the steady-state vibration determine (a) The amplitude of the steady-state displacement (b) Its phase with respect to the exciting force, and (c) The maximum velocity of the response