

Exercise 8: LaPlace Transform

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Laplace Transform

The Laplace transform of a continuous-time signal $x(t)$ is defined as

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

where s , the independent variable of the transform, is a complex variable.

where $s = \sigma + j\omega$, the independent variable of the transform.

σ : damping factor, ω : frequency variable.

Unilateral (or one-sided): $X(s) = \int_{0^-}^{\infty} x(t) e^{-st} dt;$

Bilateral (or two sided): $X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt;$

Characteristics of the Region of Convergence

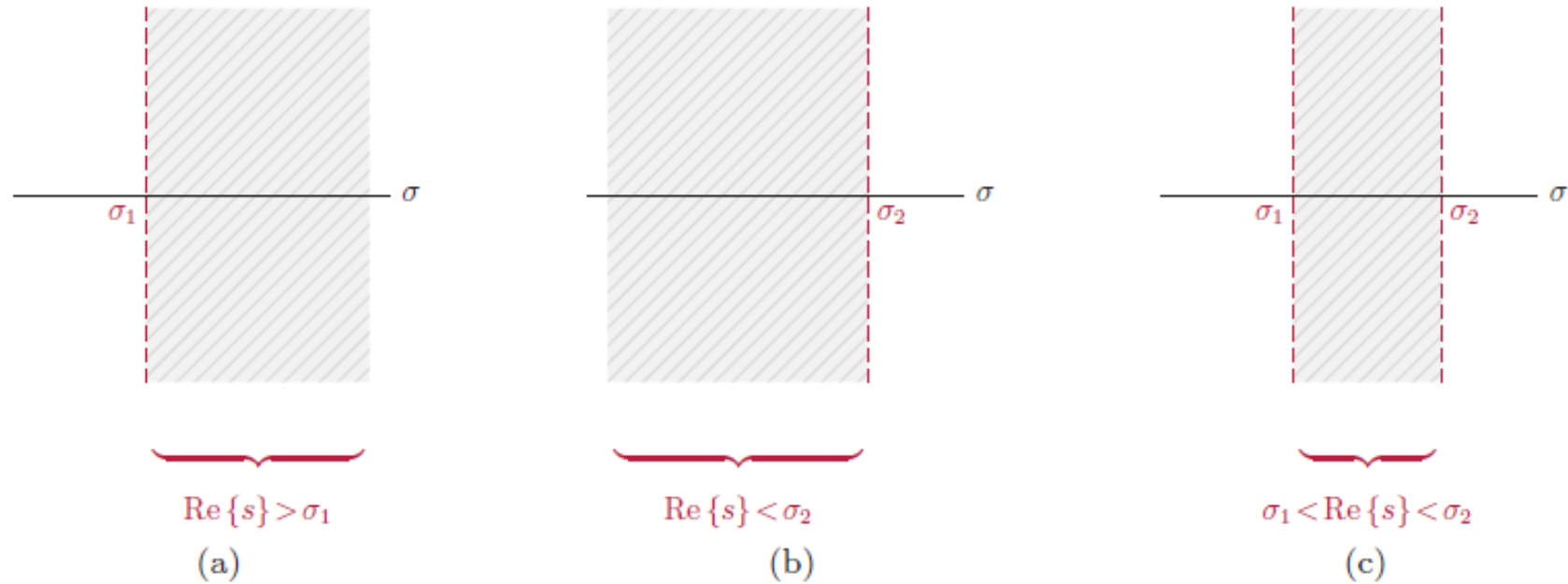


Figure 7.19 – Shape of the region of convergence.

causal signal

anticausal signal

noncausal signal

1. Using the Laplace transform definition determine the transform of each signal listed below. For each transform construct a pole-zero diagram and specify the ROC.

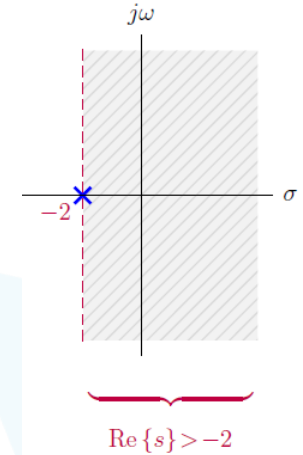
a. $x(t) = e^{-2t}u(t)$

b. $x(t) = e^{-2t}u(t-1)$

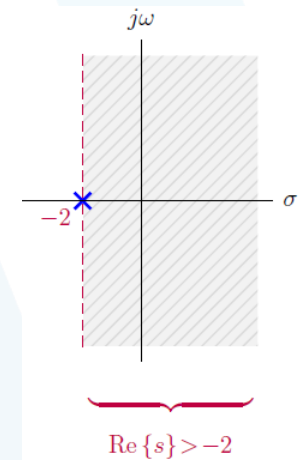
c. $x(t) = e^{2t}u(-t)$

e. $x(t) = \begin{cases} 1, & 0 < t < 1 \\ -1, & t > 1 \\ 0, & t < 0 \end{cases}$

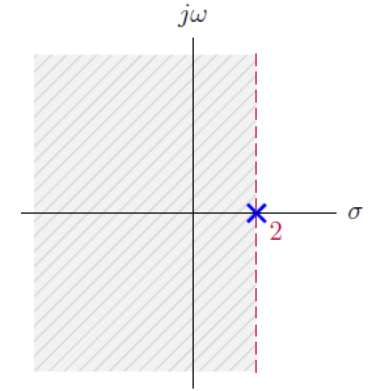
$$a. X(s) = \int_{-\infty}^{\infty} e^{-2t} u(t) e^{-st} dt = \int_0^{\infty} e^{-2t} e^{-st} dt = \frac{e^{-(s+2)t}}{-(s+2)} \Big|_0^{\infty} = \frac{1}{s+2}$$



$$b. X(s) = \int_{-\infty}^{\infty} e^{-2t} u(t-1) e^{-st} dt = \int_1^{\infty} e^{-2t} e^{-st} dt = \frac{e^{-(s+2)t}}{-(s+2)} \Big|_1^{\infty} = \frac{e^{-2} e^{-s}}{s+2}$$

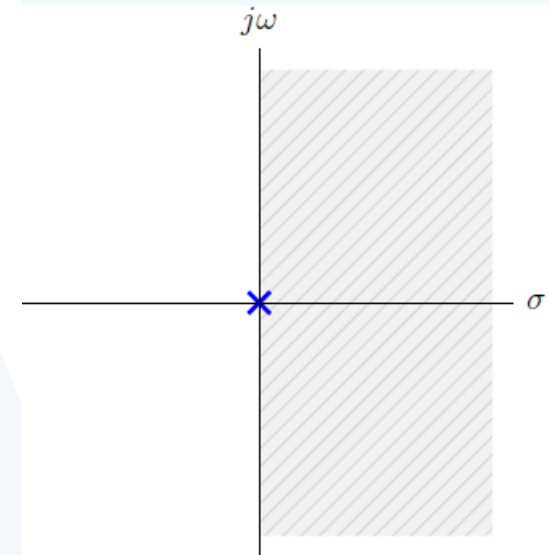


$$c. X(s) = \int_{-\infty}^{\infty} e^{2t} u(-t) e^{-st} dt = \int_{-\infty}^0 e^{2t} e^{-st} dt = \left. \frac{e^{(2-s)t}}{(2-s)} \right|_{-\infty}^0 = \frac{1}{2-s}$$



$\text{Re}\{s\} < 2$

$$e. X(s) = \int_0^1 (1) e^{-st} dt + \int_1^{\infty} (-1) e^{-st} dt = \left. \frac{e^{-st}}{-s} \right|_0^1 + \left. \frac{e^{-st}}{s} \right|_1^{\infty} = \frac{1}{s} [1 - 2e^{-s}]$$



$\text{Re}\{s\} < 0$

$\text{Re}\{s\} > 0$

2. Construct a pole-zero diagram and specify the ROC for each of the transforms given below. Also, determine the Fourier transform $X(\omega)$ if it exists.

a. $X(s) = \frac{s - 2}{s^2 + 3s + 2}$, $x(t)$ is causal

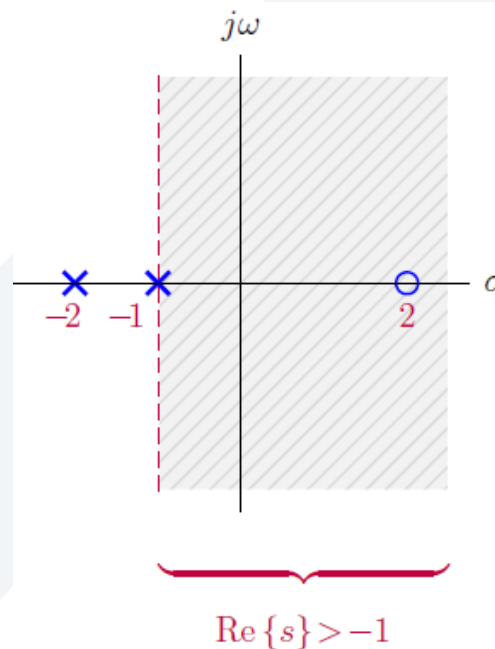
b. $X(s) = \frac{s}{s^2 - 1}$, $x(t)$ is causal

c. $X(s) = \frac{s + 1}{s^2 - 4s + 3}$, $x(t)$ is anti-causal

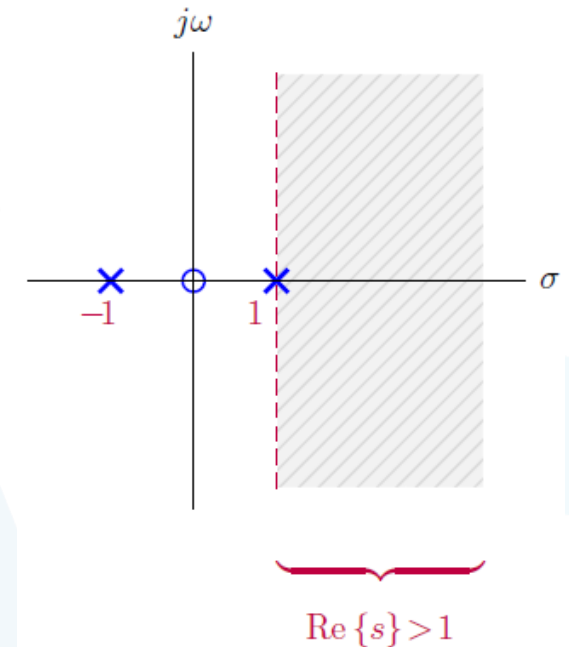
d. $X(s) = \frac{s^2 - s}{s^2 - s - 6}$, $x(t)$ is anti-causal

a. The transform has a zero at $s = 2$ and poles at $s = -1, -2$. Since $x(t)$ is causal, the ROC is $\text{Re}\{s\} > -1$. The Fourier transform $X(\omega)$ is

$$X(\omega) = X(s)|_{s=j\omega} = \frac{j\omega - 2}{(j\omega)^2 + j3\omega + 2} = \frac{j\omega - 2}{(2 - \omega^2) + j3\omega}$$



b. The transform has a zero at $s = 0$ and poles at $s = \pm 1, -2$. Since $x(t)$ is causal, the ROC is $\text{Re}\{s\} > 1$. The ROC does not include the $j\omega$ -axis of the s -plane. Therefore the Fourier transform does not exist.

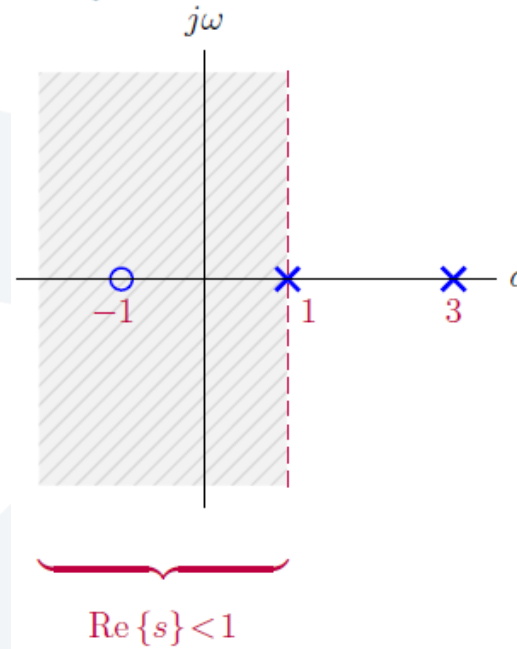
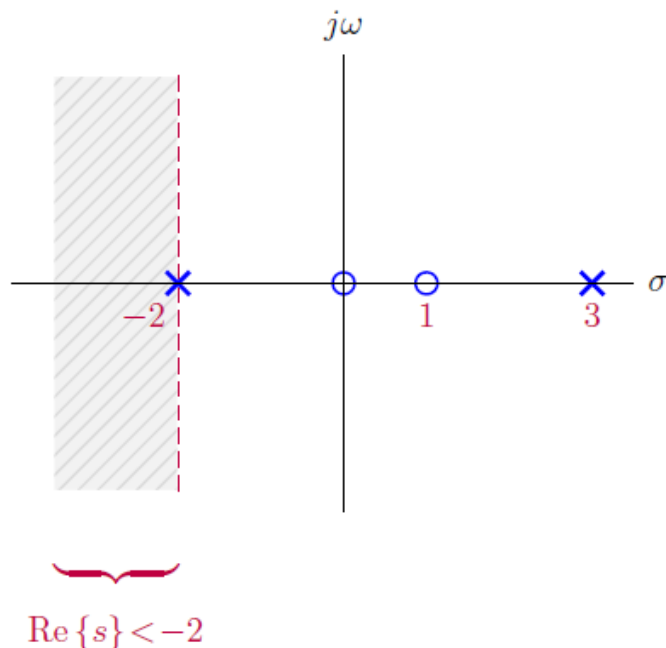


c. The transform has a zero at $s = -1$ and poles at $s = 1, 3$. Since $x(t)$ is anti-causal, the ROC is $\text{Re}\{s\} < 1$. The Fourier transform $X(\omega)$ is

$$X(\omega) = X(s)|_{s=j\omega} = \frac{j\omega + 1}{(j\omega)^2 - j4\omega + 3} = \frac{j\omega + 1}{(3 - \omega^2) - j4\omega}$$



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- d. The transform has a zero at $s = 0, 1$ and poles at $s = -2, 3$. Since $x(t)$ is anti-causal, the ROC is $\text{Re}\{s\} < -2$. The ROC does not include the $j\omega$ -axis of the s -plane. Therefore the Fourier transform does not exist.

Properties of Laplace Transform

Property	$x(t)$	$X(s)$	ROC
Linearity	$ax_1(t) + bx_2(t)$	$aX_1(s) + bX_2(s)$	$\supset (R_1 \cap R_2)$
Delay by T	$x(t - T)$	$X(s)e^{-sT}$	R
Multiply by t	$tx(t)$	$-dX(s)/ds$	R
Multiply by $e^{-\alpha t}$	$x(t)e^{-\alpha t}$	$X(s + \alpha)$	Shift R by $-\alpha$
Scaling in t	$x(at)$	$\frac{1}{ a } X\left(\frac{s}{a}\right)$	aR
Differentiate in t	$dx(t)/dt$	$sX(s)$	$\supset R$
Integrate in t	$\int_{-\infty}^t x(\tau) d\tau$	$\frac{X(s)}{s}$	$\supset (R \cap (\text{Re}(s) > 0))$
Convolve in t	$x_1 * x_2(t)$	$X_1(s) X_2(s)$	$\supset (R_1 \cap R_2)$

3. Using the property of the Laplace transform, determine $X(s)$ for each of the signals listed below. Also indicate the ROC in each case.

a. $x(t) = \delta(t) + 2e^{-t} u(t)$

b. $x(t) = (1 - e^{-t}) u(t)$

c. $x(t) = e^{-2t} \cos(3t) u(t)$

d. $x(t) = e^{-2(t-1)} u(t-1)$

e. $x(t) = e^{-2t} u(t-1)$

a. $x(t) = \delta(t) + 2e^{-t} u(t)$

a. $L\{\delta(t)\} = 1, \quad \text{all } s$ $L\{e^{-t}u(t)\} = \frac{1}{s+1}, \quad \text{Re}\{s\} > -1$

$$L\{u(t)\} = \frac{1}{s}$$

Using linearity $X(s) = 1 + \frac{2}{s+1} = \frac{s+3}{s+1}, \quad \text{Re}\{s\} > -1$

b. $x(t) = (1 - e^{-t}) u(t)$

b. $L\{u(t)\} = \frac{1}{s}, \quad \text{Re}\{s\} > 0$ $L\{e^{-t}u(t)\} = \frac{1}{s+1}, \quad \text{Re}\{s\} > -1$

Using linearity $X(s) = \frac{1}{s} - \frac{1}{s+1} = \frac{1}{s(s+1)}, \quad \text{Re}\{s\} > 0$

c. $x(t) = e^{-2t} \cos(3t) u(t)$

c. $x(t) = \frac{1}{2} e^{t(-2+j3)} u(t) + \frac{1}{2} e^{t(-2-j3)} u(t)$

$L\{e^{-t(2-j3)} u(t)\} = \frac{1}{s+2-j3}, \quad \text{Re}\{s\} > -2$

$$L\{e^{-t(2+j3)}u(t)\} = \frac{1}{s+2+j3}, \quad \text{Re}\{s\} > -2$$

Using linearity

$$X(s) = \frac{\frac{1}{2}}{s+2-j3} + \frac{1/2}{s+2+j3} = \frac{s+2}{s^2+4s+13}, \quad \text{Re}\{s\} > -2$$

d. $x(t) = e^{-2(t-1)}u(t-1)$

d. $L\{e^{-2t}u(t)\} = \frac{1}{s+2}, \quad \text{Re}\{s\} > -2$

Using time shifting property

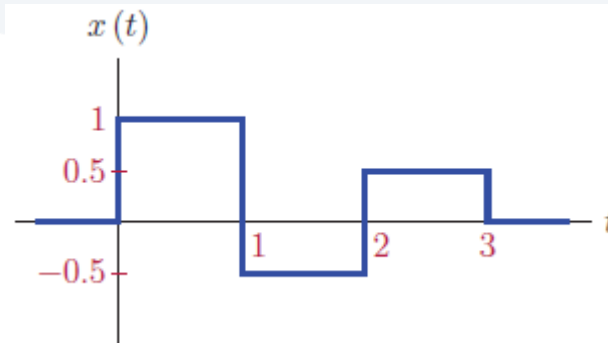
$$X(s) = L\{e^{-2(t-1)}u(t-1)\} = \frac{e^{-s}}{s+2}, \quad \text{Re}\{s\} > -2$$

e. $x(t) = e^{-2t}u(t-1)$

e. $L\{e^{-2t}u(t-1)\} = e^{-2}L\{e^{-2(t-1)}u(t-1)\} = \frac{e^{-s-2}}{s+2}, \quad \text{Re}\{s\} > -2$

Using scaling property

4. Using the linearity and time shifting properties, determine the Laplace transform of the signal shown. Specify the ROC in each case.



$$x(t) = u(t) - 1.5u(t - 1) + u(t - 2) - 0.5u(t - 3)$$

$$X(s) = \frac{1}{s} (1 - 1.5e^{-s} + e^{-2s} - 0.5e^{-3s}), \quad \text{Re}\{s\} > -\infty$$

5. Find a transfer function for each CTLTI system described below by means of a differential equation.

$$a. \frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} - x(t)$$

$$b. \frac{d^2 y(t)}{dt^2} + 4y(t) = \frac{d^2 x(t)}{dt^2} + \frac{dx(t)}{dt} + 3x(t)$$

$$a. H(s) = \frac{Y(s)}{X(s)} = \frac{s - 1}{s^2 + 4s + 3}$$

$$b. H(s) = \frac{Y(s)}{X(s)} = \frac{s^2 + s + 3}{s^2 + 4}$$

6. Find a differential equation for each CTLTI system described below by means of a transfer function.

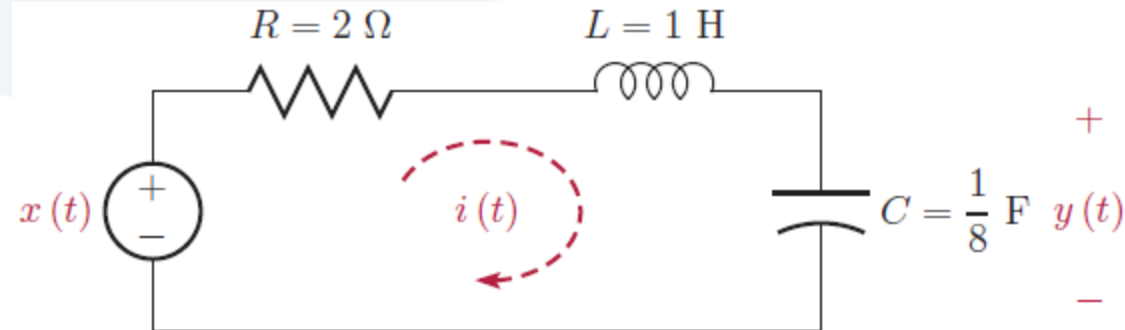
a. $H(s) = \frac{s}{s+4}$

a. $\frac{dy(t)}{dt} + 4y(t) = \frac{dx(t)}{dt}$

b. $H(s) = \frac{s+1}{s^2+5s+6}$

b. $\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = \frac{dx(t)}{dt} + x(t)$

7. For the RLC circuit shown,



- Find a differential equation between the input $x(t)$ and the output $y(t)$.
- Obtain the transfer function $H(s)$ from the DE found in part (a).

a. $x(t) = y(t) + L \frac{di(t)}{dt} + Ri(t)$

$$i(t) = C \frac{dy(t)}{dt} \Rightarrow \frac{di(t)}{dt} = C \frac{d^2y(t)}{dt^2} \quad \Rightarrow \quad LC \frac{d^2y(t)}{dt^2} + RC \frac{dy(t)}{dt} + y(t) = x(t)$$

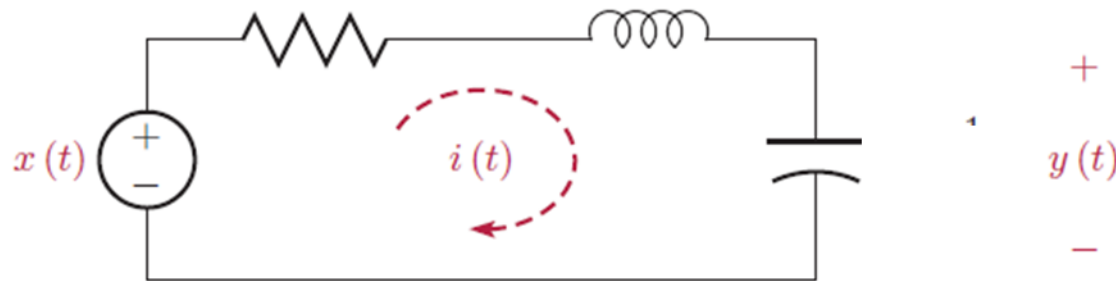
$$\frac{d^2y(t)}{dt^2} + \frac{R}{L} \frac{dy(t)}{dt} + \frac{1}{LC} y(t) = \frac{1}{LC} x(t)$$

$$\frac{d^2y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 8y(t) = 8x(t)$$

b. $(s^2 + 2s + 8)Y(s) = 8X(s) \Rightarrow H(s) = \frac{Y(s)}{X(s)} = \frac{8}{s^2 + 2s + 8}$

8. For the RLC circuit shown, the initial values are *relaxed*

$$R = 5 \, \Omega, L = 1 \, \text{H} \text{ and } C = 1/6 \, \text{F}.$$



- Find a differential equation between the input $x(t)$ and the output $y(t)$.
- Obtain the transfer function $H(s)$ from the DE found in part (a).
- Obtain the impulse response $h(t)$ by using Inverse Laplace Transform

a. $x(t) = y(t) + L \frac{di(t)}{dt} + Ri(t)$

$$i(t) = C \frac{dy(t)}{dt} \Rightarrow \frac{di(t)}{dt} = C \frac{d^2y(t)}{dt^2} \quad \Rightarrow \quad LC \frac{d^2y(t)}{dt^2} + RC \frac{dy(t)}{dt} + y(t) = x(t)$$

$$\frac{d^2y(t)}{dt^2} + \frac{R}{L} \frac{dy(t)}{dt} + \frac{1}{LC} y(t) = \frac{1}{LC} x(t)$$

$$\frac{d^2y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 6y(t) = 6x(t)$$

b. $(s^2 + 5s + 6)Y(s) = 6X(s) \Rightarrow H(s) = \frac{Y(s)}{X(s)} = \frac{6}{s^2 + 5s + 6}$

c.

$$H(s) = \frac{Y(s)}{X(s)} = \frac{6}{s^2 + 5s + 6} = \frac{6}{(s + 2)(s + 3)}$$

The poles are : $s = -3$; $s = -2$; : $ROC : RE\{s\} > -2$

The Poles Are Real and Distinct

$$H(s) = \frac{A}{s + 2} + \frac{B}{s + 3}$$

$$A = (s + 2)H(s)|_{s=-2} \gg A = \frac{6}{s + 3}|_{s=-2} = 6$$

$$B = (s + 3)H(s)|_{s=-3} \gg B = \frac{6}{s + 2}|_{s=-3} = -6$$

The transfer function

$$\Rightarrow H(s) = \frac{6}{s + 2} - \frac{6}{s + 3}$$

The impulse response

$$\Rightarrow h(t) = 6e^{-2t}u(t) - 6e^{-3t}u(t)$$

d. Find the output if the input is $x(t) = u(t)$

$$x(t) = u(t)$$

$$X(s) = \frac{1}{s}$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{6}{s^2 + 5s + 6}$$

$$Y(s) = H(s).X(s) = \frac{6}{s^2 + 5s + 6} \cdot \frac{1}{s}$$

The Poles Are Real and Distinct

The poles are : $s = -3$; $s = -2$; $s = 0$;

$ROC : RE\{s\} > 0$

$$Y(s) = \frac{6}{s^2 + 5s + 6} \cdot \frac{1}{s} = \frac{A}{s+2} + \frac{B}{s+3} + \frac{C}{s}$$

$$A = (s+2)Y(s)|_{s=-2} \gg A = \frac{6}{s(s+3)}|_{s=-2} = -3$$

$$B = (s+3)Y(s)|_{s=-3} \gg B = \frac{6}{s(s+2)}|_{s=-3} = 2$$

$$C = sY(s)|_{s=0} \gg C = \frac{6}{(s+3)(s+2)}|_{s=0} = \frac{6}{5}$$

$$Y(s) = \frac{-3}{s+2} + \frac{2}{s+3} + \frac{6/5}{s}$$

$$y(t) = -3e^{-2t}u(t) + 2e^{-3t}u(t) + \frac{6}{5}u(t)$$

e. Find the impulse response

$$x(t) = \delta(t)$$

$$y(t) = \text{Trans} (u(t)) \rightarrow \frac{dy(t)}{dt} = \text{Trans} \left(\frac{du(t)}{dt} \right) = \text{Trans}(\delta(t)) = h(t)$$

$$h(t) = \frac{dy(t)}{dt} = \frac{d \left(-3e^{-2t}u(t) + 2e^{-3t}u(t) + \frac{6}{5}u(t) \right)}{dt}$$

$$h(t) = \left(\frac{3}{2}e^{-2t} - \frac{2}{3}e^{-3t} \right) u(t)$$

Extra examples

Inverse Laplace transform

9. For a causal signal $x(t)$ the Laplace transform is : $X(s) = \frac{1}{s^2 + 3s + 2}$
Find the inverse Laplace transform

The poles are : $s = -1$; $s = -2$; : $ROC : RE\{s\} > -1$

The Poles Are
Real and Distinct

$$X(s) = \frac{A}{s+2} + \frac{B}{s+1}$$

$$A = (s+2)X(s)|_{s=-2} \gg A = \frac{1}{s+1}|_{s=-2} = -1$$

$$B = (s+1)X(s)|_{s=-1} \gg B = \frac{1}{s+2}|_{s=-1} = 1$$

$$\Rightarrow X(s) = -\frac{1}{s+2} + \frac{1}{s+1} \Rightarrow x(t) = -e^{-2t}u(t) + e^{-t}u(t)$$

Inverse Laplace transform

10. For a causal signal $x(t)$ the Laplace transform is : $X(s) = \frac{s+1}{s(s+2)}$

Find the inverse Laplace transform

The poles are : $s = -2$; $s = 0$; : $ROC : RE\{s\} > 0$

$$X(s) = \frac{k_1}{s} + \frac{k_2}{s+2}$$

$$k_1 = s X(s) \Big|_{s=0} = \frac{s+1}{s+2} \Big|_{s=0} = \frac{1}{2}$$

$$k_2 = (s+2) X(s) \Big|_{s=-2} = \frac{s+1}{s} \Big|_{s=-2} = \frac{1}{2}$$

THE POLES ARE
REAL AND
DISTINCT

$$\Rightarrow X(s) = \frac{1/2}{s} + \frac{1/2}{s+2} \Rightarrow x(t) = \frac{1}{2} u(t) + \frac{1}{2} e^{-2t} u(t)$$

Inverse Laplace transform

The Laplace transform of a signal $x(t)$ is

$$X(s) = \frac{s+1}{s(s^2+9)}$$

with the ROC specified as

$$\text{Re}\{s\} > 0$$

Determine $x(t)$.

Please note :
The poles are complex

$$X(s) = \frac{s+1}{s(s+j3)(s-j3)}$$

$$X(s) = \frac{k_1}{s} + \frac{k_2}{s+j3} + \frac{k_3}{s-j3}$$

$$k_1 = sX(s)\Big|_{s=0} = \frac{s+1}{(s+j3)(s-j3)}\Big|_{s=0} = \frac{1}{9}$$

$$k_2 = (s+j3)X(s)\Big|_{s=-j3} = \frac{s+1}{s(s-j3)}\Big|_{s=-j3} = -\frac{1}{18} + j\frac{1}{6}$$

$$k_3 = k_2^* = -\frac{1}{18} - j\frac{1}{6}$$

$$\begin{aligned} x(t) &= k_1 u(t) + k_2 e^{-j3t} u(t) + k_3 e^{j3t} u(t) \\ &= \frac{1}{9} u(t) + \left(-\frac{1}{18} + j\frac{1}{6}\right) e^{-j3t} u(t) + \left(-\frac{1}{18} - j\frac{1}{6}\right) e^{j3t} u(t) \end{aligned}$$

Inverse Laplace transform

A causal signal $x(t)$ has the Laplace transform $X(s) = \frac{s(s+1)}{(s+1)^3(s+2)}$

$$X(s) = \frac{s(s+1)}{(s+1)^3(s+2)} = \frac{-3}{s+1} + \frac{3}{(s+1)^2} - \frac{2}{(s+1)^3} + \frac{3}{s+2}$$

■ Multiple-order poles

$$L\{e^{-t}u(t)\} = \frac{1}{s+1}, \quad L\{te^{-t}u(t)\} = -\frac{d}{ds}\left[\frac{1}{s+1}\right] = \frac{1}{(s+1)^2}$$

$$L\{t^2e^{-t}u(t)\} = -\frac{d}{ds}\left[\frac{1}{(s+1)^2}\right] = \frac{2}{(s+1)^3}$$

$$x(t) = -3e^{-t}u(t) + 3te^{-t}u(t) - t^2e^{-3t}u(t) + 3e^{-2t}u(t)$$

