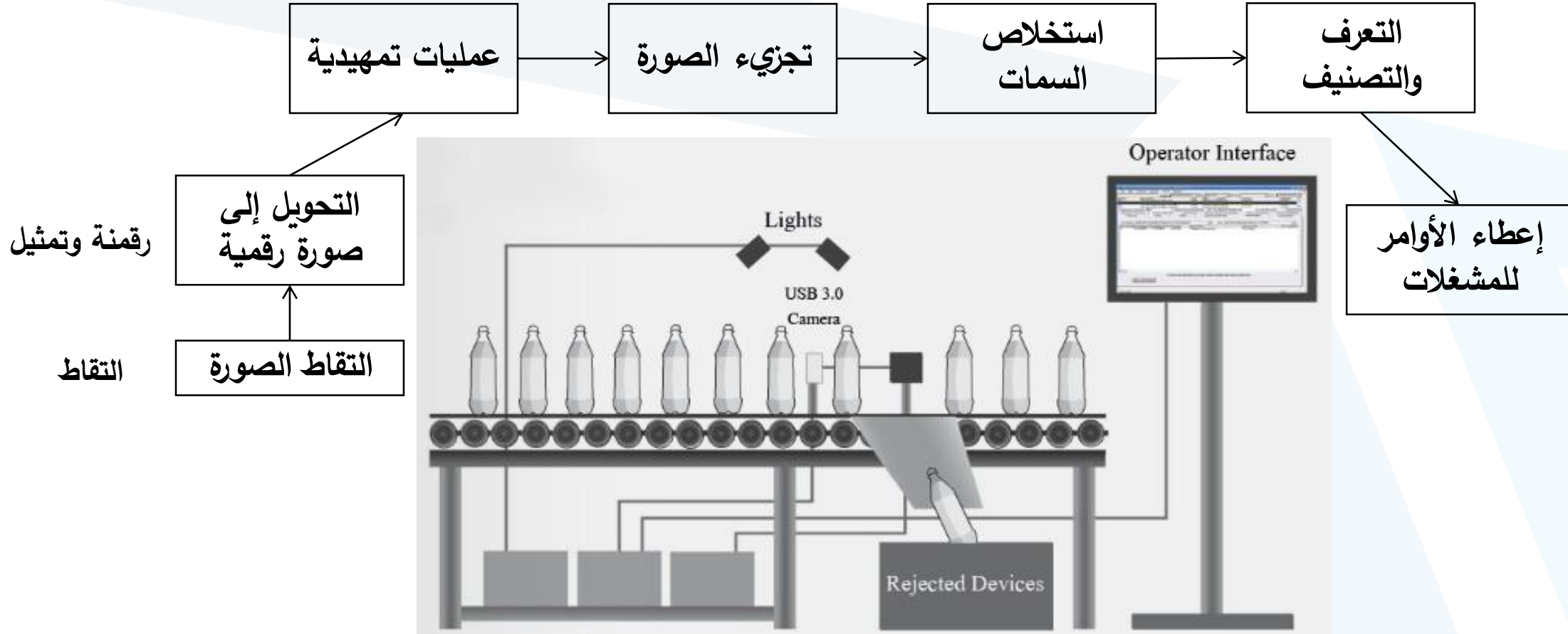


# Digital Image Processing

## المحاضرة الثانية Digital Image Fundamental

د. عيسى الغنام د. إياد حاتم  
2023 الفصل الصيفي

# مثال تطبيقي: مكونات نظام تصنيف ميكانيكي



# التقاط الصور

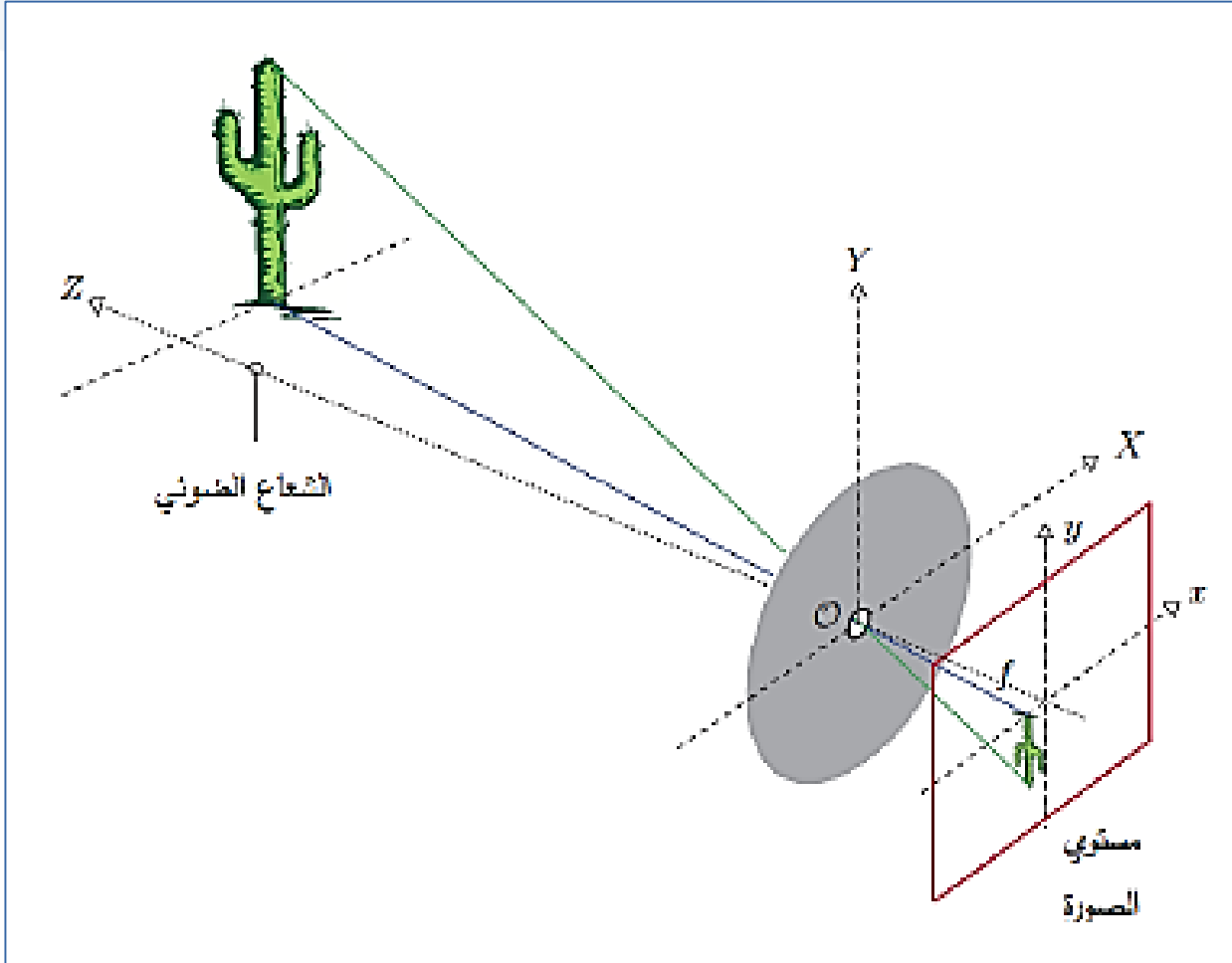
□ يعرف التقاط الصور بأنه عملية الحصول على الصورة  
 من **مصدر ما** بحيث تصبح هذه الصور جاهزة لأي عملية  
 معالجة قادمة

□ أبسط نموذج للحصول على الصور هو الكاميرا ذات الثقب

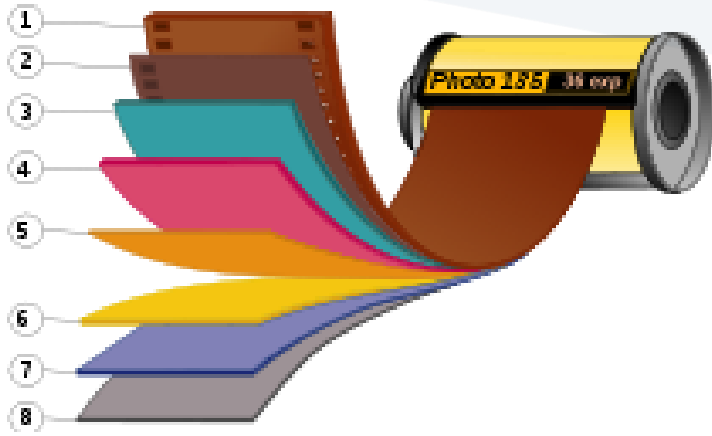
▪ يعكس نموذج هذه الكاميرا العلاقة الرياضية بين  
 إحداثيات نقطة في الفراغ وانعكاس هذه النقطة على  
 مستوي الصورة

$$x = -f X/Z$$

$$y = -f Y/Z$$

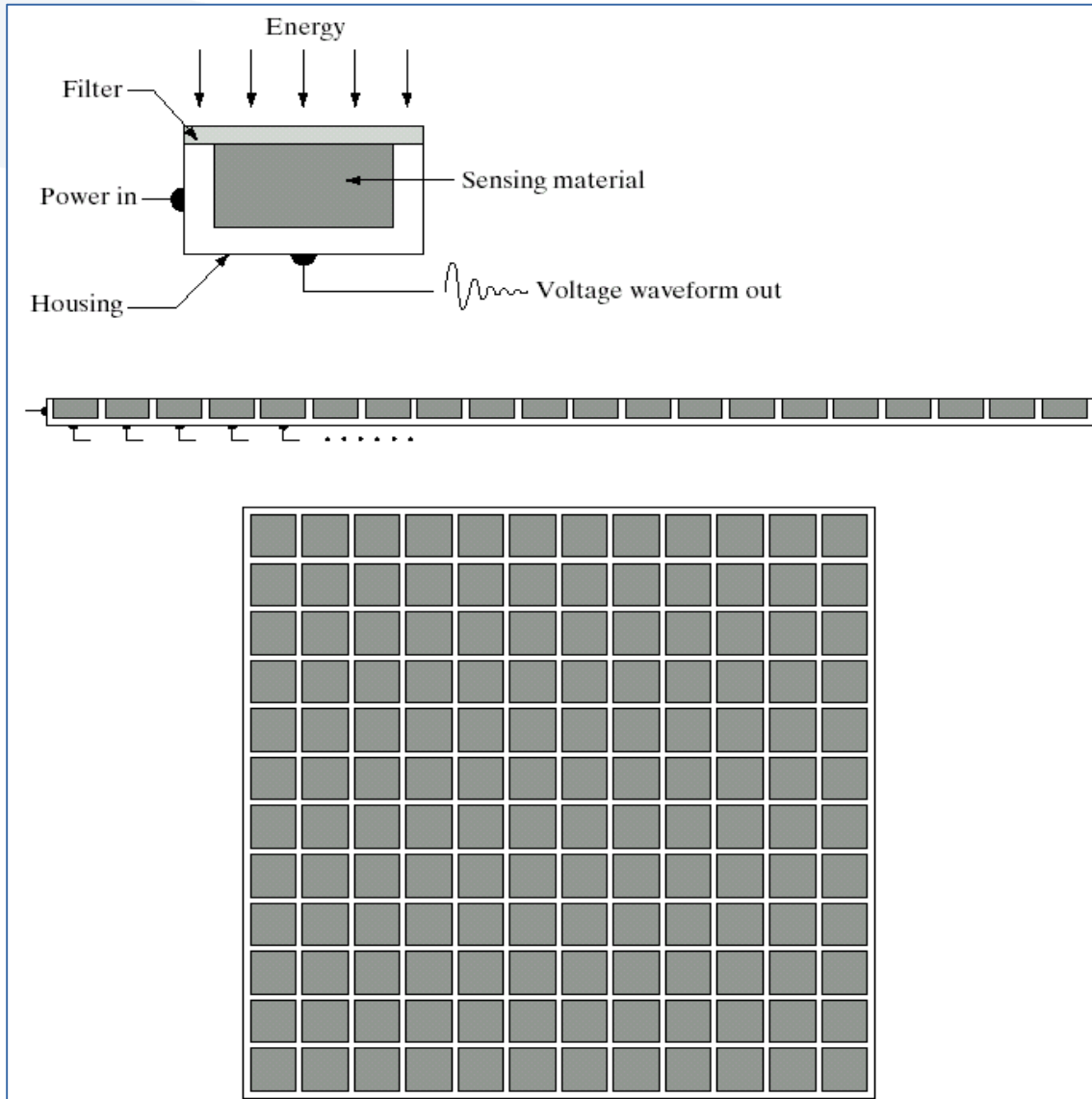


# Image Sensors



تلتقط الصور في المجال المرئي بوساطة الكاميرا العادية  
تسجل الصور على فيلم مؤلف من قطعة بلاستيكية تحمل طبقة رقيقة  
من الجيلاتين الذي يحوي مواد كيميائية حساسة للضوء  
تسجل المعلومات بما يسمى الصورة السلبية التي تعالج للحصول على  
الصورة الأصلية

# Image Sensors

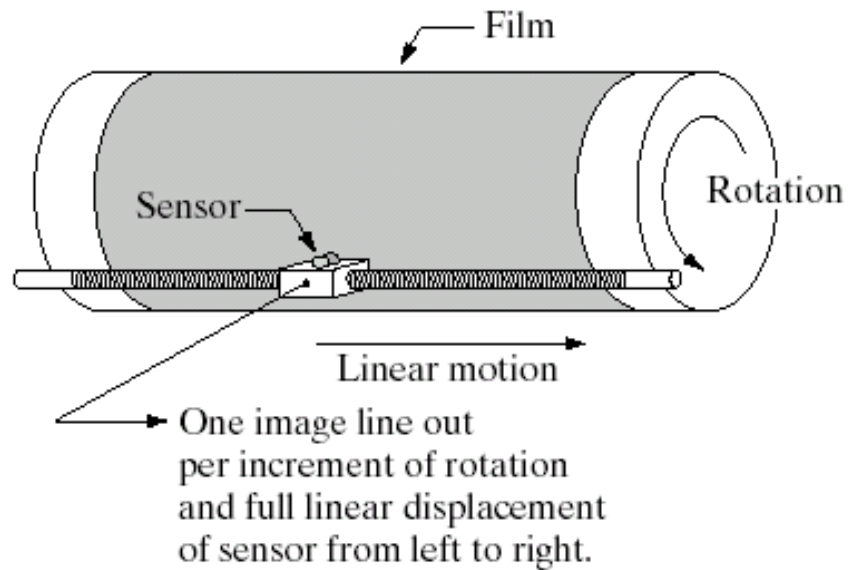
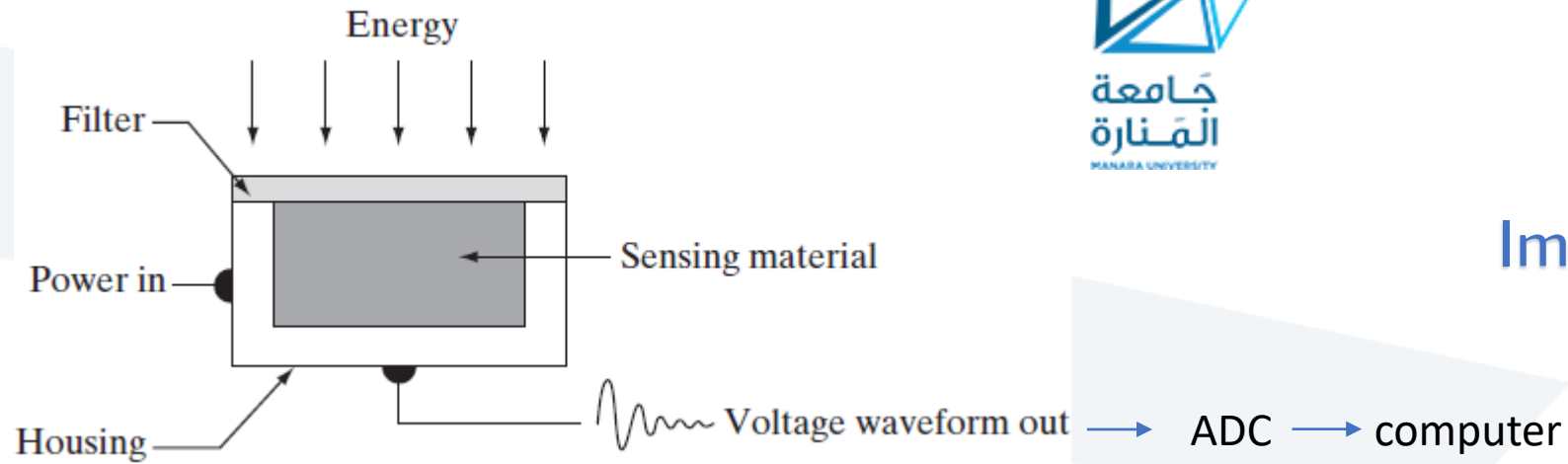


Single sensor

Line sensor

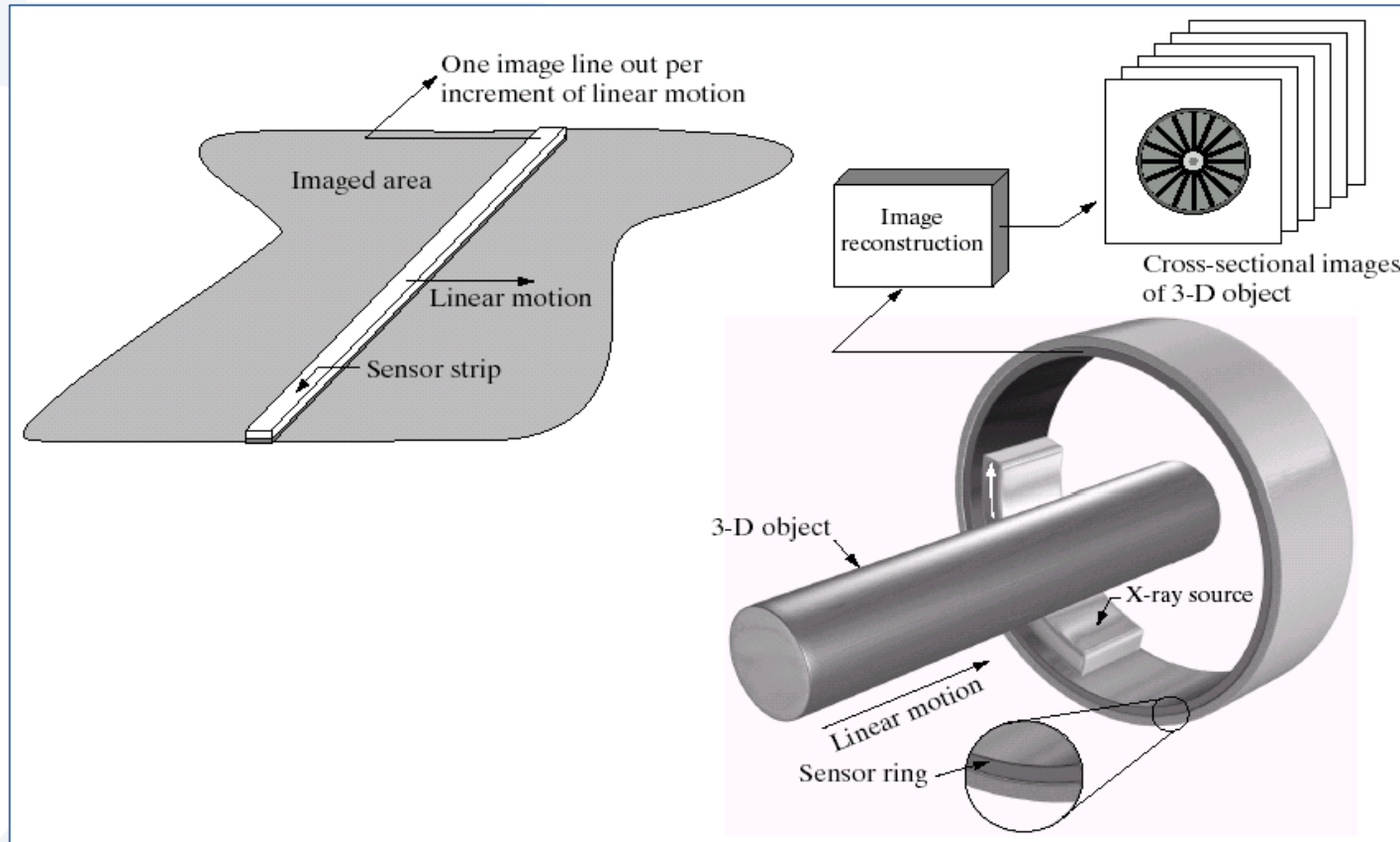
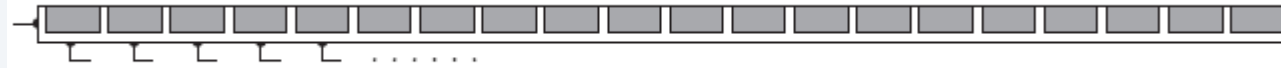
Array sensor

## Image Sensors : Single Sensor



**FIGURE 2.13** Combining a single sensor with motion to generate a 2-D image.

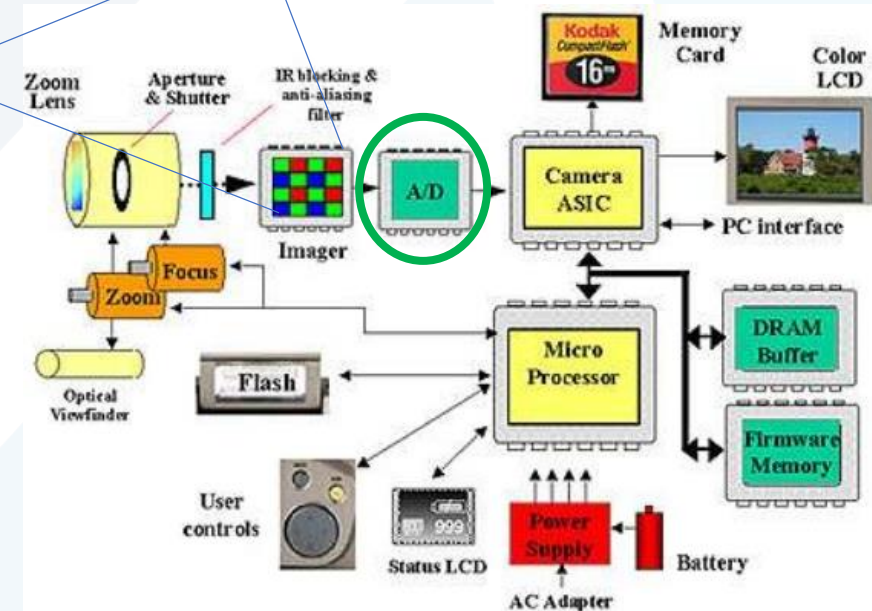
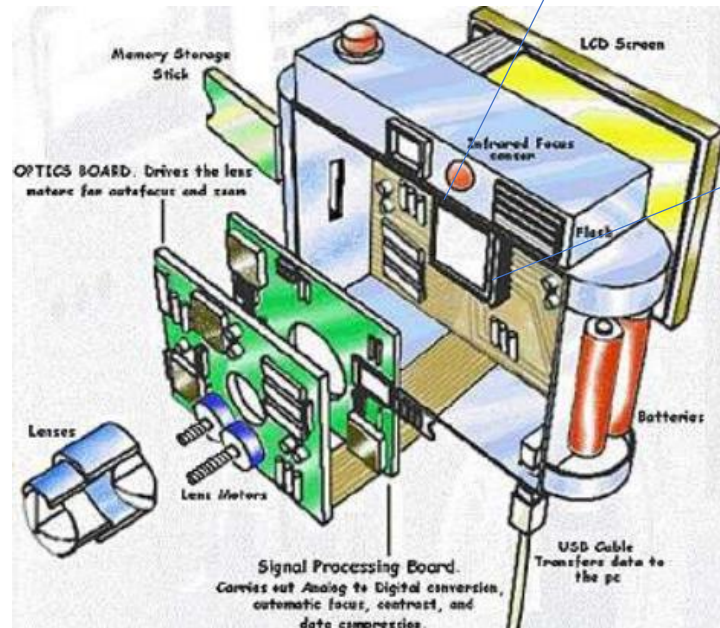
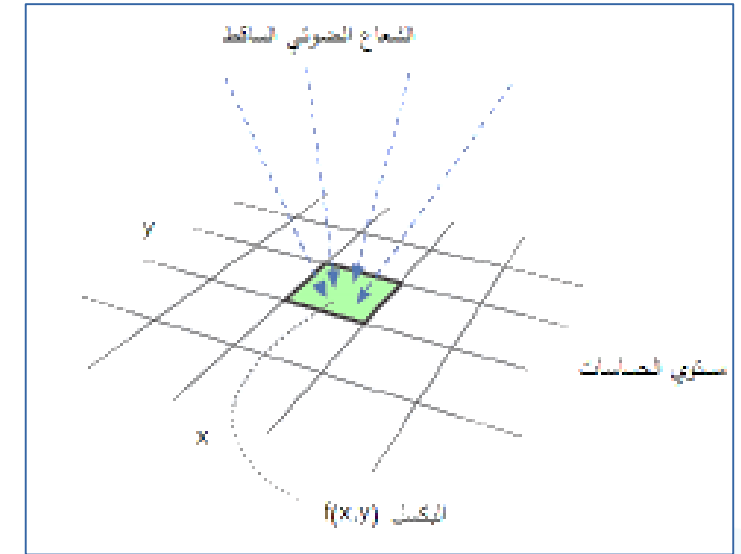
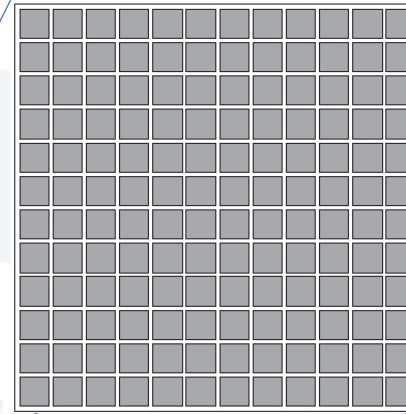
# Image Sensors : Line Sensor



Fingerprint sweep sensor

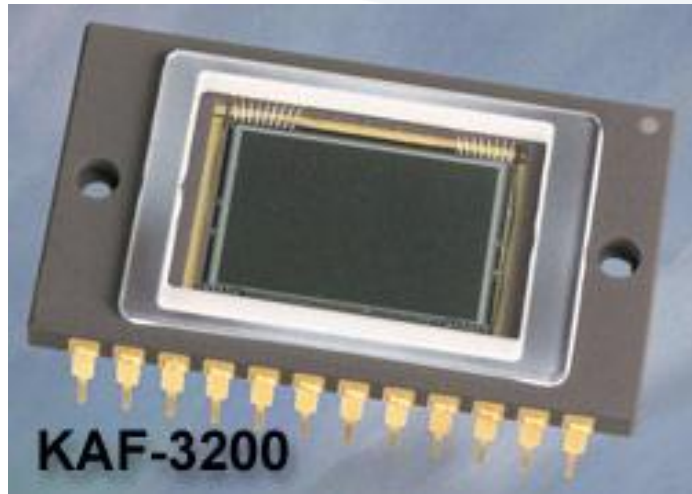
## Computerized Axial Tomography

# Image Sensors : Array Sensor





# Image Sensors : Array Sensor Charge-Coupled Device (CCD)



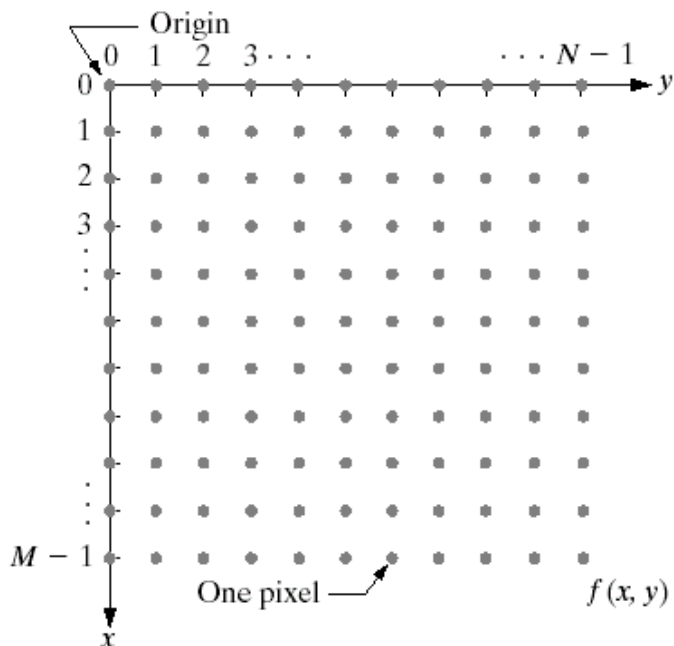
CCD KAF-3200E from Kodak.  
(2184 x 1472 pixels,  
Pixel size 6.8 microns<sup>2</sup>)

- Used for convert a continuous image into a digital image
- Contains an array of light sensors
- Converts photon into electric charges accumulated in each sensor unit

# تمثيل الصورة الرقمية

تمثل الصورة الرقمية بالمصفوفة الآتية

Digital image: an image that has been discretized both in Spatial coordinates and associated value.



$$f(x, y) \cong \begin{bmatrix} f(0,0) & f(0,1) & \dots & f(0,N-1) \\ f(1,0) & f(1,1) & \dots & f(1,N-1) \\ \vdots & \vdots & \ddots & \vdots \\ f(M-1,0) & f(M-1,1) & \dots & f(M-1,N-1) \end{bmatrix}$$



# Digital Image Types : RGB Image

## Digital Colored Image



Each component in the image called pixel associates with the pixel value (a single number in the case of intensity images or a vector in the case of color images).

**Color image or RGB image:**  
each pixel contains a vector representing red, green and blue components.

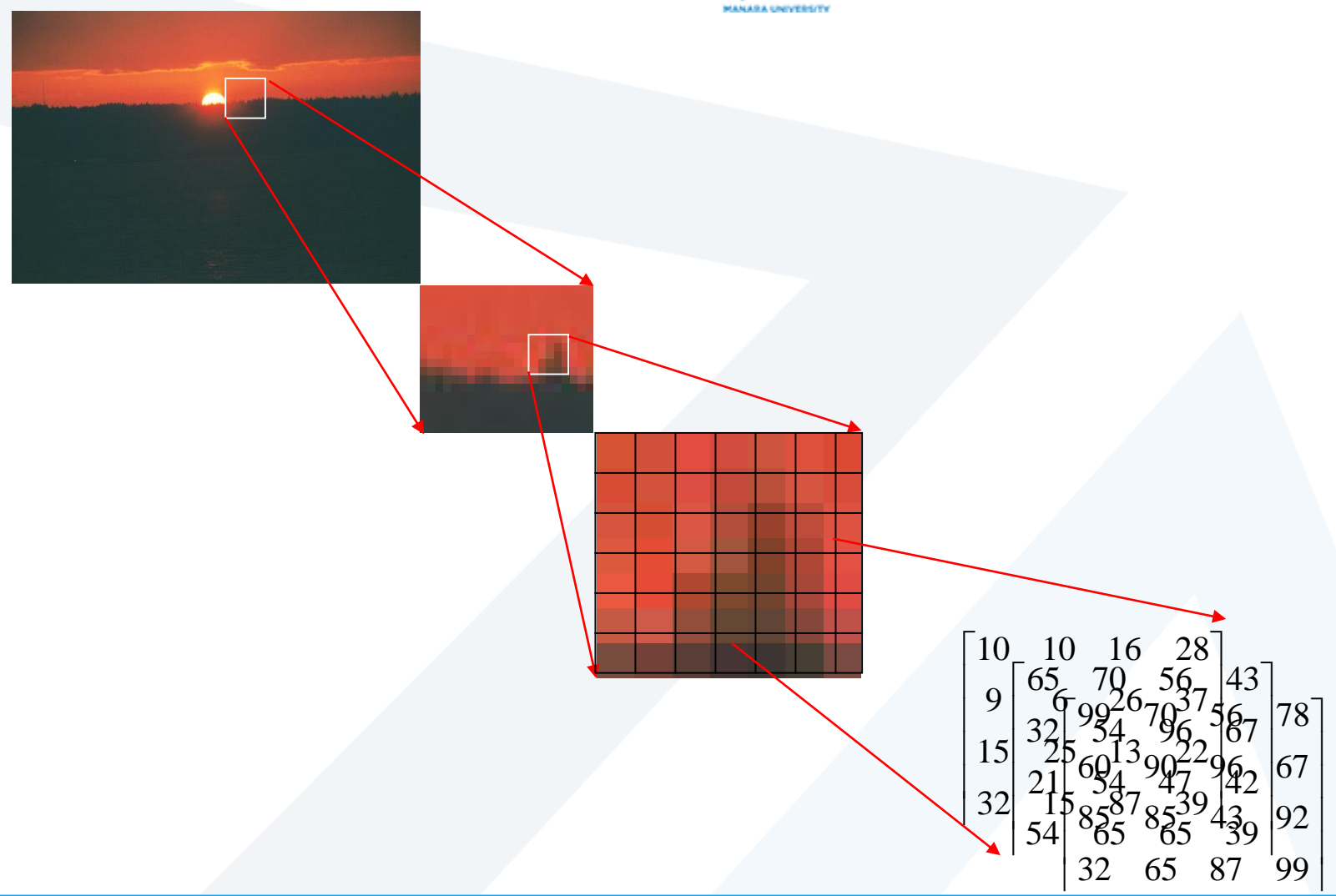
Digital image = a multidimensional array of numbers (such as intensity image) or vectors (such as color image)

RGB components

10	10	16	28
9	65	70	56
32	99	26	70
15	32	54	96
32	25	60	13
21	54	90	22
15	87	47	96
54	85	39	42
32	65	85	39
32	65	87	99

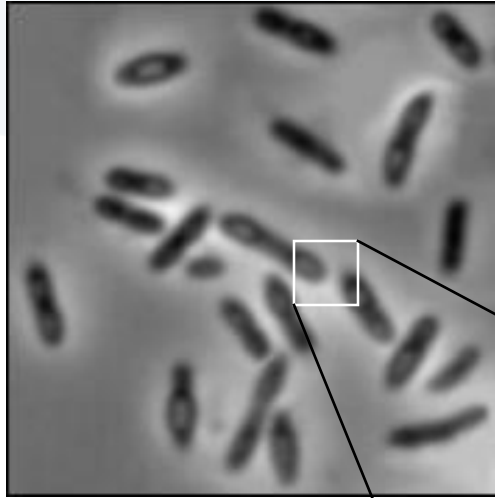
# Digital Image Types : RGB Image

## Digital Colored Image



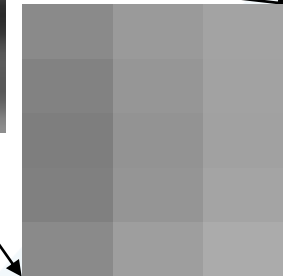
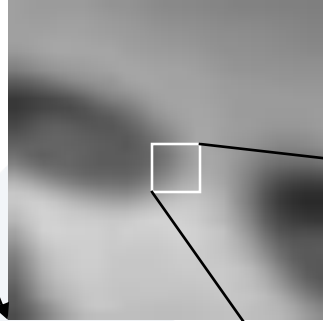
# Digital Image Types :

## Intensity Image or gray image



### Intensity image or monochrome image

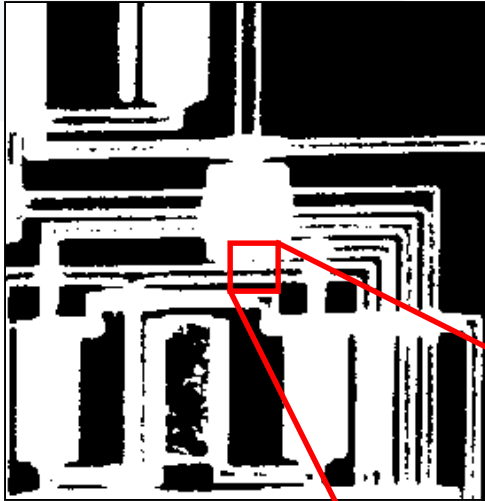
each pixel corresponds to light intensity normally represented in gray scale (gray level).



Gray scale values

10	10	16	28
9	6	26	37
15	25	13	22
32	15	87	39

# Image Types : Binary Image



## Binary image or black and white image

Each pixel contains one bit :

1 represent white

0 represents black



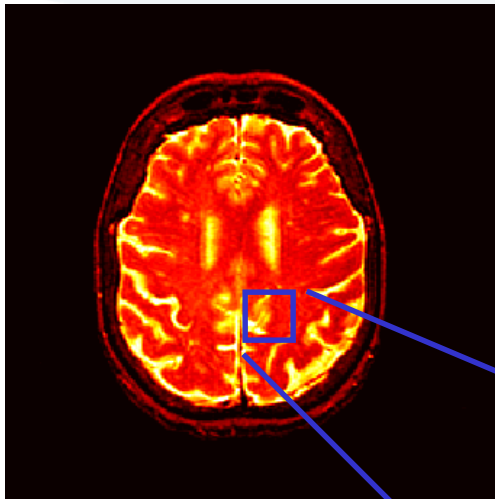
Binary data

0	0	0	0
0	0	0	0
1	1	1	1
1	1	1	1

# Image Types : Index Image

## Index image

Each pixel contains index number pointing to a color in a color table


$$\begin{bmatrix} 1 & 4 & 9 \\ 6 & 4 & 7 \\ 6 & 5 & 2 \end{bmatrix}$$

Index value

Color Table

Index No.	Red component	Green component	Blue component
1	0.1	0.5	0.3
2	1.0	0.0	0.0
3	0.0	1.0	0.0
4	0.5	0.5	0.5
5	0.2	0.8	0.9
...	...	...	...



# أمثلة عن أنواع الصور المختلفة



صورة ثنائية



صورة رمادية



صورة مفهرسة



صورة ملونة



## التحويل بين أنواع الصور في Matlab

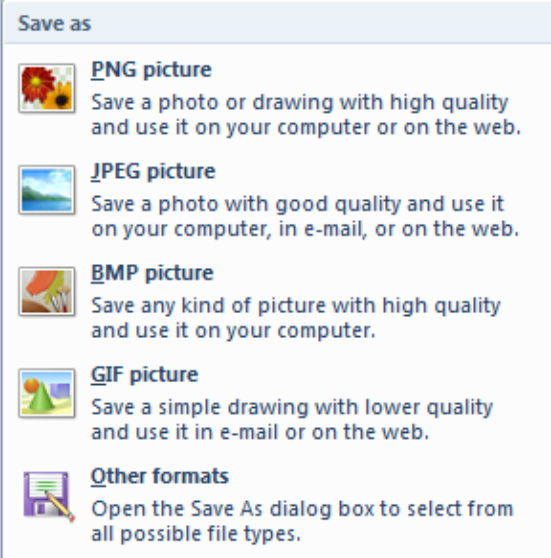
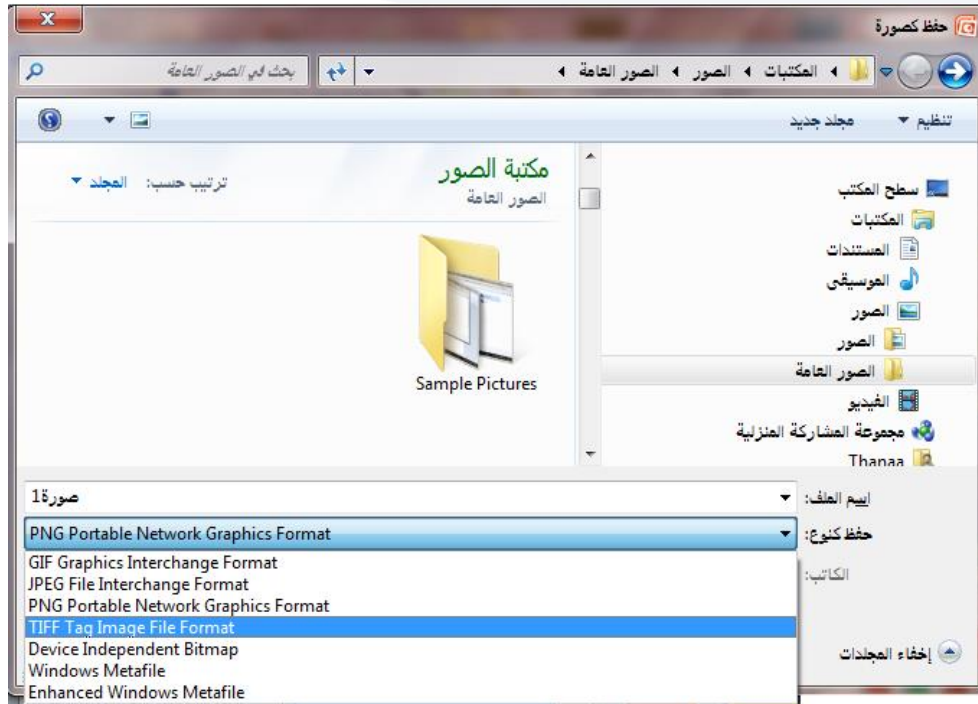
	Binary BW	Grayscale I	Truecolor RGB	Indexed X, map
BW	-	x	x	gray2ind
I	im2bw	-	x	gray2ind
RGB	im2bw	rgb2gray	-	rgb2ind
X, map	im2bw	rgb2gray	ind2rgb	-

# صيغ ملفات الصور

□ يعطي نوع ملف الصورة معلومات عن التخزين في الذاكرة والأرشفة وتبادل بيانات الصور

□ معايير اختيار صيغة مناسبة لصورة ما:

- نوع وحجم الصورة
- المساحة التخزينية وضغط الصورة (Lossy, Lossless)
- التوافق
- مجال التطبيق



## □ صيغة ملفات الصور الدلالية "الموسومة" Tagged Image File Format (TIFF)

- Compressed TIFF , Uncompressed TIFF
- ملفات TIFF غير المضغوطة تستهلك مساحة تخزينية كبيرة

## □ صيغة تبادل الرسوم Graphics Interchange Format (GIF)

- تدعم تشفير الرسوم المتحركة البسيطة graphics
- تدعم الصور المفهرسة indexed image (256 لون فقط)

## □ الرسومات المحمولة على الشبكة Portable Network Graphics (PNG)

- مناسبة لأغراض التصفح والتبادل عبر الشبكات لكن لا تدعم تشفير الرسوم المتحركة

# أشهر صيغ ملفات الصور المستخدمة

## □ صيغة مجموعة خبراء التصوير المشتركة (JPEG) Joint photographic Experts Group

- تسمح بمستويات مختلفة من جودة الصور ومدعومة من مختلف أنظمة التشغيل
- تسبب ظهور artifacts عند نسب الضغط الكبيرة

## □ صور ويندوز النقطية (BMP) Windows Bitmap

- غير مدعومة في أنظمة التشغيل المغايرة لـ windows
- تخزن القيم اللونية للبكسلات بدون ضغط لذا فهي مناسبة لأغراض الطباعة

## □ التصوير والاتصال الرقمي في الطبّ (DICOM) Digital Imaging and Communications in Medicine

- معيار متكامل لالتقاط وتخزين وتبادل الصور الطبية

# مقارنة

FORMAT	FILE EXTENSION	TYPE OF COMPRESSION	METHODS	USAGE
BMP (bitmap)	.bmp	Considerably compressed with lossless	ZIP	used to store bitmap digital images
JPEG (Joint Photographic Experts Group)	.jpg , .jpeg , .jpe	Lossy  Lossless	- Discrete Cosine Transform (DCT) & Chroma Subsampling - Run-Length Encoding (RLE)	For natural images
GIF (Graphics Interchange Format)	.gif , .giff , .gfa	Lossless	LZW (Lempel-Ziv-Welch)	For artificial images (sharp-edge lines and few colors) & support animation
PNG (Portable Network Graphics)	.png	Lossless	DEFLATE	Better compression & features than GIF, but don't support animation
TIFF (Tagged Image File Format)	.tiff , .tif	Lossless	RLE / LZW / DEFLATE / ZIP	Flexible file format, can store multiple images in a single file
JPEG2000	jp2, .j2c, jpc, j2k, jpx	Lossy & Lossless	Discrete Wavelet Transform (DWT)	Better image quality than JPEG (up to 20%), not widely used because of some patent issues.



Original file



.tiff



.gif



.bmp

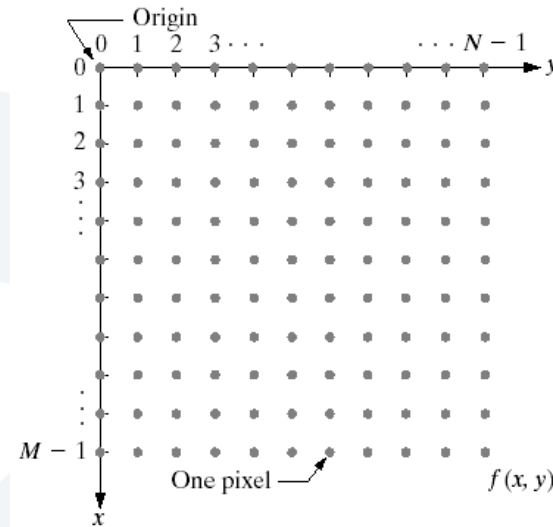


.jpg



.png





$$f(x,y) \equiv \begin{vmatrix} f(0,0) & f(0,1) & \dots & f(0,N-1) \\ f(1,0) & f(1,1) & \dots & f(1,N-1) \\ \vdots & \vdots & \ddots & \vdots \\ f(M-1,0) & f(M-1,1) & \dots & f(M-1,N-1) \end{vmatrix}$$

An image that has been discretized both in Spatial coordinates and associated value.

An image: a multidimensional function of spatial coordinates.

- ❖ **Spatial coordinate** (point set ):  $(x,y)$  for 2D case such as photograph,  $(x,y,z)$  for 3D case such as color image
- ❖ **The function  $f$**  (value set) may represent intensity (for monochrome images) or color (for color images) or other associated values.

An element of the image,  $(x,y), f(x,y)$  is called a **pixel**

where:

- $x,y$  is called the pixel location and
- $f(x,y)$  is the pixel value at the location  $x,y$

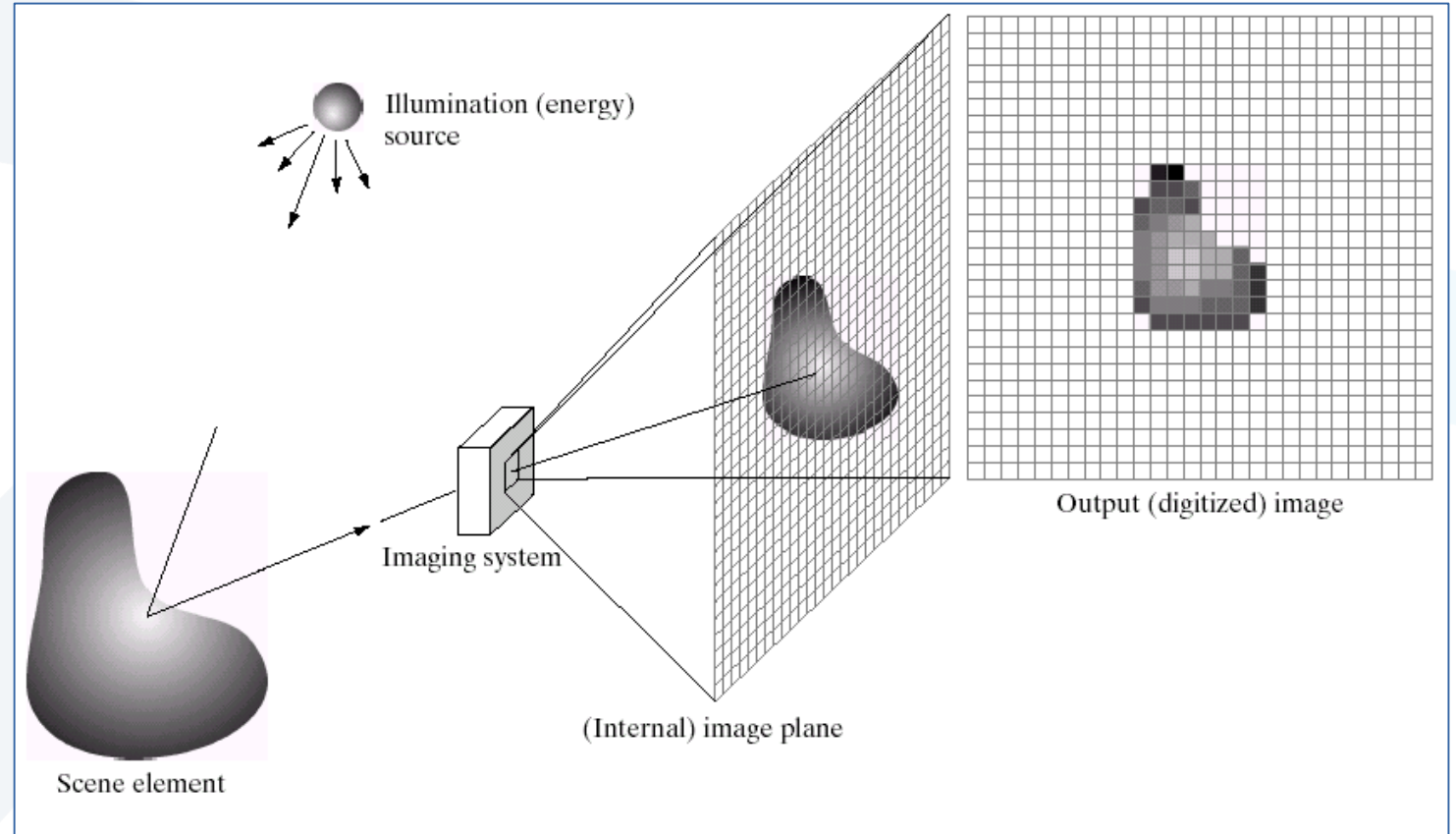
# Digitization Process

To convert continuous image (in real life)  
to digital image (in computer) we use  
Two processes:

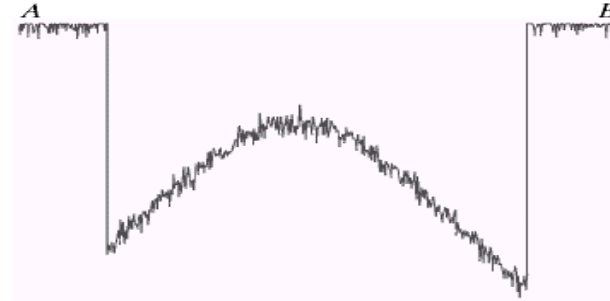
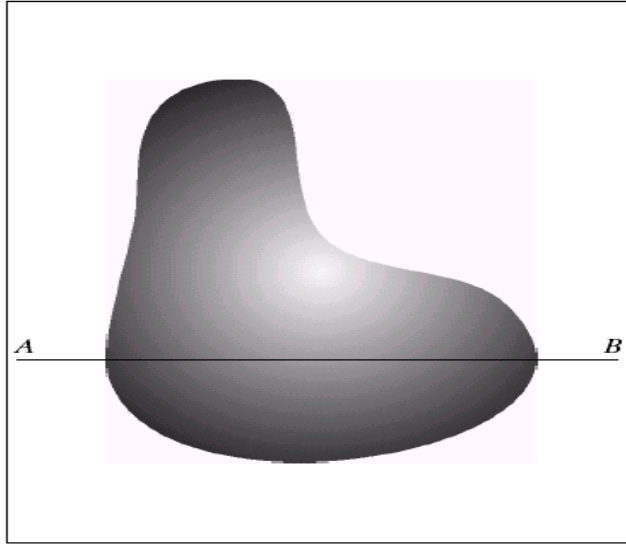
**Sampling:** digitizing the coordinate  
values

**Quantization:** digitizing the  
amplitude values or intensities.

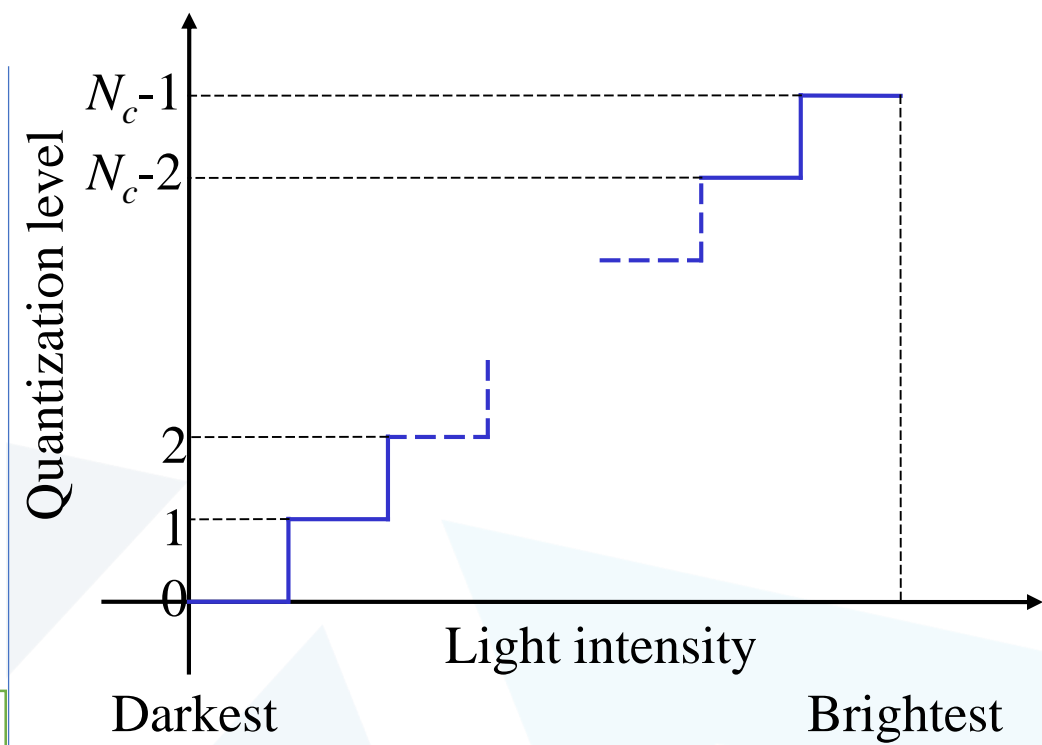
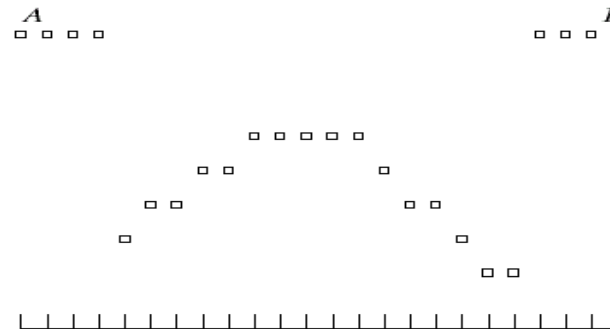
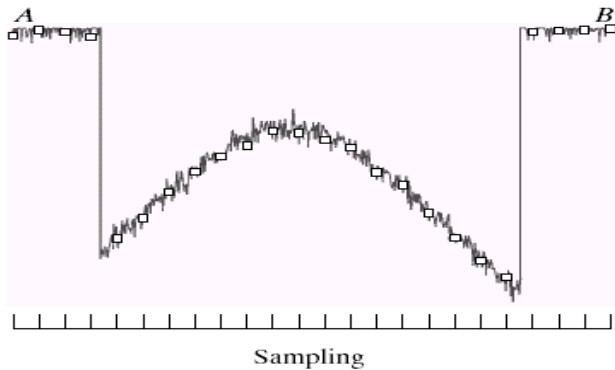
- Thus, when  $x$ ,  $y$  and  $f$  are all finite,  
discrete quantities, we call the  
image a digital image.



# Digitization Process- Sampling and Quantization function



Gray-level scale that divides gray-level into 8 discrete levels from  $b(0)$  to  $w(7)$



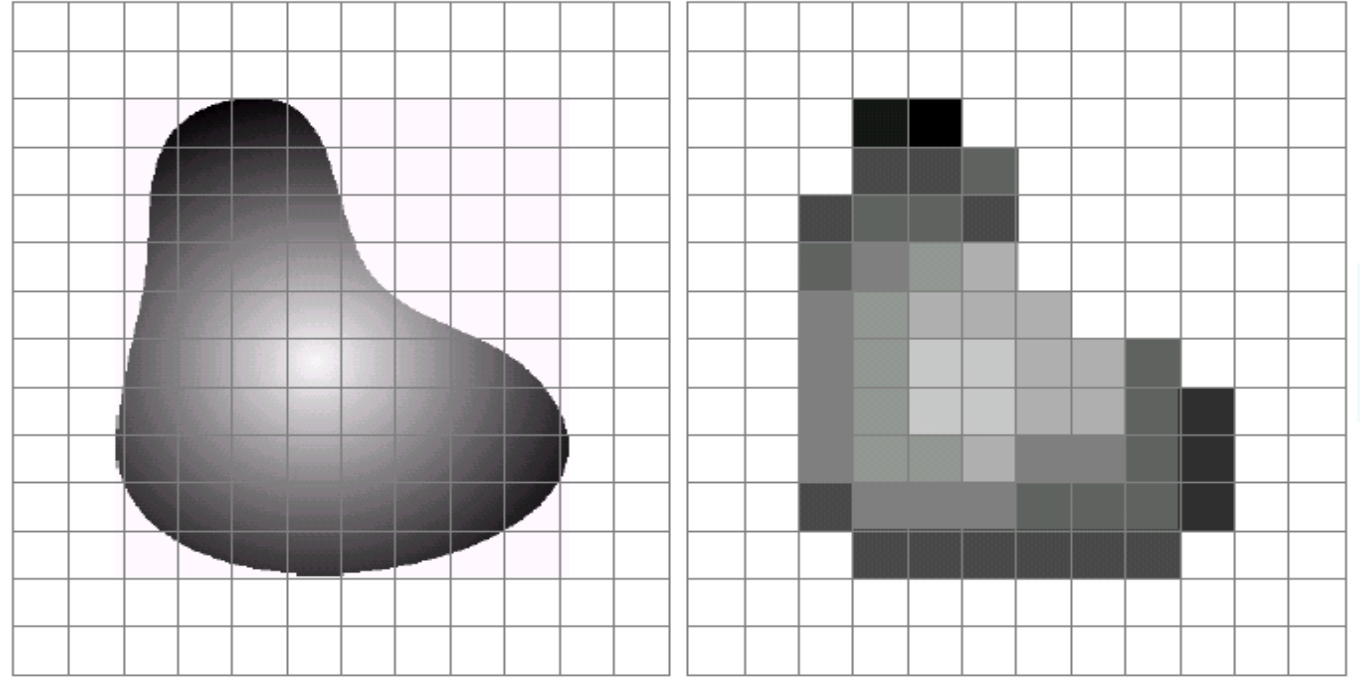
- **Image sampling:** discretize an image in the spatial domain (digitizing coordinates)
- **Image quantization:** discretize or convert continuous pixel values (each sample gray level value) into discrete numbers (digital quantity) -> digitizing intensities

**sample** is a small white square, located by a vertical tick mark as a point  $x,y$



# Digitization Process- Sampling and Quantization function

The continuous image VS the result of digital image after sampling and quantization



a b

**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.

## عمق البت bit depth أو عمق البكسل pixel depth

- **BIT DEPTH** is determined by the number of bits used to define each pixel. The greater the bit depth, the greater the number of tones (grayscale or color) that can be represented.
- **Pixel depth**, also known as bit depth, refers to the amount of information stored in each pixel of a digital image. It is typically measured in bits per pixel (bpp), with common values being 1 bpp (black and white), 8 bpp (grayscale)

يعتمد عدد سويات الشدة الضوئية المستخدمة  $L$  لتمثيل الصورة على  $k$  عدد البتات المخصصة لترميز كل بكسل، وهو ما يدعى عمق البت أو عمق البكسل

$$k=8$$

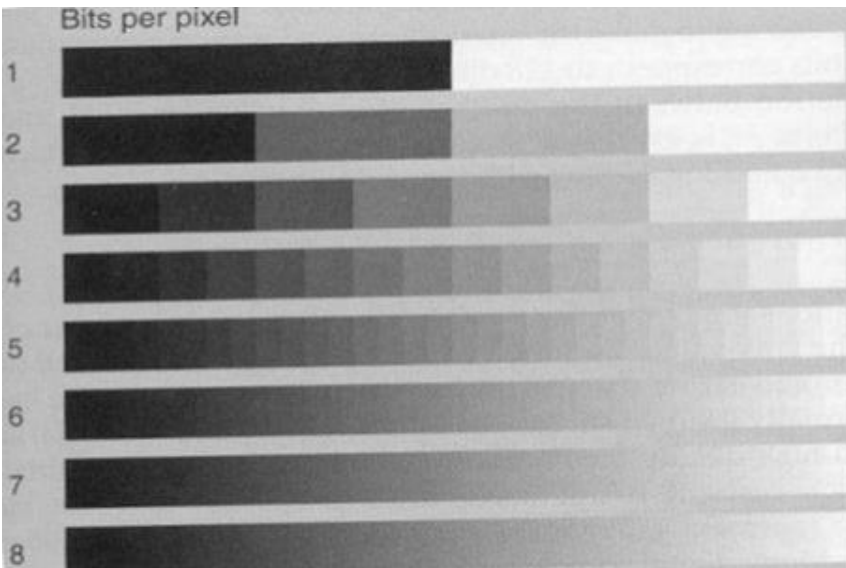
مثال:

$$L = 2^k \text{ where } k = \text{No. of bits representing each pixel value}$$

$L=256$  ;  $[0-255]$  No. of colors or gray levels OR Color resolution/ color depth/ levels:

- **Color depth** refers to the maximum number of colors an image can contain. Color depth is determined by the bit depth of an image (the number of binary bits that define the shade or color of each pixel in a bitmap). For example, a pixel with a bit depth of 1 can have two values: black and white.

$$b = M * N * K \quad \text{حجم الصورة بالبتات}$$



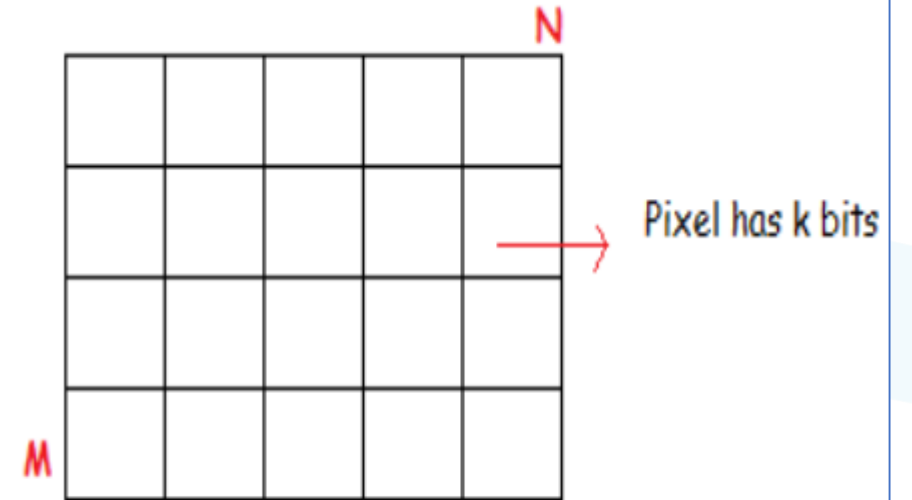
# Number of storage of bits:

- $N * M$ : the no. of pixels in all the image.
- $K$ : no. of bits in each pixel
- $L$ : grayscale levels the pixel can represent:  $L = 2^K$
- all bits in image =  $N * M * k$

EX: Here:  $M=N=32$ ,  $K=3$ ,  $L = 2^3=8$

# of pixels =  $N * M = 1024$  . (because in this example:  $M=N$ )

# of bits =  $N * M * K = 1024 * 3 = 3072$  bits.



NO of pixels =  $N * M$

NO of bits =  $N * M * k$

# Effect of Quantization Levels



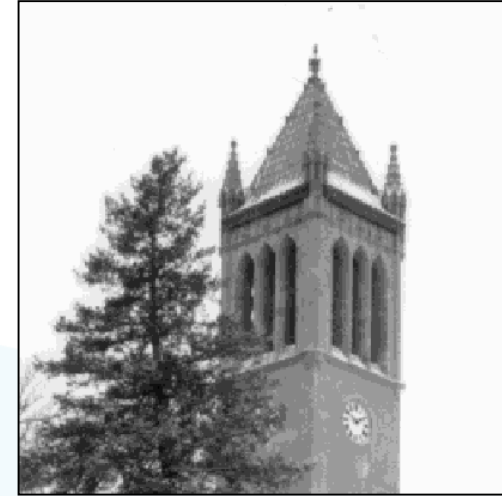
256 levels



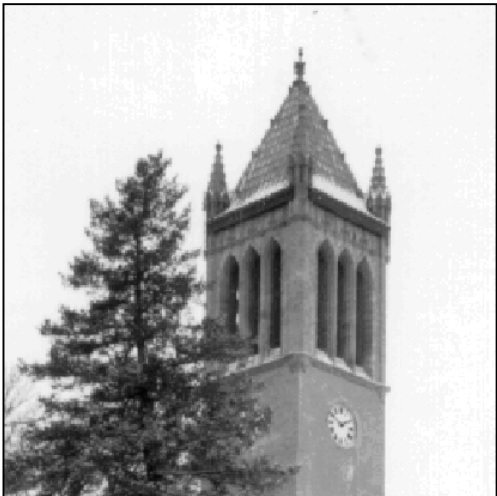
128 levels



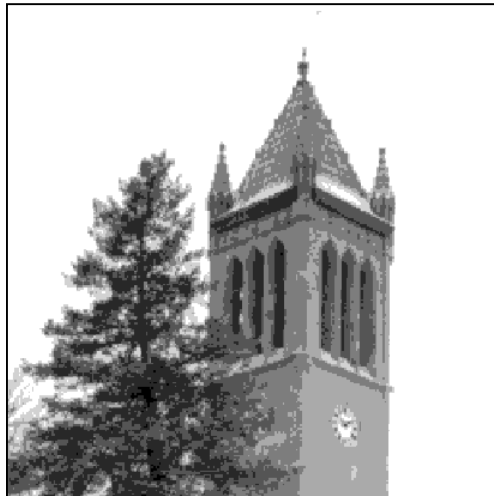
16 levels



8 levels

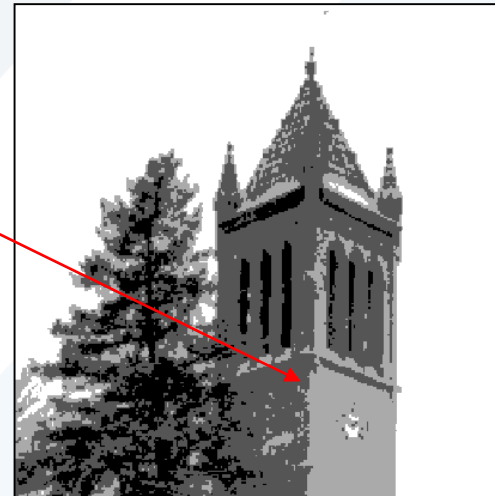


64 levels

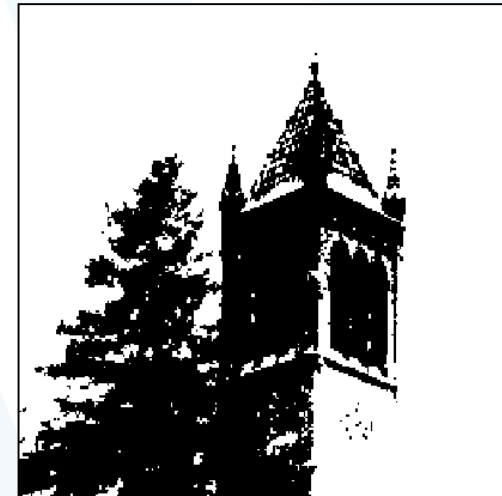


32 levels

In this image,  
it is easy to see  
false contour.



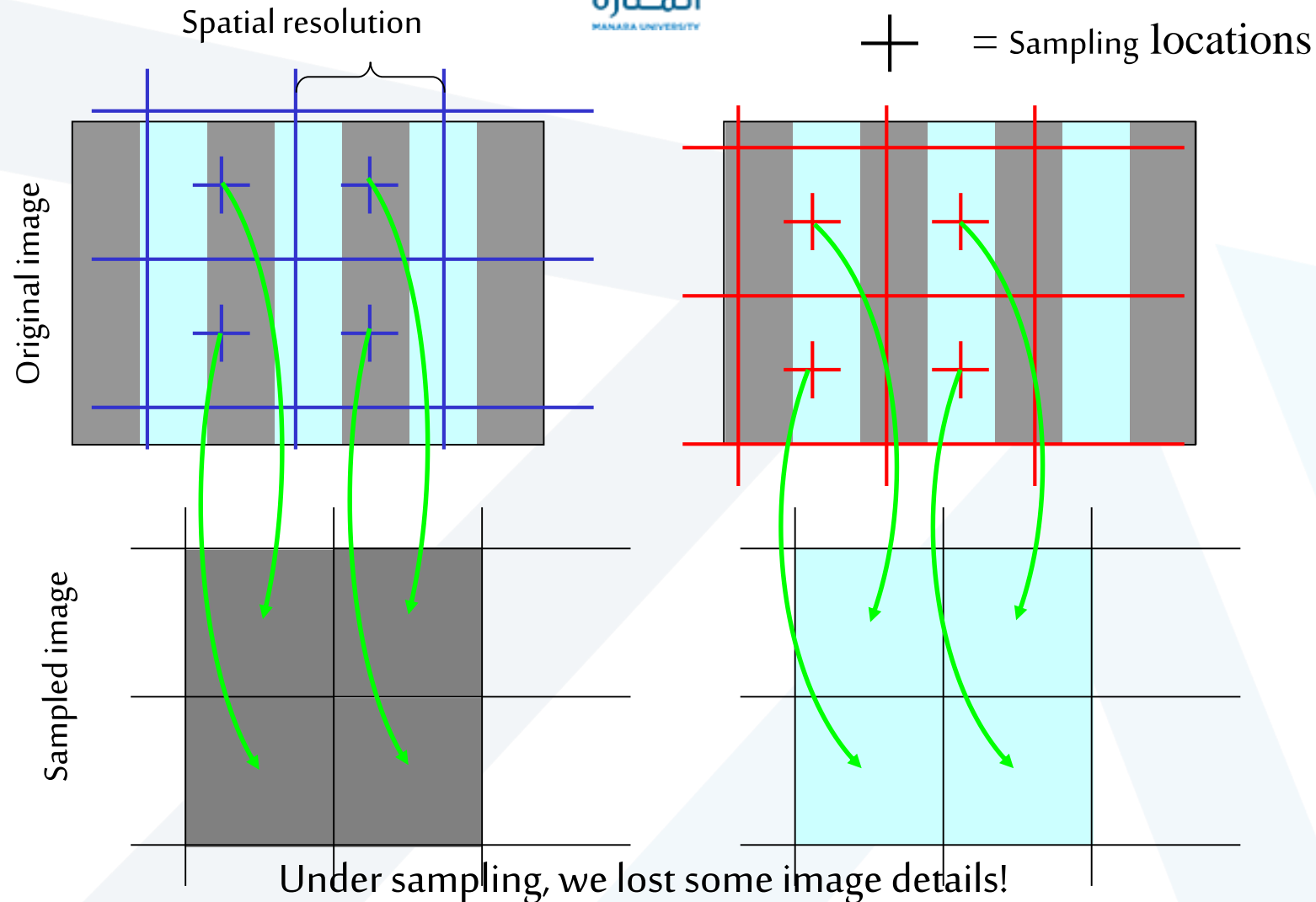
4 levels



2 levels

# Effect of Spatial Resolution

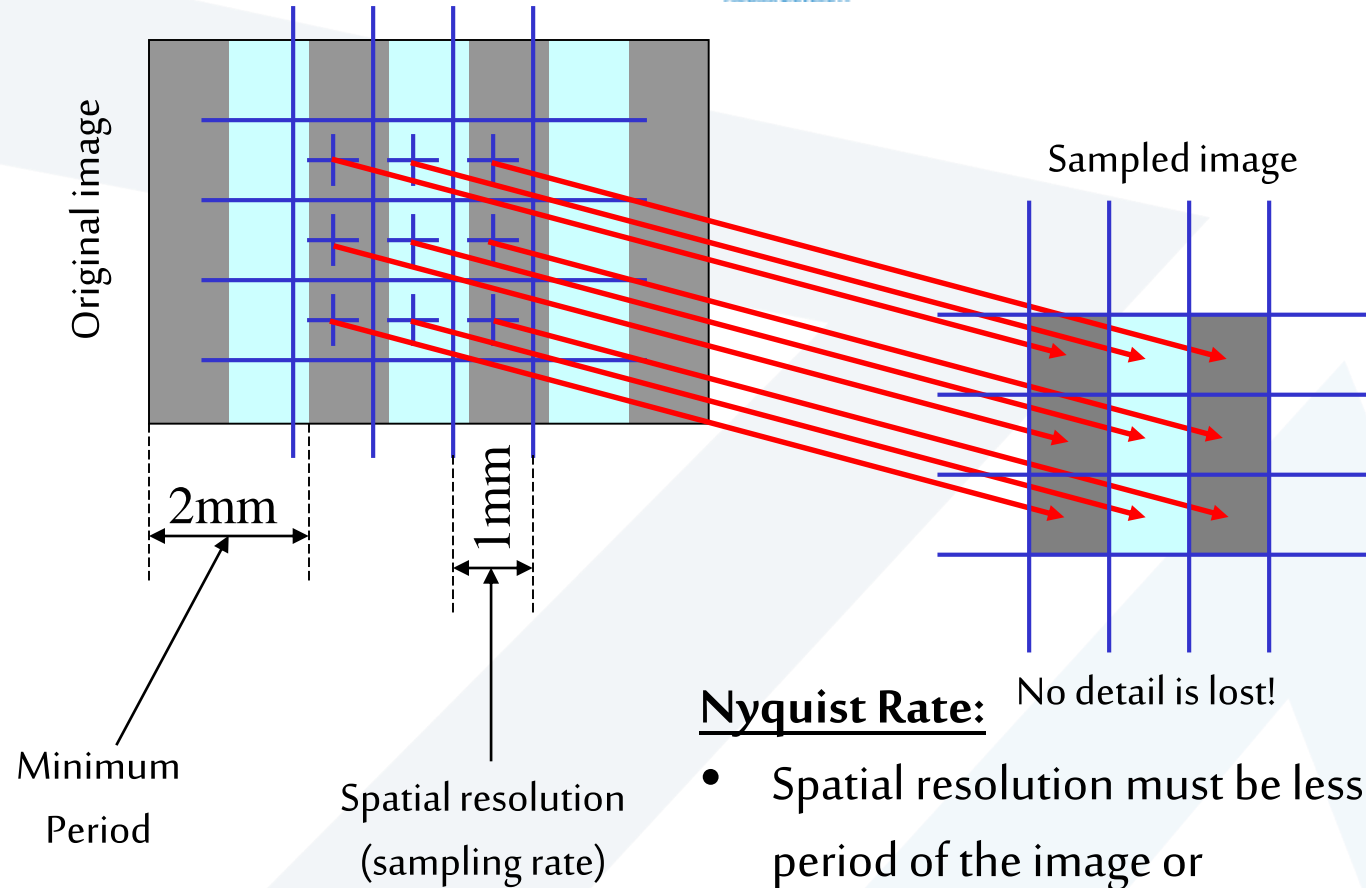
How to choose the spatial resolution



# Effect of Spatial Resolution

How to choose the spatial resolution :

Nyquist Rate



## Nyquist Rate:

- Spatial resolution must be less or equal half of the minimum period of the image or
- sampling frequency must be greater or Equal twice of the maximum frequency.



= Sampling locations

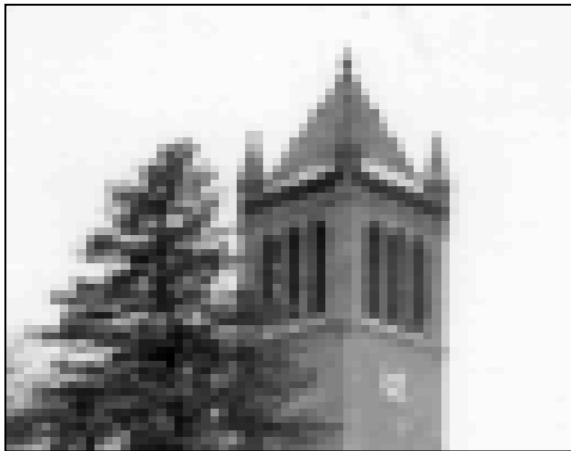
# Effect of Spatial Resolution



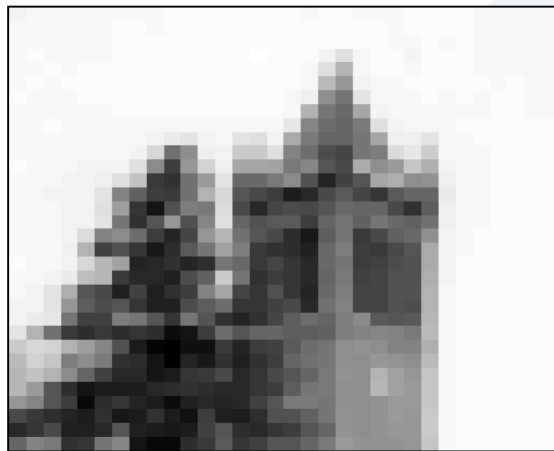
256x256 pixels



128x128 pixels



64x64 pixels



32x32 pixels



1X1



10X10



50X50



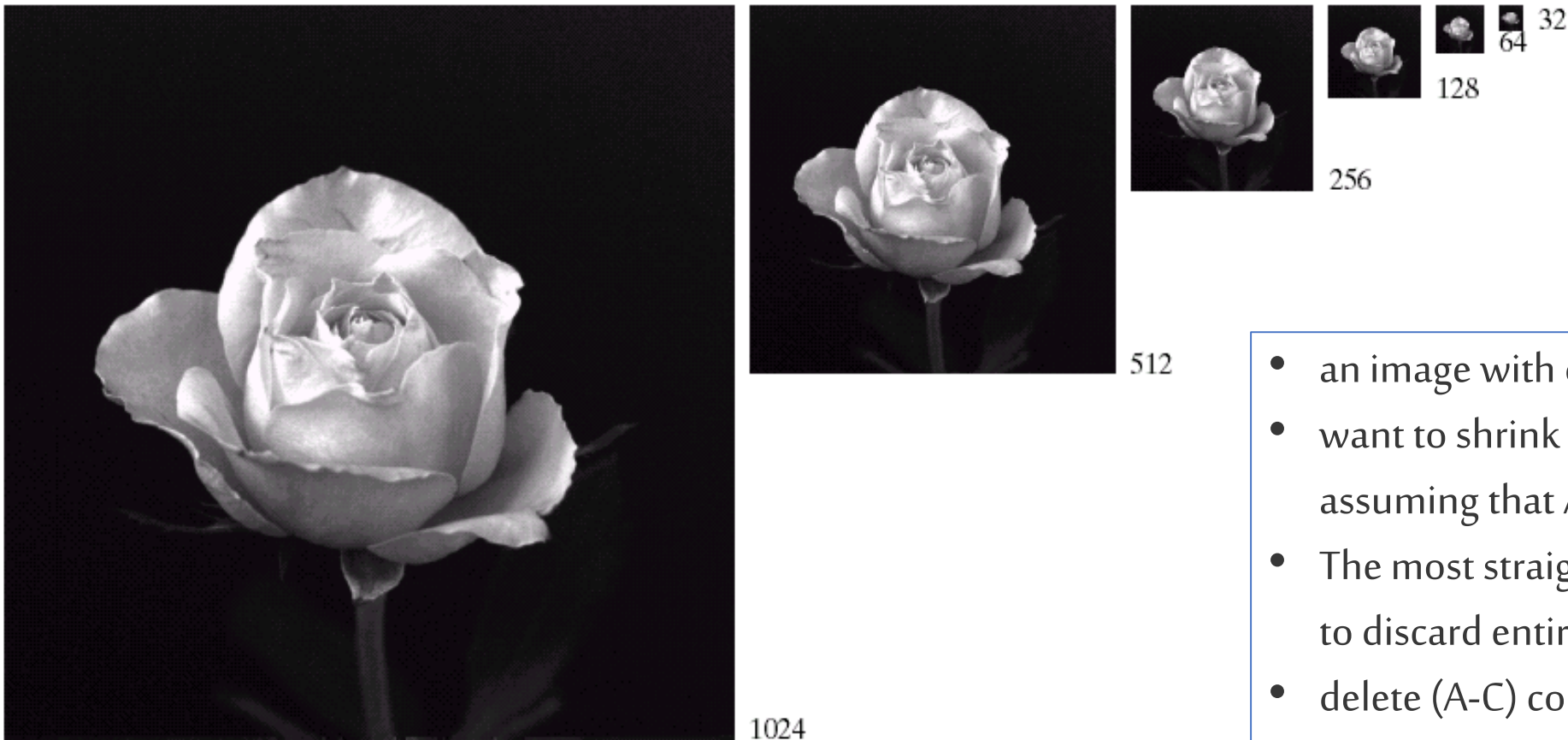
100X100

insufficient spatial  
resolution-> appearance  
of checkerboard pattern  
in the image



# Effect of Spatial Resolution Downsampling

**Downsampling:**  
“shrinking” an image’s dimensions you are essentially throwing away image information.  
(note: this is NOT the same as image compression),

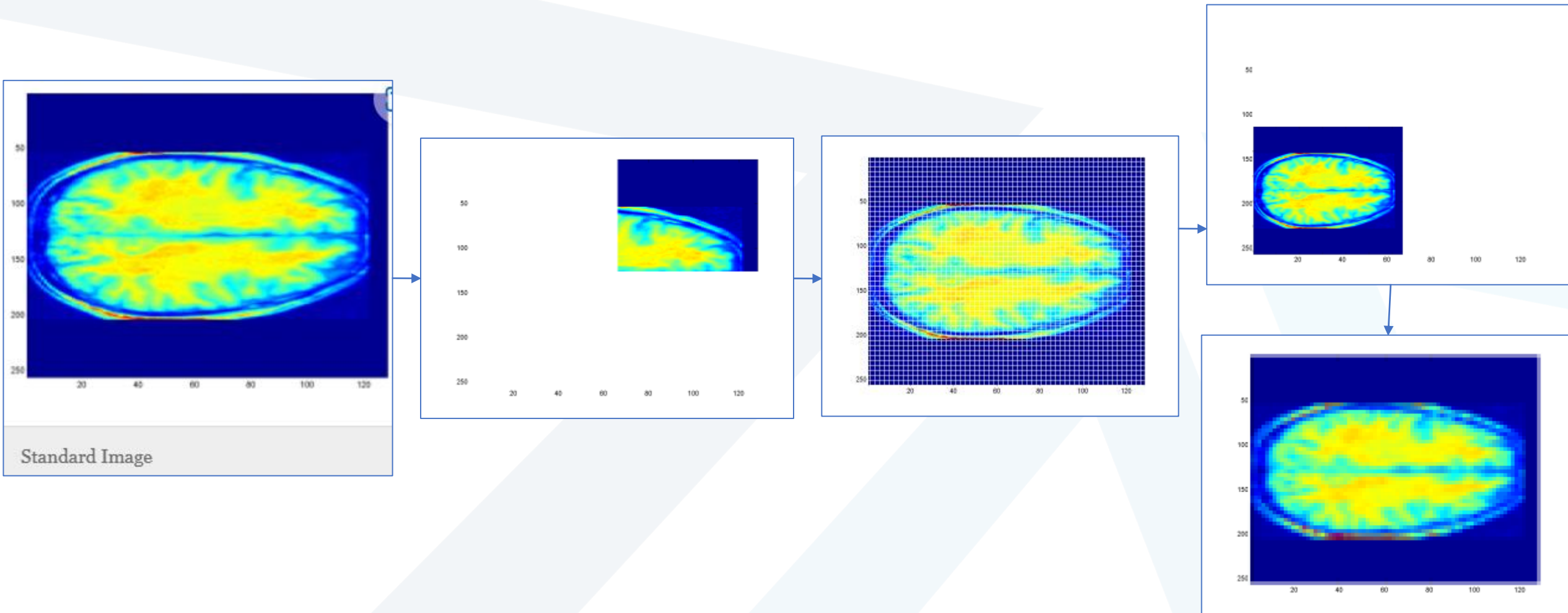


- an image with dimensions  $A \times B$ ,
- want to shrink it to the dimensions of  $C \times D$ , assuming that  $A > C$  and  $B > D$ .
- The most straightforward way to do this is to discard entire columns/rows of data.
- delete  $(A-C)$  columns, and  $(B-D)$  rows.

**FIGURE 2.19** A  $1024 \times 1024$ , 8-bit image subsampled down to size  $32 \times 32$  pixels. The number of allowable gray levels was kept at 256.



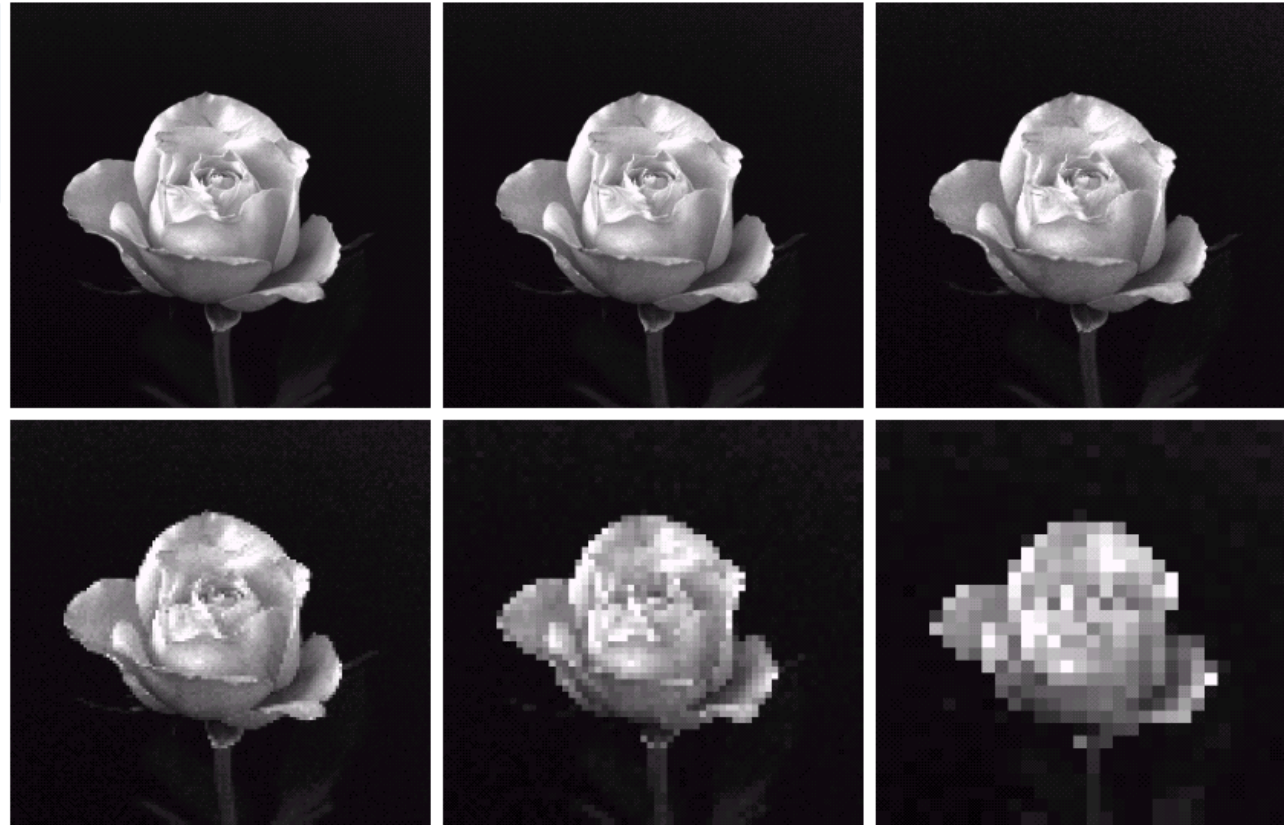
# Effect of Spatial Resolution Downsampling



## Effect of Spatial Resolution Upsampling (duplication):

### Upsampling (duplication):

basically expanding an image, and filling in “gaps” in rows and columns of the original image. For example, say we want to increase the width and height of an image by a factor of 4. We could simply “repeat/redraw” each row and column of the original image 4 times.



a	b	c
d	e	f

**FIGURE 2.20** (a)  $1024 \times 1024$ , 8-bit image. (b)  $512 \times 512$  image resampled into  $1024 \times 1024$  pixels by row and column duplication. (c) through (f)  $256 \times 256$ ,  $128 \times 128$ ,  $64 \times 64$ , and  $32 \times 32$  images resampled into  $1024 \times 1024$  pixels.

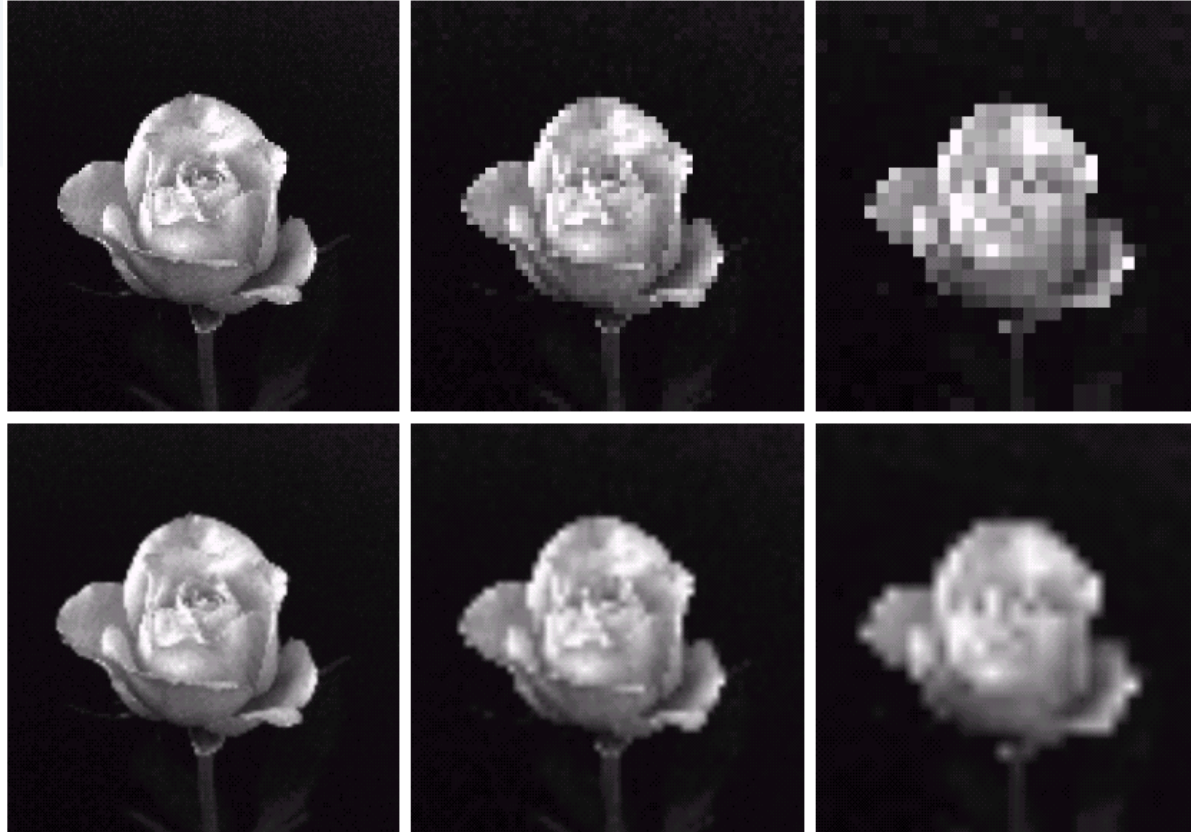
A problem with this approach is that it only works when we want to increase the image dimensions by an integral factor (ie: 2, 4, 10), as it cannot deal with the case of image scaling by a fractional number (2.5, 10/3, etc).



## Effect of Spatial Resolution Upsampling (interpolation):

Can we increase  
spatial resolution by  
interpolation ?

Down sampling is an  
irreversible process.



a b c  
d e f

**FIGURE 2.25** Top row: images zoomed from  $128 \times 128$ ,  $64 \times 64$ , and  $32 \times 32$  pixels to  $1024 \times 1024$  pixels, using nearest neighbor gray-level interpolation. Bottom row: same sequence, but using bilinear interpolation.

- I - Nearest Neighbour Interpolation
- II – Bilinear Interpolation
- III - Bicubic Spline Interpolation
- IV - Generalized Bicubic Interpolation

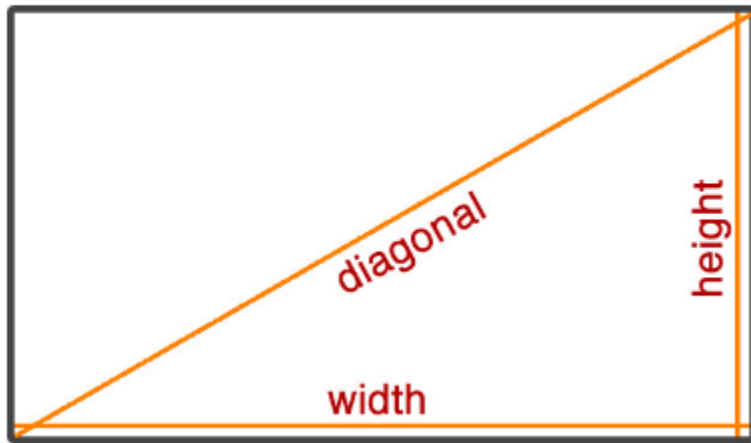
- دقة الصورة هي وحدة قياس لأصغر جزء في الصورة يمكن تمييزه بالعين. تصبح معالم الصورة اوضح تبعا ل:
  1. حجم الصور ويحدد مباشرة من عدد الأسطر  $M$  وعدد الأعمدة  $N$  للمصفوفة الممثلة للصورة وبالتالي عدد البكسلات في الصورة وهو **لا يعطي معلومات دقيقة عن الدقة المكانية** ولا يحدد وضوحها لوحده.
  2. Spatial resolution الدقة المكانية: كلما كانت البكسلات متقاربة كانت الدقة أعلى. تحدد الدقة المكانية للصورة بعدد العناصر المميزة في واحدة القياس وتقاس بمقاييس مختلفة حسب التطبيق:
    - Dot per inch (dpi): monitors
    - Lines per inch (lpi): laser printers
    - Pixels per inch (ppi): tablets, Mobile- phones
    - Pixel per Km: sattelite images
    - Samples per inch (spi): scanners
  3. **دقة الشدة الضوئية**: عدد القيم أو السويات اللونية الممكنة في الصورة (عمق البت)، كلما كانت اكثر كان لها قدرة اعلى على زيادة الدقة.

**Spatial resolution**: pixel size AND number of pixels



# Calculate PPI

$$\text{diagonal} = \sqrt{\text{width}^2 + \text{height}^2}$$



$$\text{PPI} = \frac{\text{diagonal in pixels}}{\text{diagonal in inches}}$$

- A screen that is 1920 pixels wide by 1080 pixels high
- The diagonal is 10 inches= 25.4cm=254mm

$$\text{diagonal}_{\text{pixels}} = \sqrt{(1920^2 + 1080^2)}$$

$$\text{diagonal}_{\text{pixels}} = \sqrt{(3686400 + 1166400)}$$

$$\text{diagonal}_{\text{pixels}} = \sqrt{4852800}$$

$$\text{diagonal}_{\text{pixels}} = 2202.91 \text{ pixels}$$

$$\text{PPI} = \text{diagonal}_{\text{pixels}} / \text{diagonal}_{\text{inches}}$$

$$\text{PPI} = 2202.91 / 10$$

$$\text{PPI} = 220.29 \text{ pixels}$$

- So there are 220.29 pixels in a 1 inch line on the display (about 220.29/25.4=8.6 pixels per mm).
- $220.29^2 = 48528$  pixels per square inch
- So there are 48528 pixels in an area of the screen that is 1 inch wide by one inch high
- Screen length= 1920/220.29=8.71 inch=221.38 mm
- Screen width=1080/220.29=4.9 inch = 124.5 mm

# How to Calculate the diagonal dot pitch



Diagonal dot pitch is the diagonal distance from the center of one pixel to the center of the next.

Dot pitch is calculated from the diagonal length in inches and pixels then converted from inches per pixel to millimeters per pixel but normally only expressed in millimeters (mm).

$$\text{PPI} = \frac{\text{diagonal in pixels}}{\text{diagonal in inches}}$$

$$\text{dot pitch} = \frac{\text{diagonal in inches}}{\text{diagonal in pixels}} \times \frac{25.4 \text{ mm}}{\text{inch}}$$

If a screen diagonal is 15.4 inches and has 3396 pixels. Dot pitch =  $(15.4/3396) \times 25.4 \approx 0.1152 \text{ mm}$ .

# Example

Pixel total	1000 x 1000 Pixel [ 1 Mpx]	Diagonal in pixels = $\sqrt{1000^2 + 1000^2}$ = 1414.2 <i>pixels</i>
Picture size	10inch*10inch	254 x 254 mm
dpi / ppi	100 dpi	NOTE:1mm = 1000/254=4 pixels Diagonal in inch = $\sqrt{10^2 + 10^2}$ = 14.142 <i>inch</i>
Color depth	8 Bit - MSX2 computer	
Disk space	1 MB	PPI = $diagonal_{pixels} / diagonal_{inches}$
Pitch	254 $\mu m$	PPI = 1414.2/14.142=100 pixel per inch = 100/25.4=4 pixel per mm
Pixel size	64516 $\mu m^2$	PITCH=(1/PPI)*25.4 =(1/100)*25.4=0.254mm

# Does smartphone having same camera sensor have different image quality?



There are several factors that can affect the quality of an image taken with a camera, even if they have the same number of pixels. Some of these factors include:

1. The resolution of the camera in megapixels.
2. The quality of the lens.
3. The sensor size AND The sensor technology used in the camera
4. the image processing software and algorithms used.
5. and the overall design and engineering of the camera.
6. lighting conditions: It's basically your camera's sensitivity to light. The higher the ISO sensitivity, the less light required to take a high-quality image. This is an important factor in determining your balance of settings in low or high light scenarios.
7. Additionally, external factors such as; movement, and subject matter can also play a role in the quality of the final image.
8. **Resolution 2880\*2160      Aperture F1.7      Focal length:4.2mm      Flash      ISO      Exposure time:1/50s**



# Resolution: How Much Is Enough?

The word “suitable” is subjective: depending on “subject”.



The picture on the right is fine for counting the number of cars, but not for reading the number plate



Low detail image  
**Lena image**



Medium detail image  
**Cameraman image**



High detail image

# نهاية المحاضرة