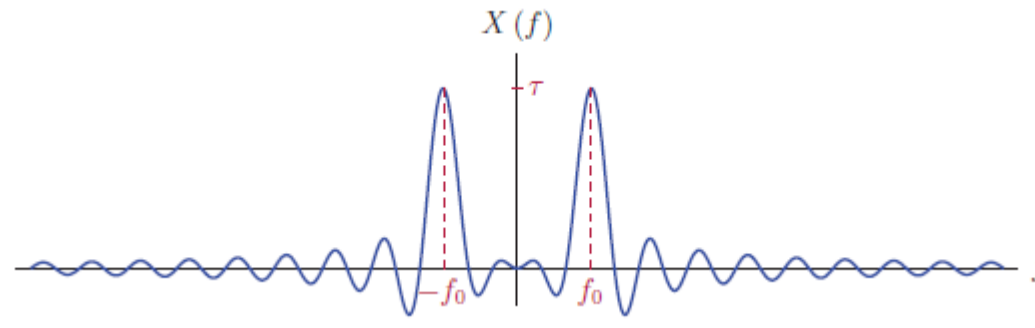


CEDC403: Signals and Systems

Exercises 3: Analyzing Continuous Time Systems in the Time Domain



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1. For each case, determine if the system is linear and/or time-invariant:

a. $y(t) = |x(t)| + x(t)$

b. $y(t) = tx(t)$

c. $y(t) = e^{-t}x(t)$

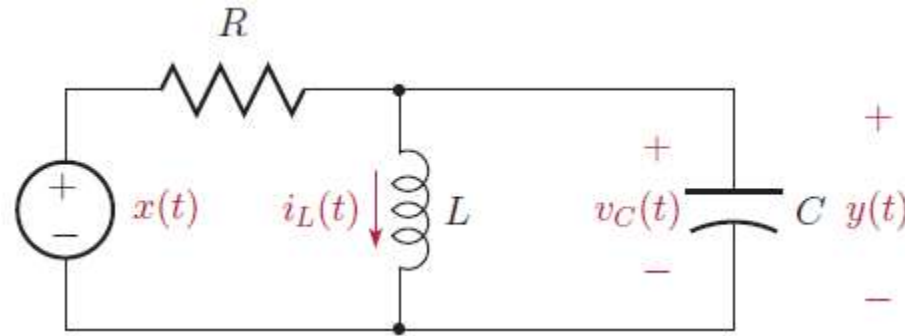
d. $y(t) = \int_{-\infty}^t x(\tau) d\tau$

e. $y(t) = \int_{t-1}^t x(\tau) d\tau$

f. $y(t) = (t + 1) \int_{-\infty}^t x(\tau) d\tau$

2. Differential equation for RLC circuit:

Find a DE between the input $x(t)$ and the output $y(t)$. At $t = 0$ the initial values are $i_L(0) = 1$ A, $v_C(0) = 2$ V. Express the initial conditions for $y(t)$ and $dy(t)/dt$.

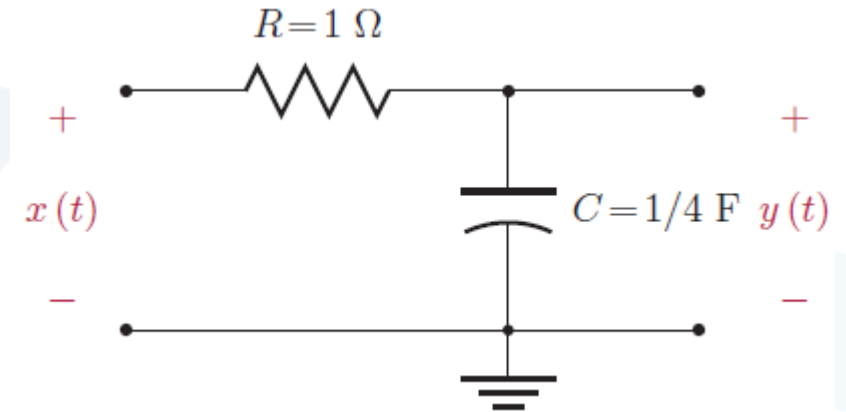


3. Consider the differential equation for the RC circuit :

$$\frac{dy(t)}{dt} + 4y(t) = 4x(t)$$

Let the input signal be a unit step, that is, $x(t) = u(t)$. Using the first-order differential equation solution technique find the solution $y(t)$ for $t \geq 0$ subject to each initial condition specified below:

- $y(0) = 0$
- $y(0) = 5$



4. Solve each of the first-order differential equations given below for the specified input signal and subject to the specified initial condition:

a. $\frac{dy(t)}{dt} + 2y(t) = 2x(t), \quad x(t) = u(t) - u(t - 5), \quad y(0) = 2$

b. $\frac{dy(t)}{dt} + 5y(t) = 3x(t), \quad x(t) = \delta(t), \quad y(0) = 0.5$

c. $\frac{dy(t)}{dt} + 5y(t) = 3x(t), \quad x(t) = tu(t), \quad y(0) = -4$

d. $\frac{dy(t)}{dt} + y(t) = 2x(t), \quad x(t) = e^{-2t}u(t), \quad y(0) = -1$

5. For each homogeneous DE given below, find the homogeneous solution for $t \geq 0$ in each case subject to the initial conditions specified condition:

a. $\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) = 0, \quad y(0) = 3, \quad \left. \frac{dy(t)}{dt} \right|_{t=0} = 0$

b. $\frac{d^3 y(t)}{dt^3} + 6 \frac{d^2 y(t)}{dt^2} + 11 \frac{dy(t)}{dt} + 6y(t) = 0, \quad y(0) = 2, \quad \left. \frac{dy(t)}{dt} \right|_{t=0} = -1, \quad \left. \frac{d^2 y(t)}{dt^2} \right|_{t=0} = 1$

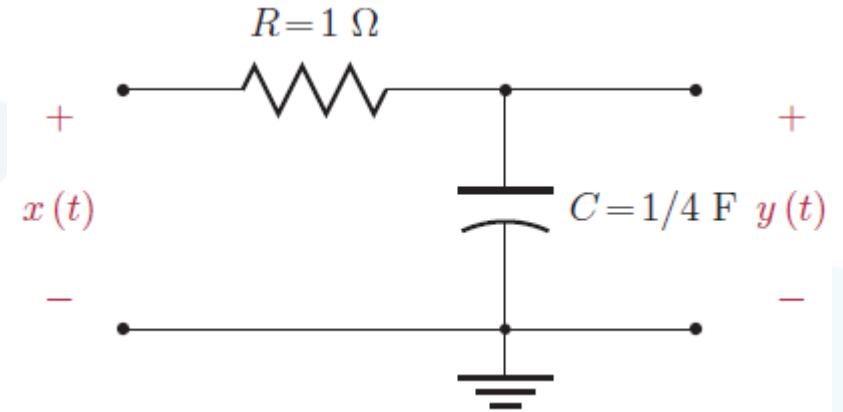
c. $\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} = 0, \quad y(0) = 2, \quad \left. \frac{dy(t)}{dt} \right|_{t=0} = 0$

d. $\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 2y(t) = 0, \quad y(0) = -2, \quad \left. \frac{dy(t)}{dt} \right|_{t=0} = -1$

6. Consider the differential equation for the RC circuit :

$$\frac{dy(t)}{dt} + 4y(t) = 4x(t)$$

Assuming the circuit is initially relaxed, compute and sketch the response to a sinusoidal input signal in the form $x(t) = 5\cos(8t)$

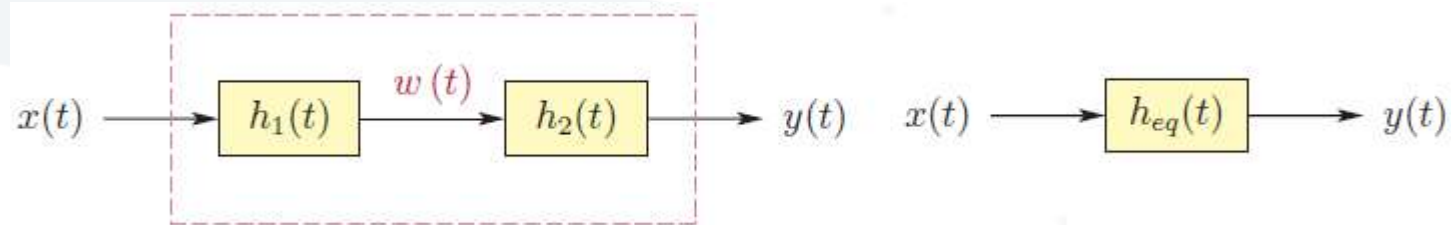


7. A system is described by the differential equation:

$$\frac{d^2y(t)}{dt^2} + 4\frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} - 2x(t), \quad y(0) = -2, \quad \left.\frac{dy(t)}{dt}\right|_{t=0} = 1$$

Draw a block diagram

8. Two CTLTI systems with impulse responses $h_1(t)$ and $h_2(t)$ are connected in cascade:



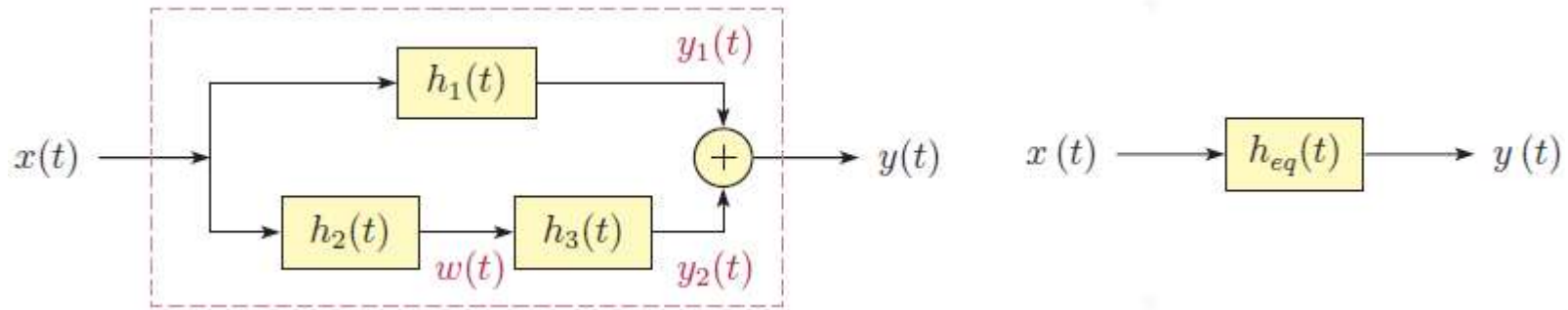
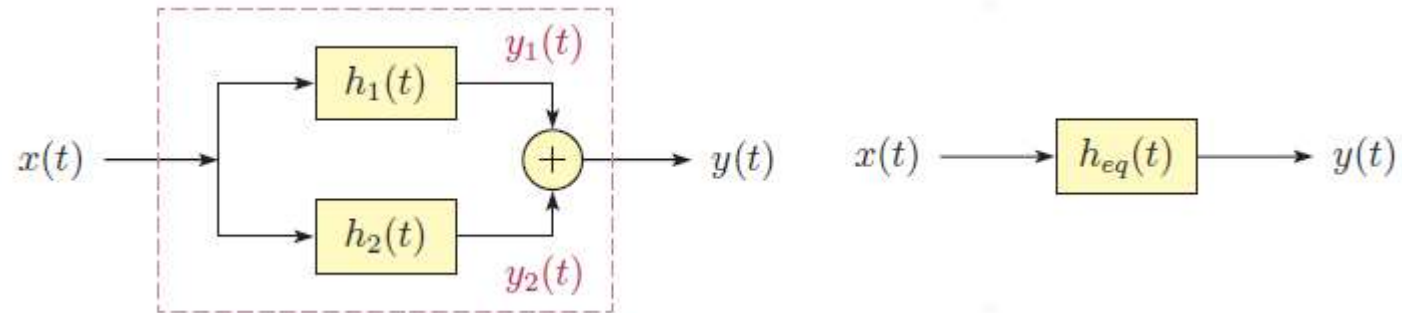
a. Determine the impulse response $h_{eq}(t)$ of the equivalent system, in terms of $h_1(t)$ and $h_2(t)$.

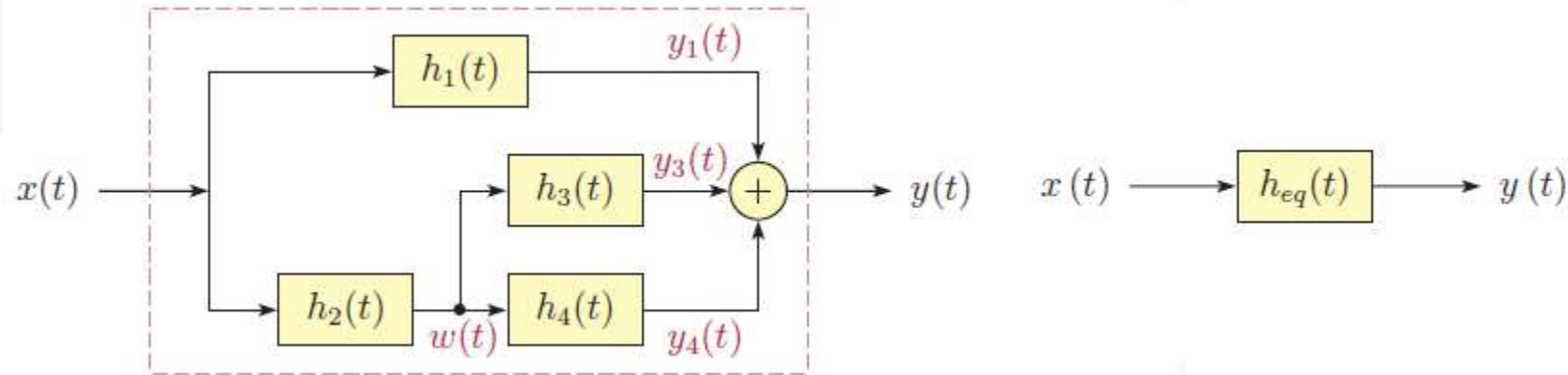
Hint: Use convolution to express $w(t)$ in terms of $x(t)$. Afterwards use convolution again to express $y(t)$ in terms of $w(t)$.

b. Let $h_1(t) = h_2(t) = \Pi(t - 0.5)$ where $\Pi(t)$ is the unit pulse. Determine and sketch $h_{eq}(t)$ for the equivalent system.

c. With $h_1(t)$ and $h_2(t)$ as specified in part (b), let the input signal be a unit step, that is, $x(t) = u(t)$. Determine and sketch the signals $w(t)$ and $y(t)$.

9. Determine the impulse response $h_{eq}(t)$ of the equivalent system:

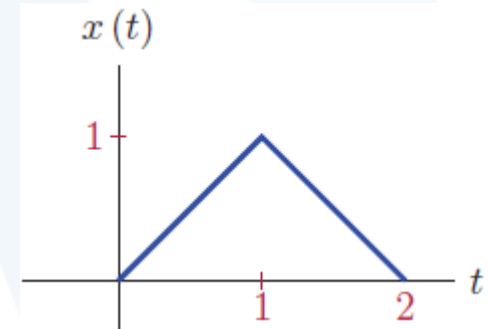




10. The impulse response of a CTLTI system is:

$$h(t) = \delta(t) - \delta(t - 1)$$

Determine sketch the response of this system to the triangular waveform



11. For each pair of signals $x(t)$ and $h(t)$ given below, find the convolution $y(t) = x(t) * h(t)$.

a. $x(t) = u(t), \quad h(t) = e^{-2t}u(t)$

b. $x(t) = u(t - 2), \quad h(t) = e^{-2t}u(t)$

c. $x(t) = u(t) - u(t - 2), \quad h(t) = e^{-2t}u(t)$

d. $x(t) = e^{-t}u(t), \quad h(t) = e^{-2t}u(t)$

12. For each pair of signals $x(t)$ and $h(t)$ given below, find the convolution $y(t) = x(t) * h(t)$ first graphically, and then analytically.

a. $x(t) = \Pi\left(\frac{t-2}{4}\right), \quad h(t) = u(t)$

b. $x(t) = 3\Pi\left(\frac{t-2}{4}\right), \quad h(t) = e^{-t}u(t)$

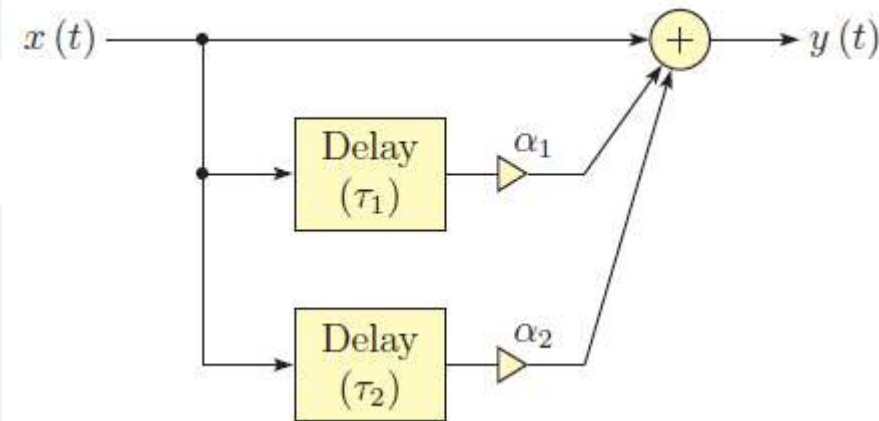
c. $x(t) = \Pi\left(\frac{t-2}{4}\right), \quad h(t) = \Pi\left(\frac{t-3}{6}\right)$

13. The system shown represents addition of echos to the signal $x(t)$:

$$y(t) = x(t) + \alpha_1 x(t - \tau_1) + \alpha_2 x(t - \tau_2)$$

Comment on the system's

- a. Linearity
- b. Time invariance
- c. Causality
- d. Stability



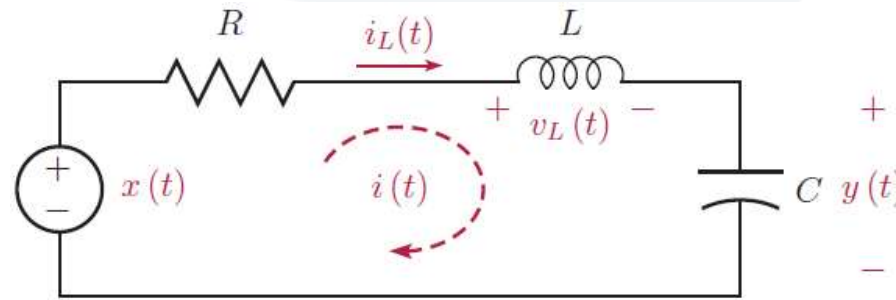
14. For each system described below find the impulse response. Afterwards determine if the system is causal and/or stable.

a. $y(t) = T\{x(t)\} = \int_{-\infty}^t x(\tau) d\tau$

b. $y(t) = T\{x(t)\} = \int_{t-T}^t x(\tau) d\tau, \quad T > 0$

c. $y(t) = T\{x(t)\} = \int_{t-T}^{t+T} x(\tau) d\tau, \quad T > 0$

15. Consider the RLC circuit shown, where the input is a voltage source $x(t)$ and the output the voltage $y(t)$ across the capacitor. Let $LC = 1$ and $R/L = 2$. Find the impulse response $h(t)$ of the circuit.

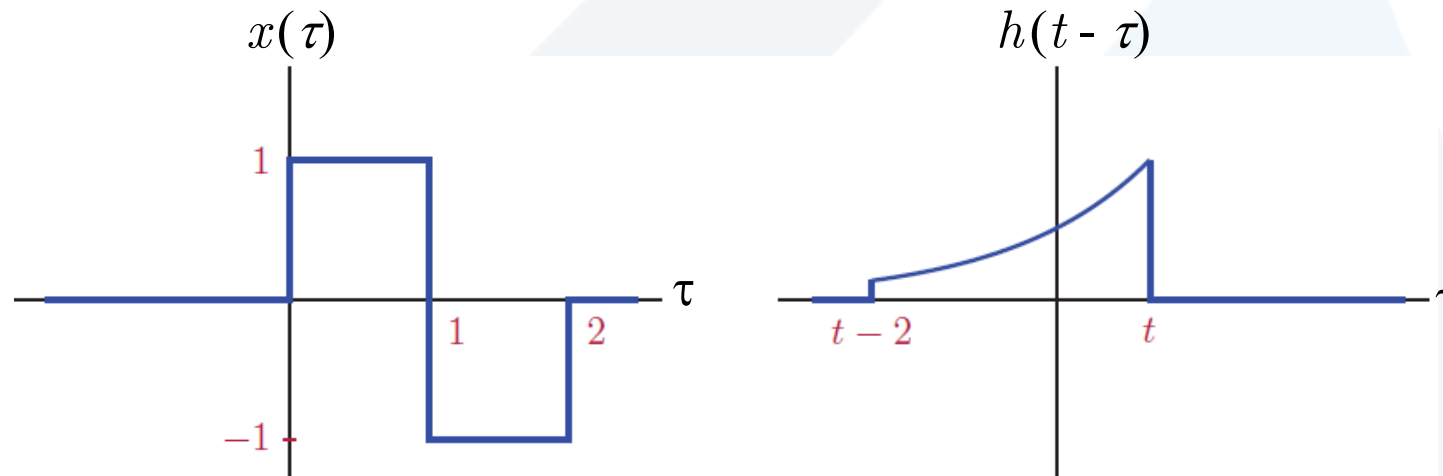


16. Determine the step response of the RC circuit using the convolution operation.
17. Using convolution, determine the response of the RC circuit to a unit-pulse input signal $x(t) = \Pi(t)$.

18. Consider a system with the impulse response $h(t) = e^{-t} [u(t) - u(t - 2)]$
Let the input signal applied to this system be

$$x(t) = \Pi(t - 0.5) - \Pi(t - 1.5) = \begin{cases} 1 & 0 \leq t < 1 \\ -1 & 1 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

Determine the output signal $y(t)$ using convolution.



19. A voltage $x(t) = 10e^{-3t}u(t)$ is applied at the input of the RLC circuit. Find the output voltage $v_C(t) = y(t)$ for $t \geq 0$ if the initial inductor current is $i_L(0^-) = 0$, and the initial capacitor voltage $v_C(0^-) = 5$ V. Use $R = 3 \Omega$, $L = 1$ H and $C = 1/2$ F.
20. Find the output loop current $i_L(t) = y(t)$ for $t \geq 0$ for the circuit described in exercise 19.