

البرمجة الإجرائية

Lecture No. 12

Syms - Solve equations - dsolve

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2024

syms-solve

```
syms x
eqn = sin(x) == 1;
solx1 = solve(eqn, x)
```

solx1 =

pi/2

Workspace

Name ^	Value	Size	Class
eqn	1x1 sym	1x1	sym
solx1	1x1 sym	1x1	sym
x	1x1 sym	1x1	sym

Variables

x

1x1 sym

Variables - eqn

x eqn

1x1 sym

Variables - solx1

x eqn solx1

1x1 sym

val =

x

val =

sin(x) == 1

val =

pi/2

```
syms p x r
solx2 = solve(p*sin(x) == r, x)
solx3 = solve(p*sin(x) == r)
%chooses 'x' as the unknown and returns
```

solx2 =
asin(r/p)
pi - asin(r/p)

solx3 =
asin(r/p)
pi - asin(r/p)

syms-solve



```
syms x y
solx4 = solve(x^2 - 4*x + 4 == 0, x)
```

```
solx4 =
 2
 2
```

```
syms x y
solx5 = solve(x^2 + x*y + y == 3, x)
```

```
solx5 =
- y/2 - (y^2 - 4*y + 12)^(1/2)/2
(y^2 - 4*y + 12)^(1/2)/2 - y/2
```

Syms-solve



```
Editor - Untitled.m
Sx Sx(1, 1) Sx(2, 1)
Sx(1, 1)

val =
1
```

```
syms x y
eq1 = x^2 + x*y + y == 3;
eq2 = x^2 - 4*x + 3 == 0;
[Sx, Sy] = solve(eq1, eq2)
```

Sx =
1
3

Sy =
1
-3/2

```
Command Window
New to MATLAB? See resources for Getting

>> Sx(1, 1)

ans =
1

>> Sx(2, 1)

ans =
3
```

	Sx	Sy
	1	2
1	1x1 sym	
2	1x1 sym	

Name	Value	Size	Class
eq1	1x1 sym	1x1	sym
eq2	1x1 sym	1x1	sym
Sx	2x1 sym	2x1	sym
Sy	2x1 sym	2x1	sym
x	1x1 sym	1x1	sym
y	1x1 sym	1x1	sym

Syms-solve



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S x

1x1 struct with 2 fields

Field ^	Value
x	2x1 sym
y	2x1 sym

```
syms x y
eq1 = x^2 + x*y + y == 3;
eq2 = x^2 - 4*x + 3 == 0;
S=solve(eq1,eq2)
```

S =

struct with fields:

x: [2x1 sym]
y: [2x1 sym]

Command Window

New to MATLAB? See resou

```
>> S.x(1,1)
ans =
1
>> S.x(2,1)
ans =
3
```

S x S.x x

S.x	
1	2
1x1 sym	
1x1 sym	

S x

1x1 struct with 2 fields

Field ^	Value
x	2x1 sym
y	2x1 sym

Workspace

Name ^	Value	Size	Class
eq1	1x1 sym	1x1	sym
eq2	1x1 sym	1x1	sym
S	1x1 struct	1x1	struct
x	1x1 sym	1x1	sym
y	1x1 sym	1x1	sym

Syms-solve

$${}^4T_0 = {}^1T_0 \cdot {}^2T_1 \cdot {}^3T_2 \cdot {}^4T_3 = \begin{bmatrix} c_{\theta_1} & -s_{\theta_1} & 0 & k_1 c_{\theta_1} \\ s_{\theta_1} & c_{\theta_1} & 0 & k_1 s_{\theta_1} \\ 0 & 0 & 1 & h \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_{\theta_2} & s_{\theta_2} & 0 & k_2 \cdot c_{\theta_2} \\ s_{\theta_2} & -c_{\theta_2} & 0 & k_2 \cdot s_{\theta_2} \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & k_3 + d_3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_{\theta_4} & -s_{\theta_4} & 0 & 0 \\ s_{\theta_4} & c_{\theta_4} & 0 & 0 \\ 0 & 0 & 1 & e \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

```
code
clc;clear;format bank
syms t01(theta1,k1,h)
syms t12(theta2,k2)
syms t23(k3,d3)
syms t34(theta4,e)

t01(theta1,k1,h)=[cos(theta1),-sin(theta1),0,k1*cos(theta1); sin(theta1),cos(theta1),0,k1*sin(theta1); 0,0,1,h;0,0,0,1];

t12(theta2,k2)=[cos(theta2) sin(theta2) 0 k2*cos(theta2);sin(theta2) -cos(theta2) 0 k2*sin(theta2);0 0 -1 0;0 0 0 1];

t23(k3,d3)=[1 0 0 0;0 1 0 0; 0 0 1 k3+d3;0 0 0 1];

t34(theta4,e)=[cos(theta4) -sin(theta4) 0 0;sin(theta4) cos(theta4) 0 0; 0 0 1 e;0 0 0 1];
```

```
t04=simplify(t01(theta1,k1,h)*t12(theta2,k2)*t23(k3,d3)*t34(theta4,e));
```

الاختصار

النتيجة النهائية بعد الاختصار

```
t04 =
[ cos(theta1 + theta2 - theta4), sin(theta1 + theta2 - theta4), 0, k2*cos(theta1 + theta2) + k1*cos(theta1)]
[ sin(theta1 + theta2 - theta4), -cos(theta1 + theta2 - theta4), 0, k2*sin(theta1 + theta2) + k1*sin(theta1)]
[ 0, 0, 0, -1, h - e - d3 - k3]
[ 0, 0, 0, 0, 1]
```

```
th1=0.00;th2=0.00;di3=0.00;th4=0.00;
h=47; k1=50; k2=50; k3=50; e=10;
t040=double(t01(th1,k1,h)*t12(th2,k2)*t23(k3,di3)*t34(th4,e))
```

```
t040 =
    1.00         0         0    100.00
         0    -1.00         0         0
         0         0    -1.00    -13.00
         0         0         0         1.00
```

diff - dsolve



Solve the equation: $dy/dt=ay$

Solve the equation: $dx/dt=-ax$

```
syms a y(t)
eqn = diff(y,t) == a*y
dsolve(eqn)
```

```
eqn(t) =
diff(y(t), t) == a*y(t)
```

```
ans =
C5*exp(a*t)
```

```
syms x(t) a
eq= diff(x) == -a*x
dsolve(eq)
```

```
eq(t) =
diff(x(t), t) == -a*x(t)
```

```
ans =
C4*exp(-a*t)
```

Name ^	Value	Size	Class
a	1x1 sym	1x1	sym
ans	1x1 sym	1x1	sym
eq	1x1 symfun	1x1	symfun
eqn	1x1 symfun	1x1	symfun
t	1x1 sym	1x1	sym
x	1x1 symfun	1x1	symfun
y	1x1 symfun	1x1	symfun

diff - dsolve



Solve the equation
 $d^2y/dt^2=ay$.

```
syms y(t) a
eqn = diff(y,t,2) == a*y;
ySol(t) = dsolve(eqn)
```

$ySol(t) =$

$$C6*\exp(-a^{1/2}*t) + C7*\exp(a^{1/2}*t)$$

Specify the second-order derivative of a function y by using $\text{diff}(y,t,2)$ or $\text{diff}(y,t,t)$. Similarly, specify the n -th order derivative by using $\text{diff}(y,t,n)$.

Solve Differential Equation with Condition

Solve the equation $dy/dt=ay$ with the condition $y(0)=5$.

```
syms y(t) a
eqn = diff(y,t) == a*y;
cond = y(0) == 5;
ySol(t) = dsolve(eqn,cond)
```

ySol(t) =

$5*\exp(a*t)$

Solve the equation $d^2y/dt^2 = (a^2)y$ with two conditions, $y(0)=b$ and $y'(0)=1$.

```
syms y(t) a b
eqn = diff(y,t,2) == a^2*y;
Dy = diff(y,t);
cond = [y(0)==b, Dy(0)==1];
ySol(t) = dsolve(eqn,cond)
```

$ySol(t) =$
 $(\exp(a*t)*(a*b + 1))/(2*a) + (\exp(-a*t)*(a*b - 1))/(2*a)$

Solve the equation

$d^2y/dt^2 = (a^2) y$ with two conditions, $y(0)=b$ and $y'(0)=1$.
 $b=0, a=2$

```
syms y(t)
eqn = diff(y,t,2) == 2^2*y;
Dy = diff(y,t);
cond = [y(0)==0, Dy(0)==1];
ySol(t) = dsolve(eqn,cond)
```

$ySol(t) =$
 $\exp(2*t)/4 - \exp(-2*t)/4$

$ySol(t) =$
 $(\exp(a*t)*(a*b + 1))/(2*a) + (\exp(-a*t)*(a*b - 1))/(2*a)$

Solve System of Differential Equations



$$\frac{dy}{dt} = z$$

$$\frac{dz}{dt} = -y.$$

```
syms y(t) z(t)
eqns = [diff(y,t) == z, diff(z,t) == -y];
sol = dsolve(eqns)
soly(t) = sol.y
solz(t) = sol.z
```

Name	Value	Size	Class
eqns	1x1 symfun	1x1	symfun
sol	1x1 struct	1x1	struct
soly	1x1 symfun	1x1	symfun
solz	1x1 symfun	1x1	symfun
t	1x1 sym	1x1	sym
y	1x1 symfun	1x1	symfun
z	1x1 symfun	1x1	symfun

```
sol =
  struct with fields:
    z: [1x1 sym]
    y: [1x1 sym]
```

```
soly(t) =
  C14*cos(t) + C13*sin(t)
```

```
solz(t) =
  C13*cos(t) - C14*sin(t)
```

```
soly(0)
ans =
  C14
```

```
>> solz(0)
ans =
  C13
```

Solve the initial value problem

$$y'(x) = xy; \quad y(1) = 1.$$

```
eqn1 = 'Dy = y*x'  
inits = 'y(1)=1';  
y = dsolve(eqn1, 'y(1)=1', 'x')  
%or  
y = dsolve(eqn1, inits, 'x')
```

```
eqn1 =  
'Dy = y*x'
```

```
y =  
exp(-1/2)*exp(x^2/2)
```

```
y =  
exp(-1/2)*exp(x^2/2)
```

Solve the second order differential equation

$$y''(x) + 8y'(x) + 2y(x) = \cos(x);$$

$$y(0) = 0, y'(0) = 1$$

```
clear
clc
eqn2 = 'D2y + 8*Dy + 2*y = cos(x) '
inits2 = 'y(0)=0, Dy(0)=1'
y=dsolve(eqn2,inits2,'x')
```

```
eqn2 =
'D2y + 8*Dy + 2*y = cos(x)'
```

```
inits2 =
'y(0)=0, Dy(0)=1'
```

```
y =
(14^(1/2)*exp(x*(14^(1/2) - 4))*(7*14^(1/2) -
27))/(28*(8*14^(1/2) - 31)) - (14^(1/2)*exp(4*x +
14^(1/2)*x)*exp(-x*(14^(1/2) + 4))*(sin(x) + cos(x)*(14^(1/2) +
4)))/(28*((14^(1/2) + 4)^2 + 1)) + (14^(1/2)*exp(4*x -
14^(1/2)*x)*exp(x*(14^(1/2) - 4))*(sin(x) - cos(x)*(14^(1/2) -
4)))/(28*((14^(1/2) - 4)^2 + 1)) + (14^(1/2)*exp(-x*(14^(1/2) +
4))*(393*14^(1/2) - 1531))/(28*(8*14^(1/2) -
31)^2*(8*14^(1/2) + 31))
```

Thanks .

