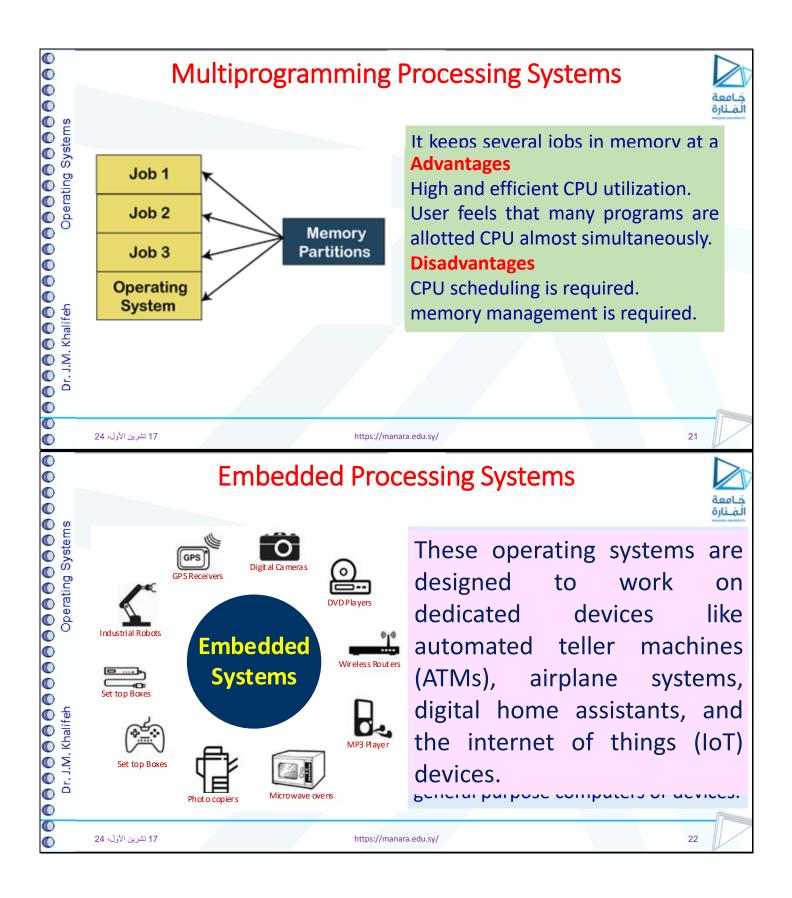


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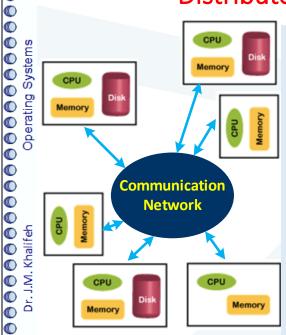
Distributed Processing Systems



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Features of Distributed Operating System

Resource Sharing: The data is shared for the exchange of information, whereas the hardware resources are shared for convenience and reduction in cost.

Concurrency: different tasks are handled by different concurrently interacting machines or computers.

Scalability: new computers or units can be added to the feature if needed.

Security: must Ensures transparency and security between users.

Heterogeneity: several programming languages, operating systems , software, hardware, networks implemented by different developers.

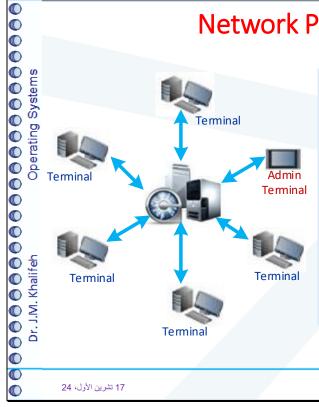
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Network Processing Systems

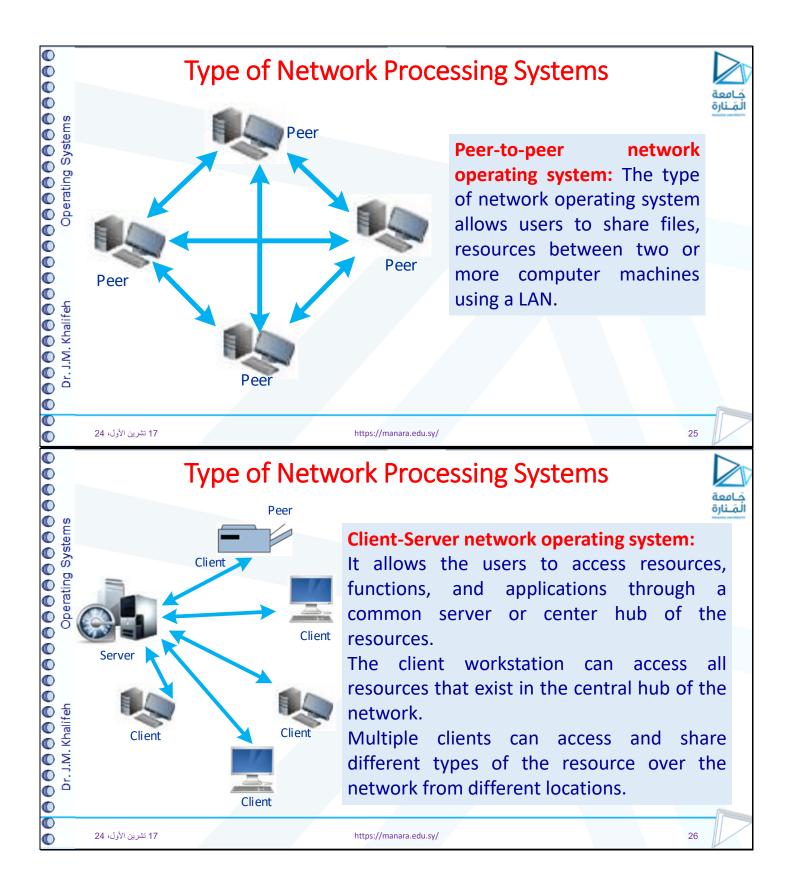


It operates on terminals using network devices like a switch, router, or firewall to handle data, applications and other network resources.

It provides connectivity among the autonomous operating system.

It is also useful to share data, files, hardware devices and printer resources among multiple computers to communicate with each other.

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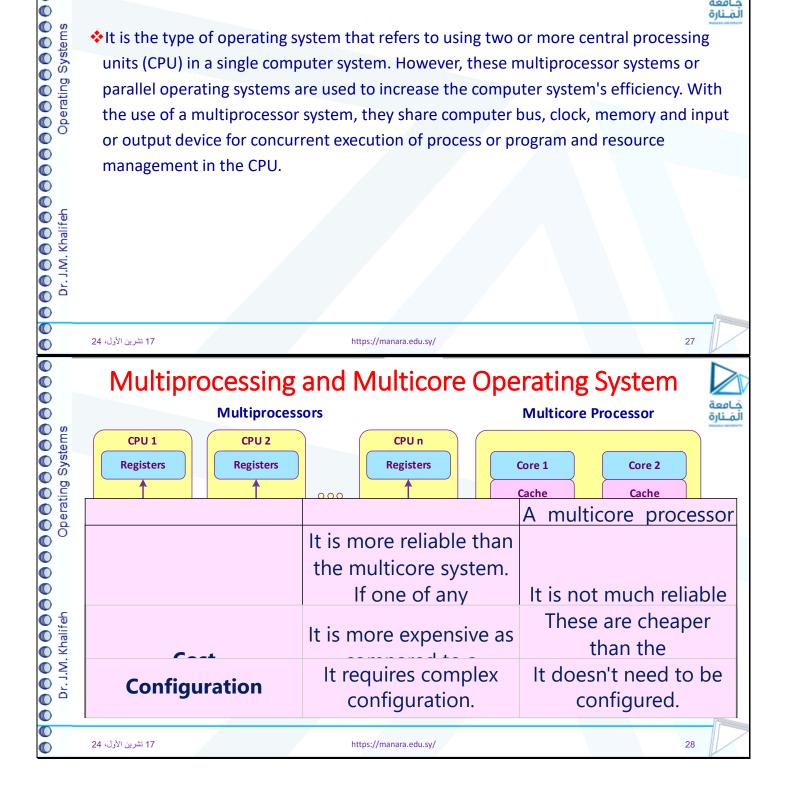


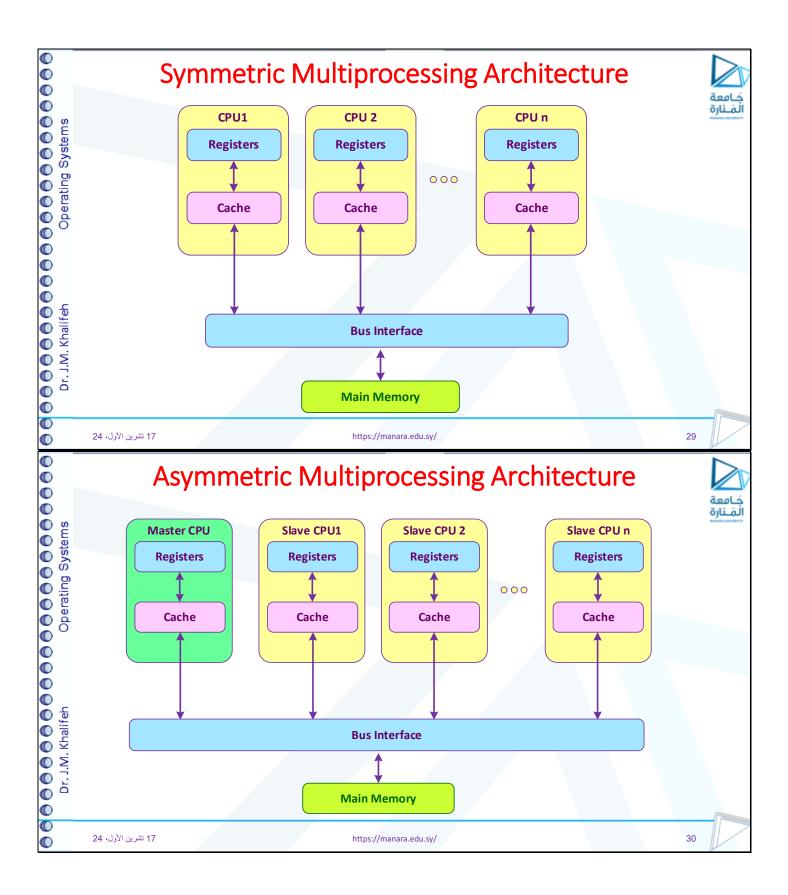
Multiprocessing Operating System

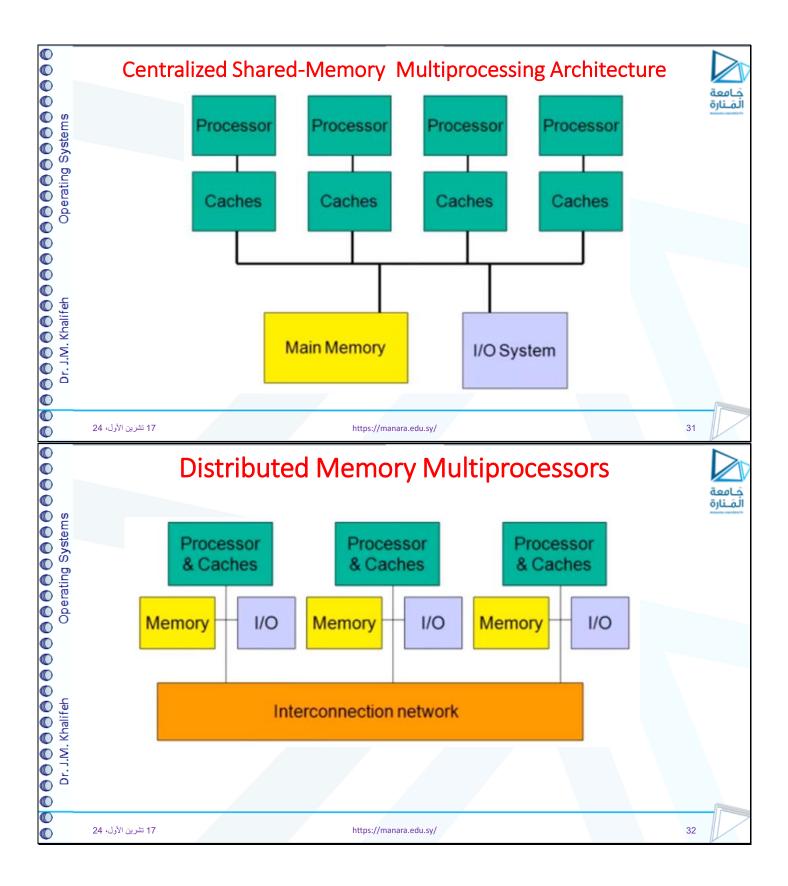
Operating Systems



It is the type of operating system that refers to using two or more central processing units (CPU) in a single computer system. However, these multiprocessor systems or parallel operating systems are used to increase the computer system's efficiency. With the use of a multiprocessor system, they share computer bus, clock, memory and input or output device for concurrent execution of process or program and resource management in the CPU.







Real-Time Operating System

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Operating Systems

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A real-time operating system is an important type of operating system used to provide services and data processing resources for applications in which the time interval required to process & respond to input/output should be so small without any delay real-time system. For example, reallife situations governing an automatic car, traffic signal, nuclear reactor or an aircraft require an immediate response to complete tasks within a specified time delay. Hence, a real-time operating system must be fast and responsive for an embedded system, weapon system, robots, scientific research & experiments and various real-time objects.

Hard Real-Time System

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These types of OS are used with those required to complete critical tasks within the defined time limit. If the response time is high, it is not accepted by the system or may face serious issues like a system failure. In a hard realtime system, the secondary storage is either limited or missing, so these system stored data in the ROM.

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Soft Real-Time System



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A soft real-time system is a less restrictive system that can accept software and hardware resources delays by the operating system. In a soft real-time system, a critical task prioritizes less important tasks, and that priority retains active until completion of the task. Also, a time limit is set for a specific job, which enables short time delays for further tasks that are acceptable. For example, computer audio or video, virtual reality, reservation system, projects like undersea, etc.

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Operating Systems

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