

# Control Systems

## Lecture /1/

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# Objectives



- ❑ In this lecture, we lead you through a study of the basics of control systems.
- ❑ After completing the chapter, you should be able to
  - Understand the principles and purpose of control engineering
  - Examine examples of control systems

# What is “Control”?



- Make some object (called system, or plant) behave as we desire.
- Imagine “control” around you!
  - Room temperature control
  - Car driving
  - Voice volume control
  - Balance of bank account
  - Epidemics control
  - “Control” (move) the position of the PC mouse pointer
  - etc.

# What is “Automatic Control”?



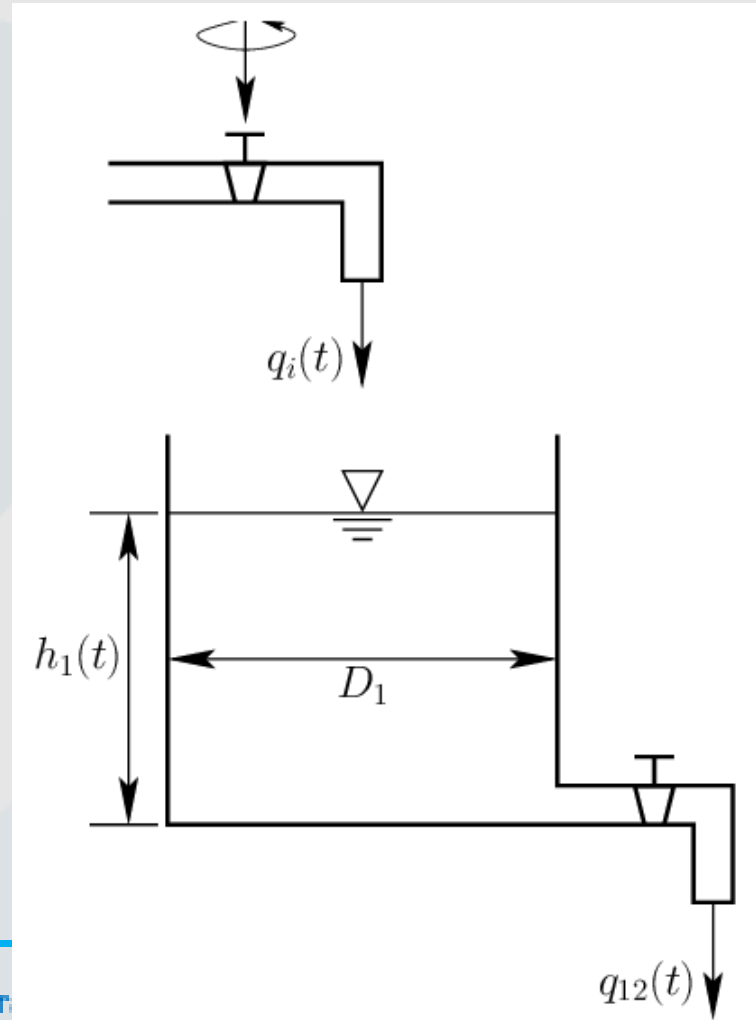
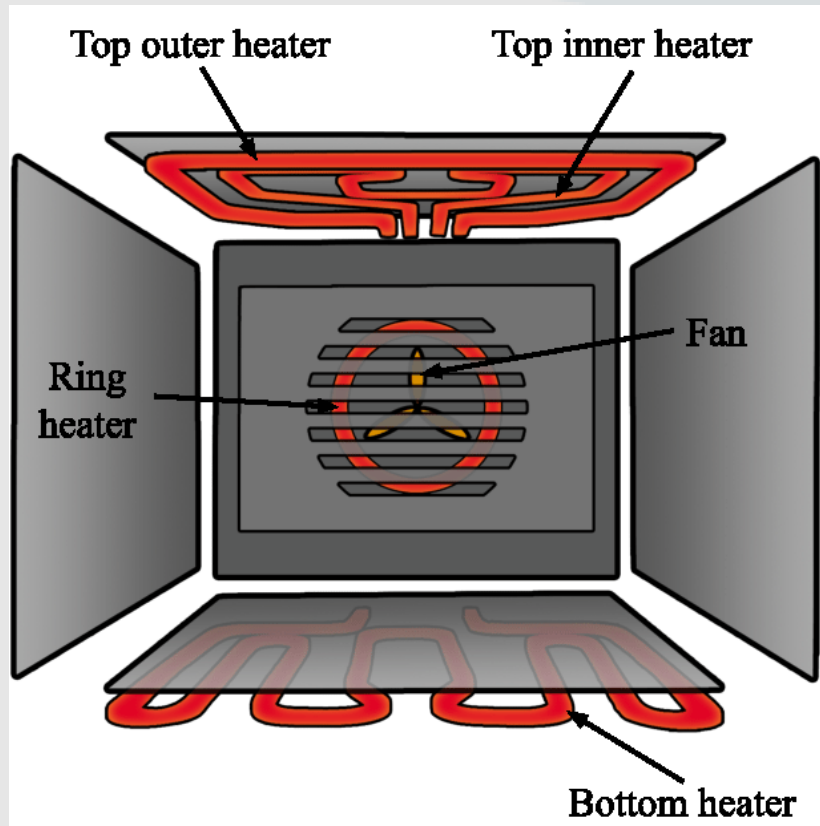
- ❑ Not manual!
- ❑ Why do we need automatic control?
  - Convenient (room temperature, laundry machine)
  - Dangerous (hot/cold places, space)
  - Impossible for human (nanometer scale precision positioning, work inside the small space that human cannot enter like ICs manufacturing process).
  - It exists in nature (human body temperature control)
  - High efficiency (engine control)
- ❑ Many examples of automatic control around us
- ❑ Applications:
  - Robotic systems, Medical tools, Aircraft, Industrial processes, Automobiles.

# Definitions.



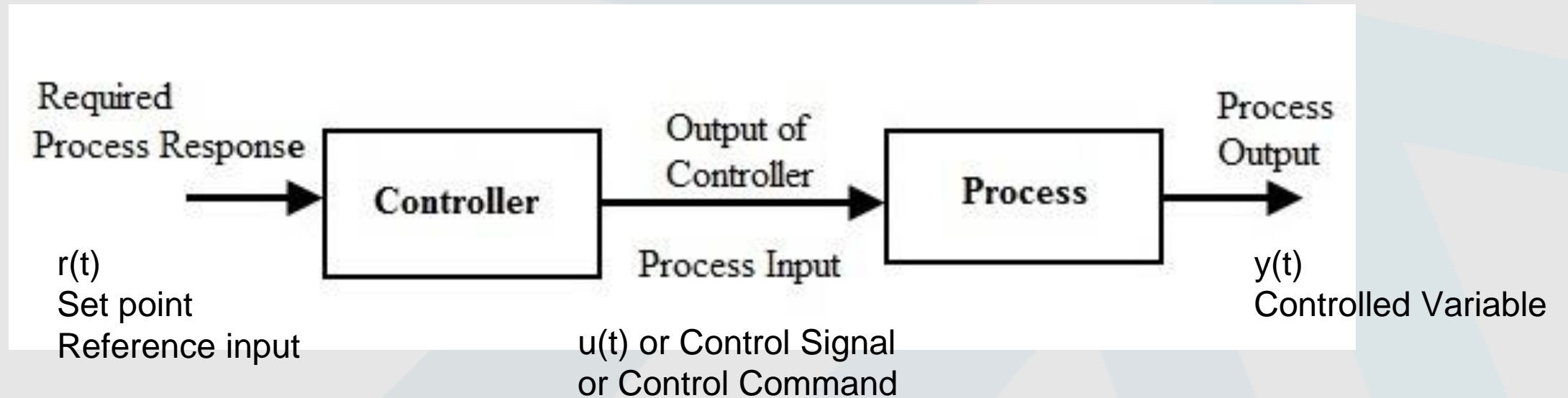
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- ❑ **System** - A system is a combination of components (Hardware/Software) that act together and perform a certain objective.



# Definitions.

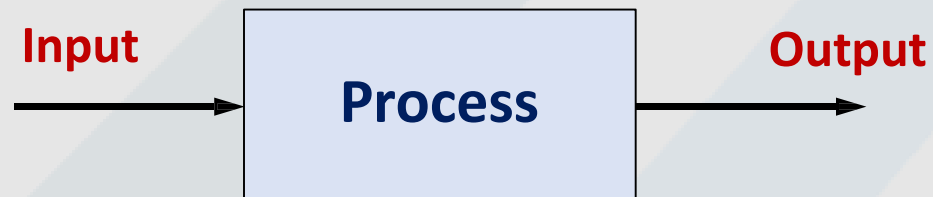
- **Control System** - An interconnection of components forming a system configuration that will provide a desired response.



# Definitions.



- **Plant/Process** - A plant may be a piece of equipment, perhaps just a set of machine parts functioning together, or the device, or system under control. The input and output relationship represents the cause-and-effect relationship of the process.



# Definitions.



- ❑ **Disturbance** - A disturbance is a signal that tends to adversely affect the value of the output of a system. If a disturbance is generated within the system, it is called internal, while an external disturbance is generated outside the system and it is treated as an input.
- ❑ **Controlled Variable** - is the quantity or condition that is measured and controlled. the controlled variable is the output of the system.
- ❑ **Actuator** – Final control element that receives the control signal  $u(t)$  and gives an output (manipulated variable) to the process's input.
- ❑ **The Manipulated Variable** - is the quantity or condition that is varied by the Actuator so as to affect the value of the controlled variable.



# Definitions.



- ❑ **Control** - means measuring the value of the output variable of the system and applying the manipulated variable to the system to correct or limit deviation of the measured value from a desired value.
- ❑ **Feedback Control** - Feedback control refers to an operation that tends to reduce the difference between the output of a system and some reference input, and that does so on the basis of this difference.
- ❑ **Transducer** - a device used to measure the magnitude of the controlled variable  $y(t)$ .
- ❑ **Error signal  $e(t)$**  - Difference between set point and measured controlled variable.

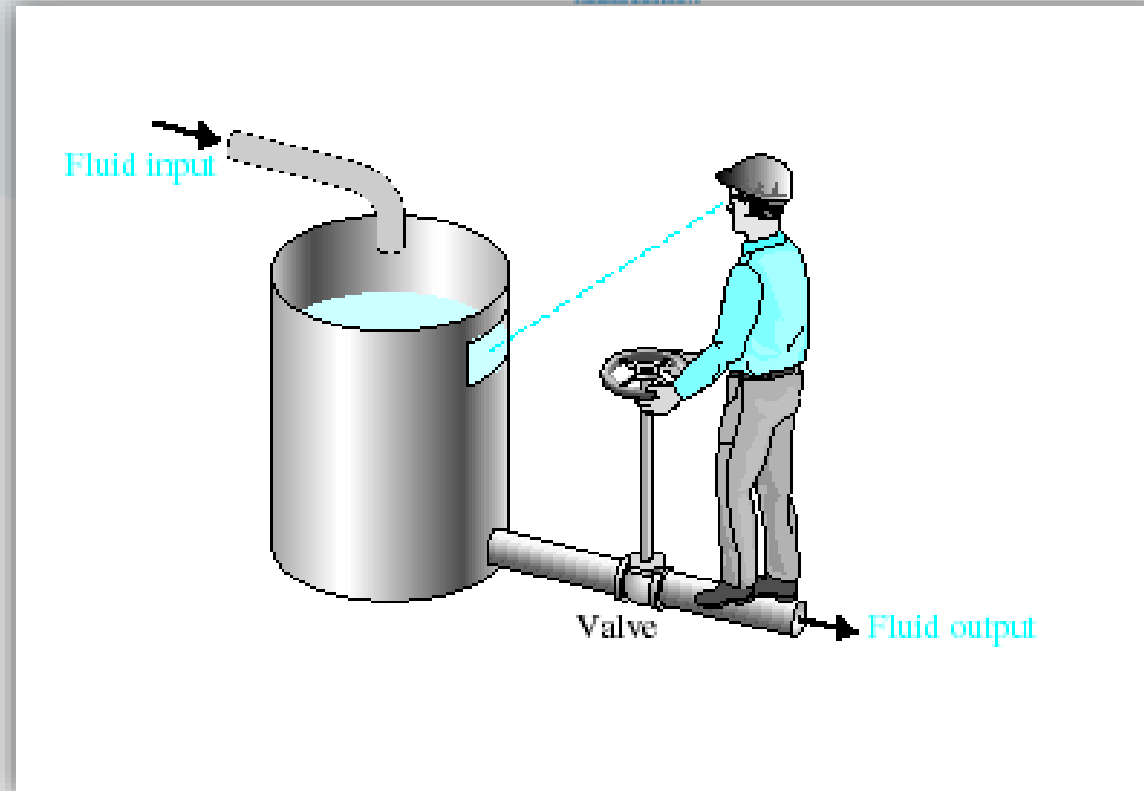
# Classification of control systems:



## Depending on the control strategy

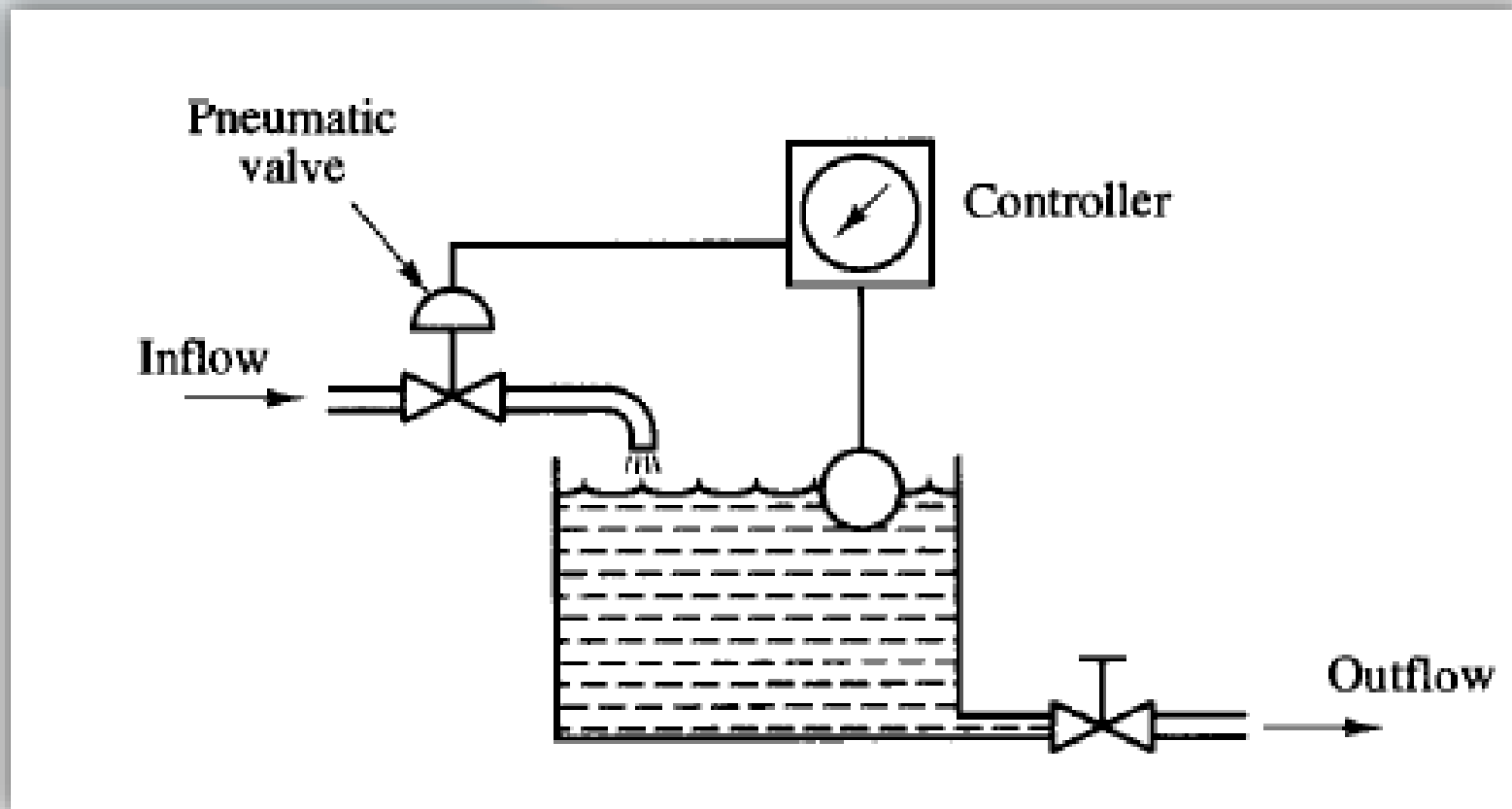
1. Manual v/s automatic
2. Open loop v/s closed loop

# Manual Liquid-level control system

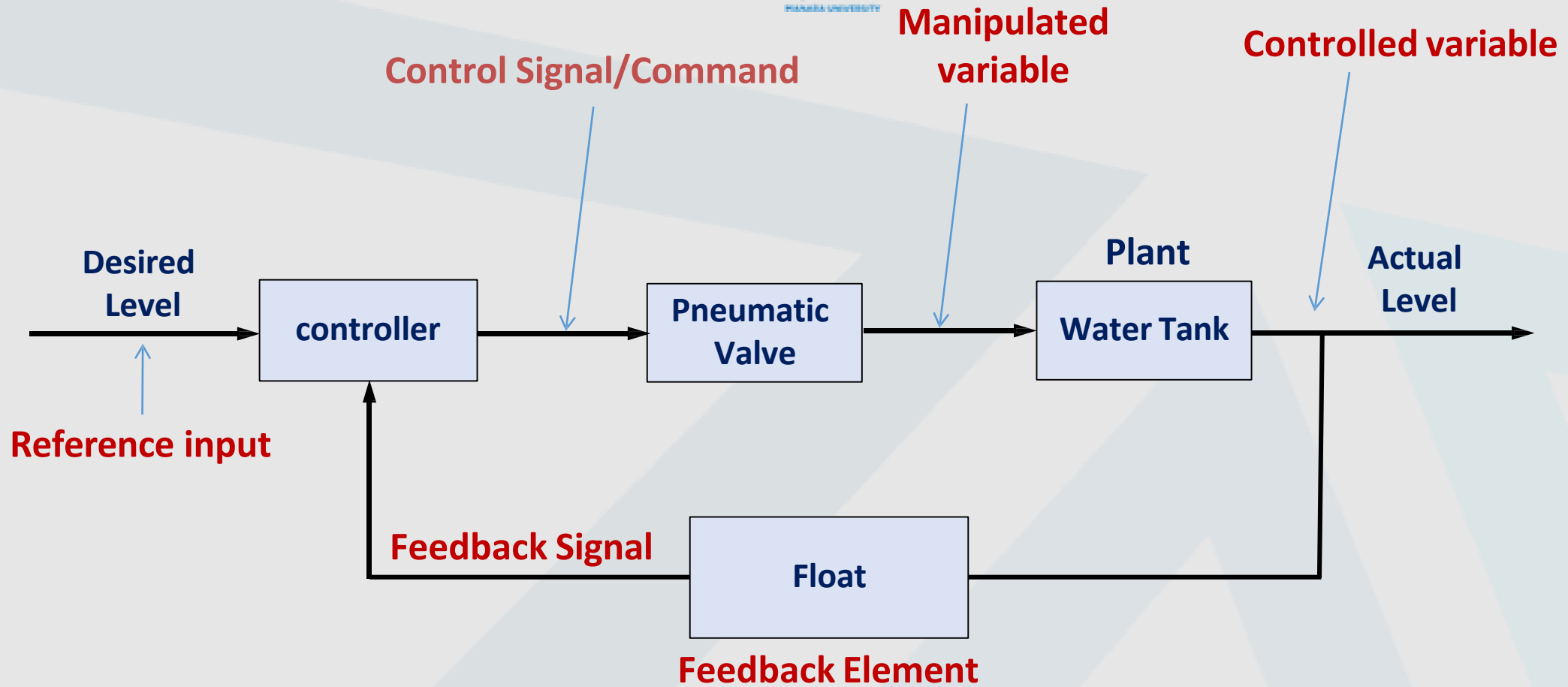


A manual Control System for regulating the level of fluid in a tank by adjusting the output valve. The operator views the level of fluid through a port in the side of the tank.

# Automatic Liquid-level control system



# Automatic Liquid-level control system

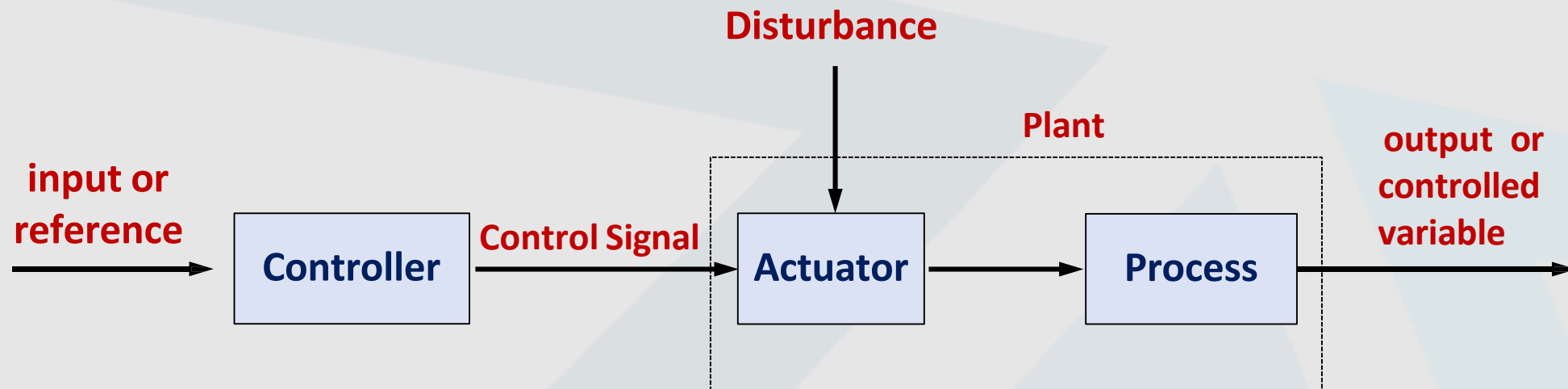


# Open-loop control systems



- ❑ Those systems in which the output has no effect on the control action are called open-loop control systems.
- ❑ In other words, in an open-loop control system the output is neither measured nor fed back for comparison with the input.
- ❑ In the presence of disturbances, an open-loop control system will not perform the desired task.
- ❑ Open-loop control can be used, in practice, only if the relationship between the input and output is known and if there are neither internal nor external disturbances.

# Open-loop control systems



An open-loop system

# Examples:



TV Remote Control.  
Electric Hand Drier.

Timer Based Systems:

Traffic lights  
Automatic Water Faucet.  
Washing machine.  
Electric Bulb.



# Example: laundry machine



- ❑ A laundry machine washes clothes, by setting a program.
- ❑ A laundry machine does not measure how clean the clothes become.
- ❑ Control without measuring devices (sensors) are called ***open-loop control***.



# Open-loop control systems



## Advantages:

- ❑ Simple construction, ease of maintenance, and less expensive.
- ❑ There is no stability concern.
- ❑ Convenient when output is hard to measure or measuring the output precisely is economically not feasible. (For example, in the washer system, it would be quite expensive to provide a device to measure the quality of the washer's output, cleanliness of the clothes).

## Disadvantages:

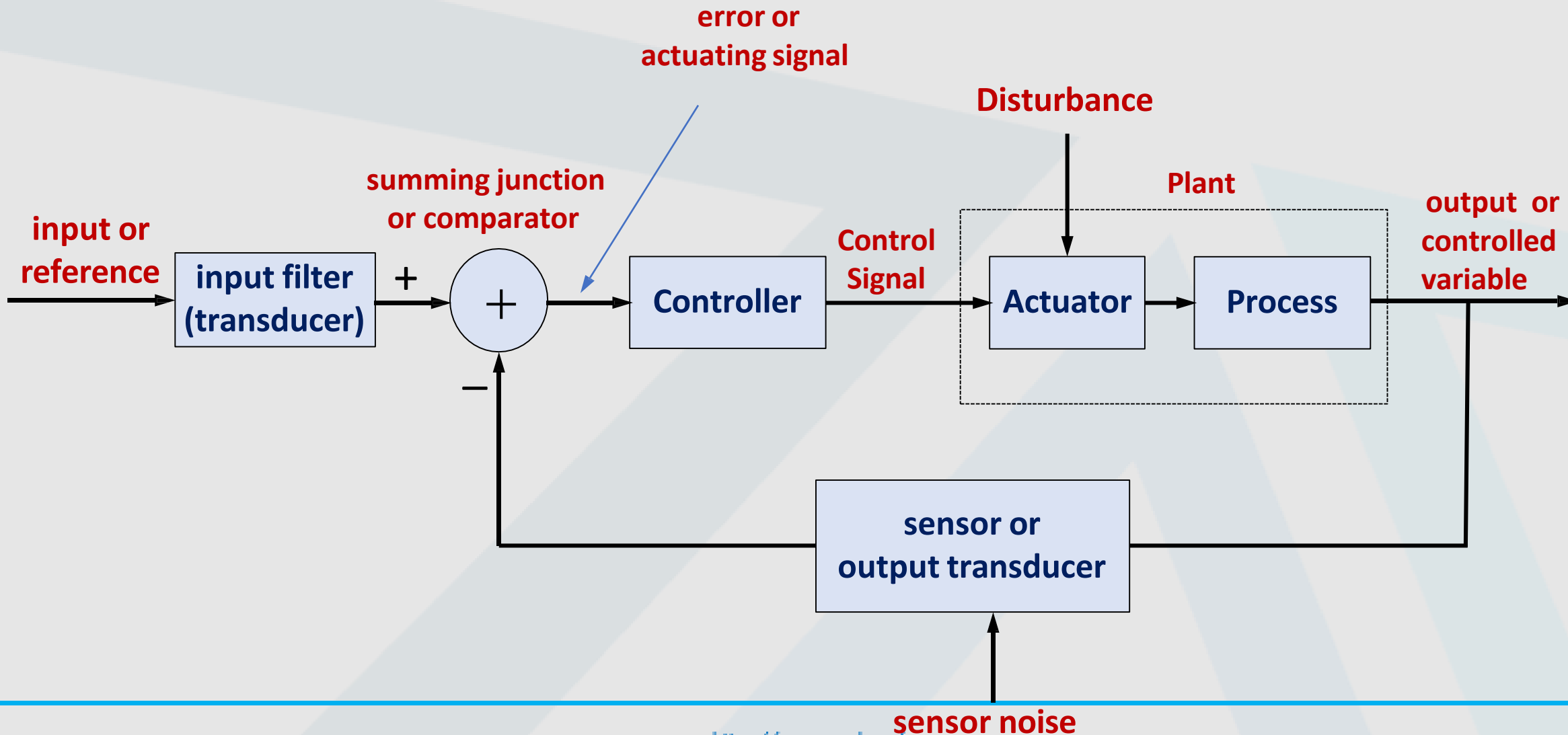
- ❑ Disturbances cause errors, and the output may be different from what is desired.
- ❑ Recalibration is necessary from time to time.

# Closed-loop control systems

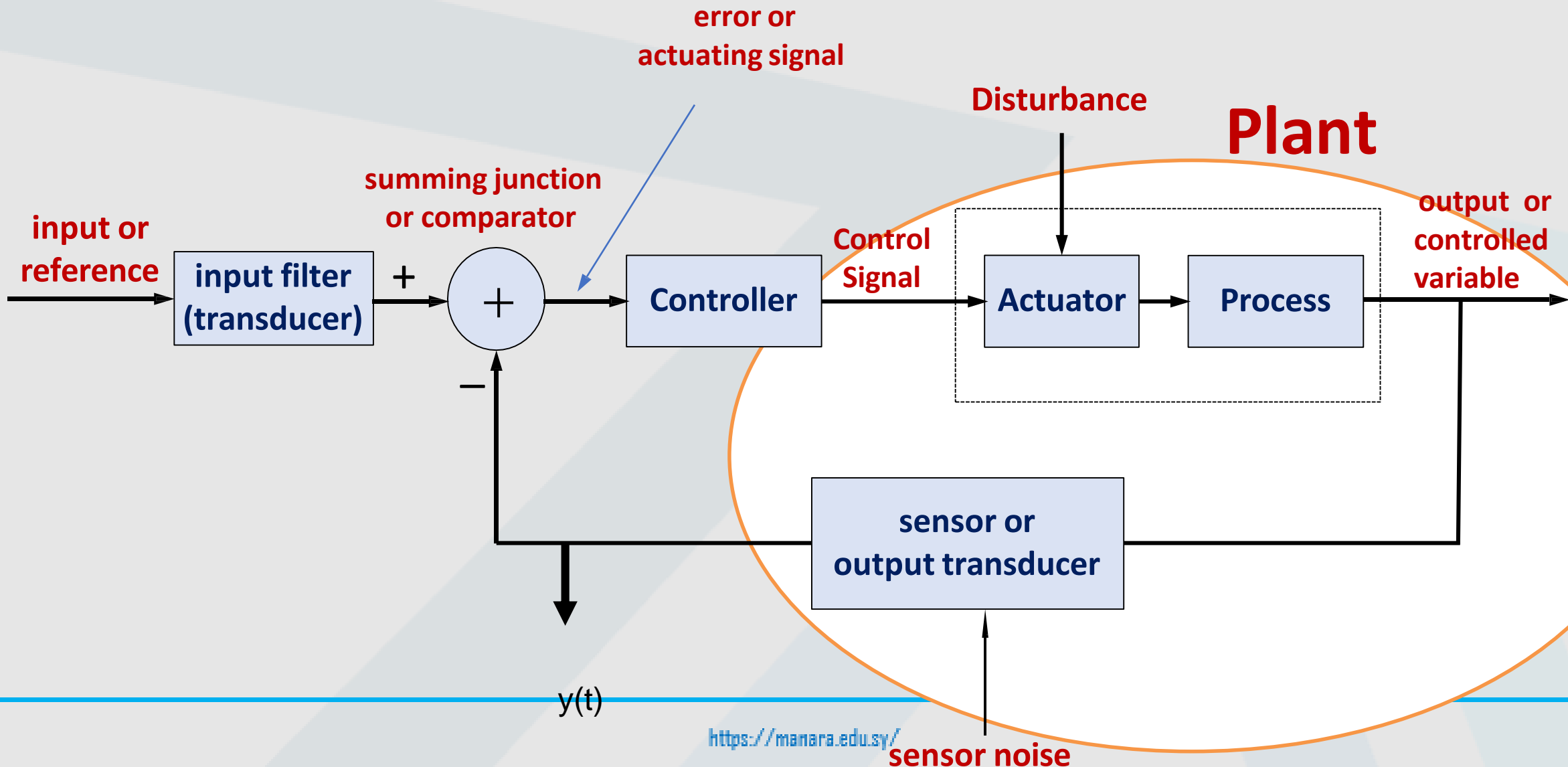


- ❑ Feedback control systems are often referred to as closed-loop control systems.
- ❑ In practice, the terms feedback control and closed-loop control are used interchangeably.
- ❑ In a closed-loop control system the actuating error signal, which is the difference between the input signal and the feedback signal, is fed to the controller so as to reduce the error and bring the output of the system to a desired value.

# Closed-loop (feedback) control



# Closed-loop (feedback) control [Real life]



# Examples:



Thermostat Heater

Sun seeker solar system

Auto Engine

Robots/Quadcopter balance system

Automatic Clothes Iron

A human traveling on the road

Automatic voltage regulator (within generators)

Dental chair compressor

# Closed-loop control systems



## Advantages:

- ❑ High accuracy
- ❑ Not sensitive to disturbance (less than open loop)
- ❑ Controllable transient response
- ❑ Controllable steady state error

## Disadvantages:

- ❑ More Complex, and More Expensive.
- ❑ Possibility of instability.
- ❑ Need for output measurement.
- ❑ Recalibration is necessary from time to time.

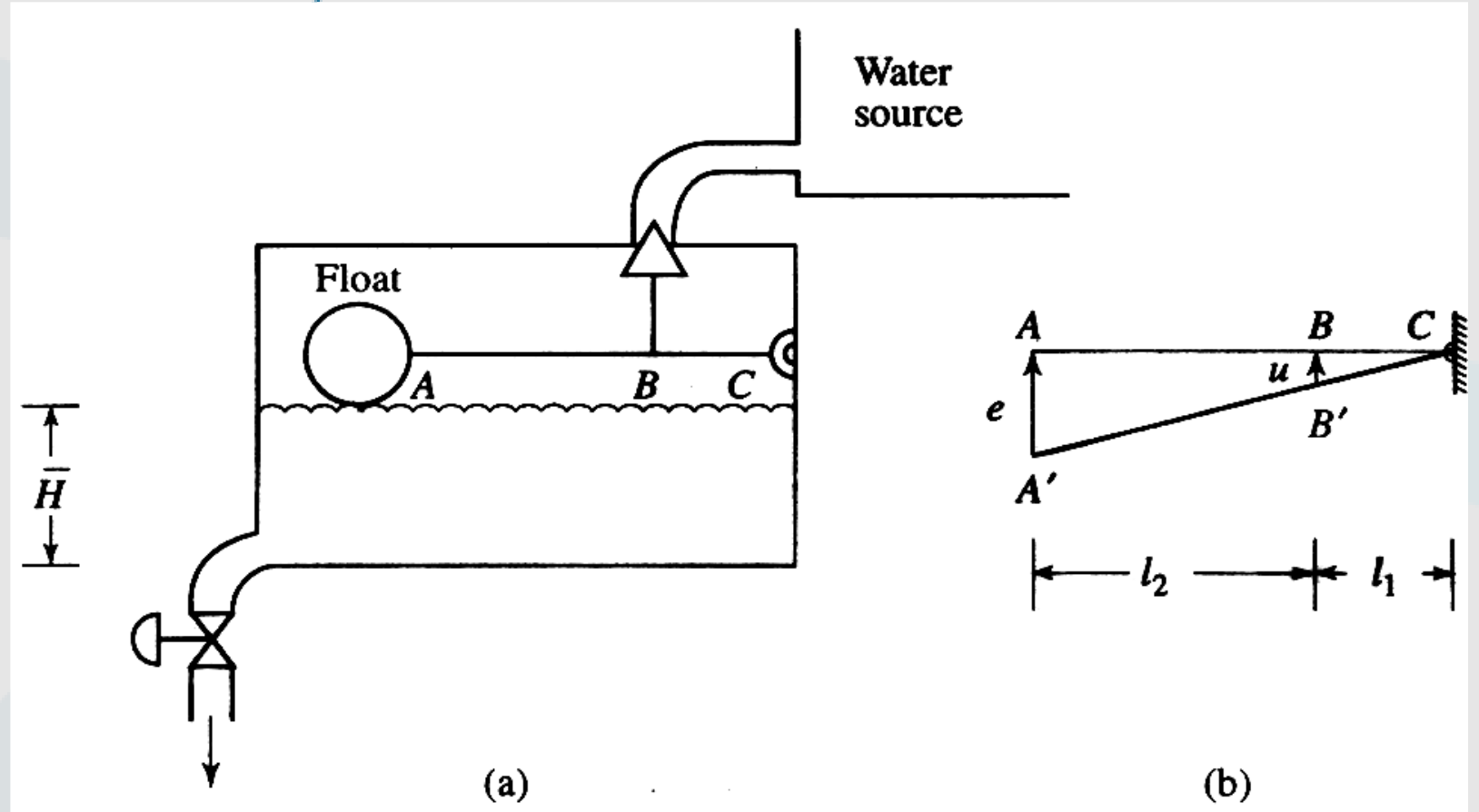
# Example1: Water tank level control

e: actuating error  
u: control signal

$$\frac{AA'}{AC} = \frac{AA'}{AB + BC} = \frac{BB'}{BC}$$

$$\frac{e}{l_1 + l_2} = \frac{u}{l_1}$$

$$u = \frac{l_1}{l_1 + l_2} e$$

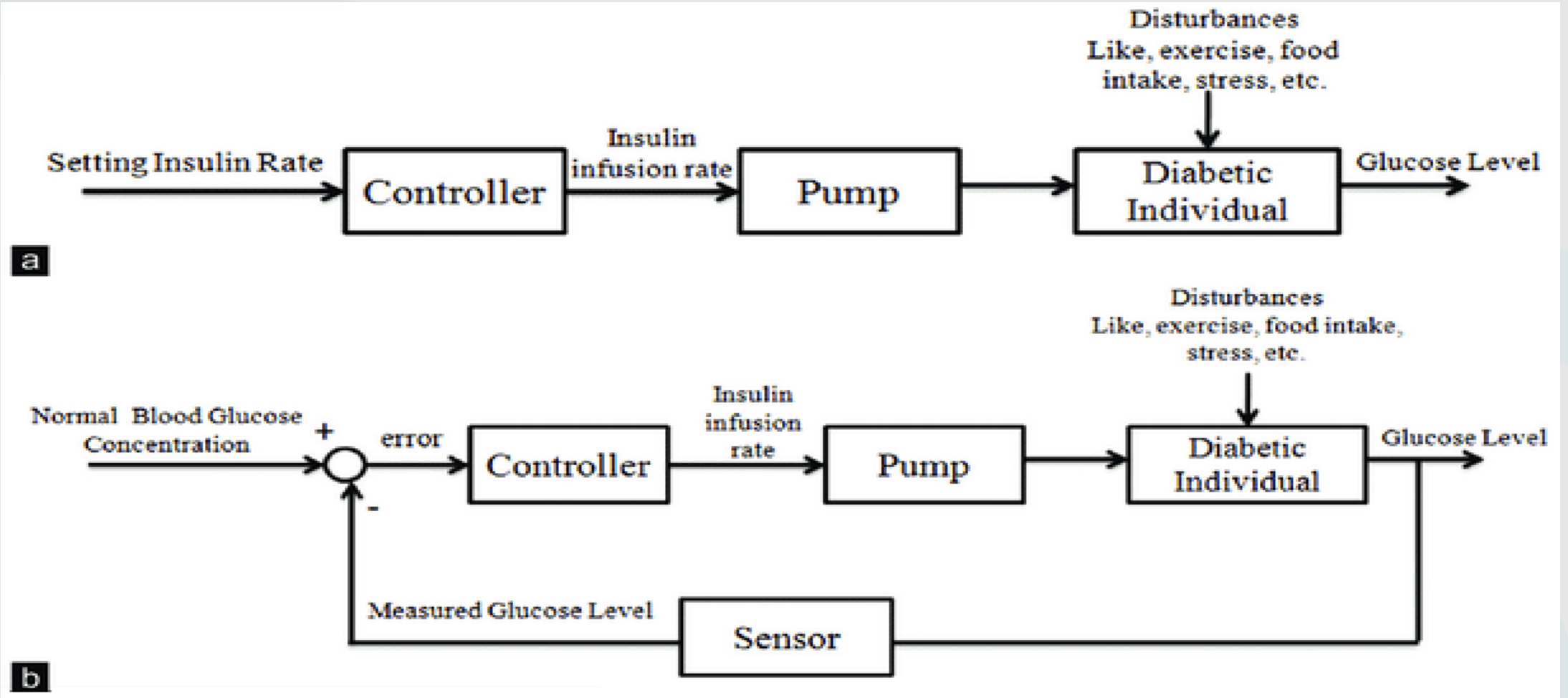


Water tank level control system



# Example2:

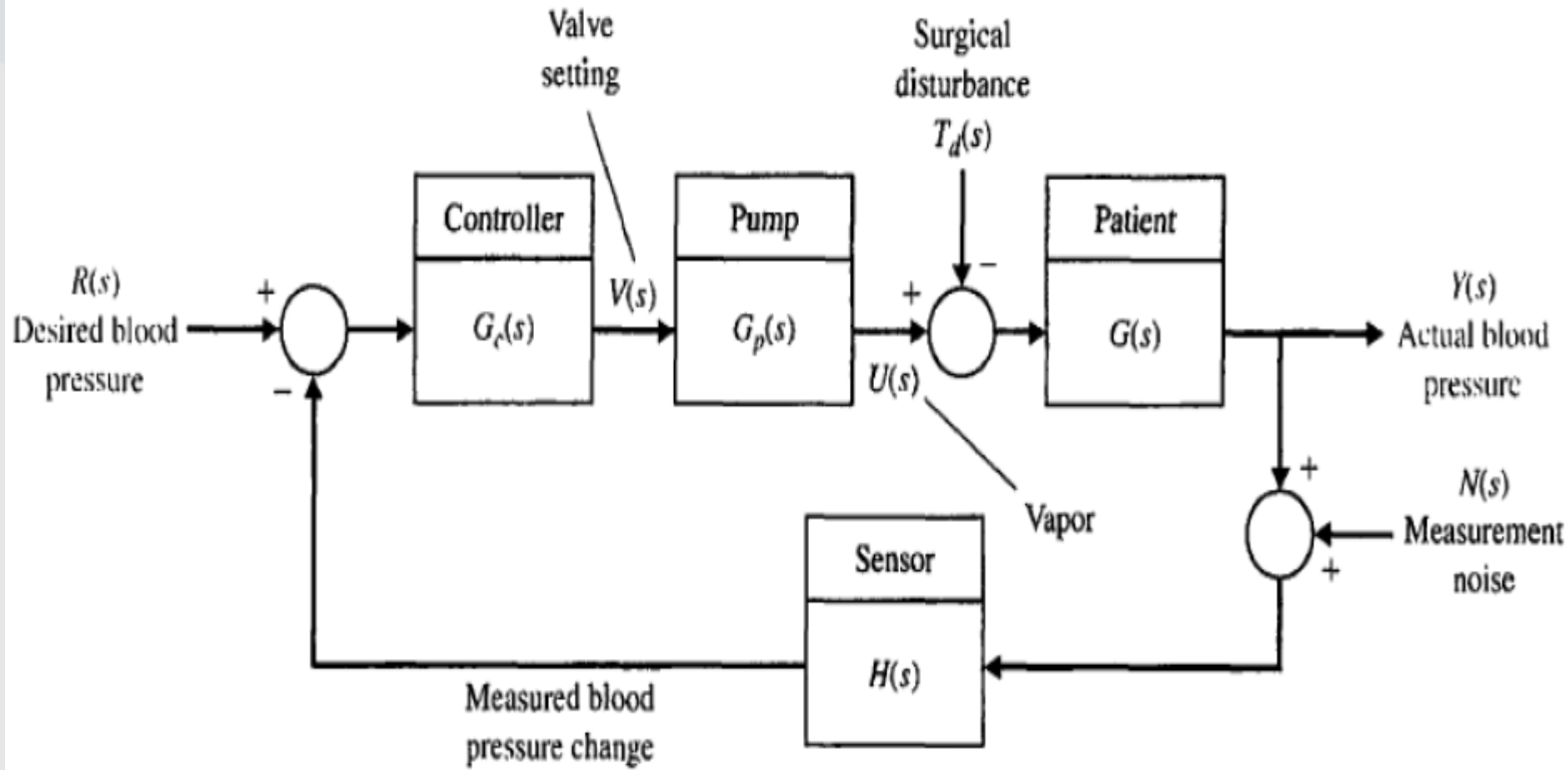
## Blood Glucose Control in Diabetes Patients



Insulin Pump Control System (Open Loop VS. Closed Loop)

# Example3:

## Mean arterial pressure (MAP)

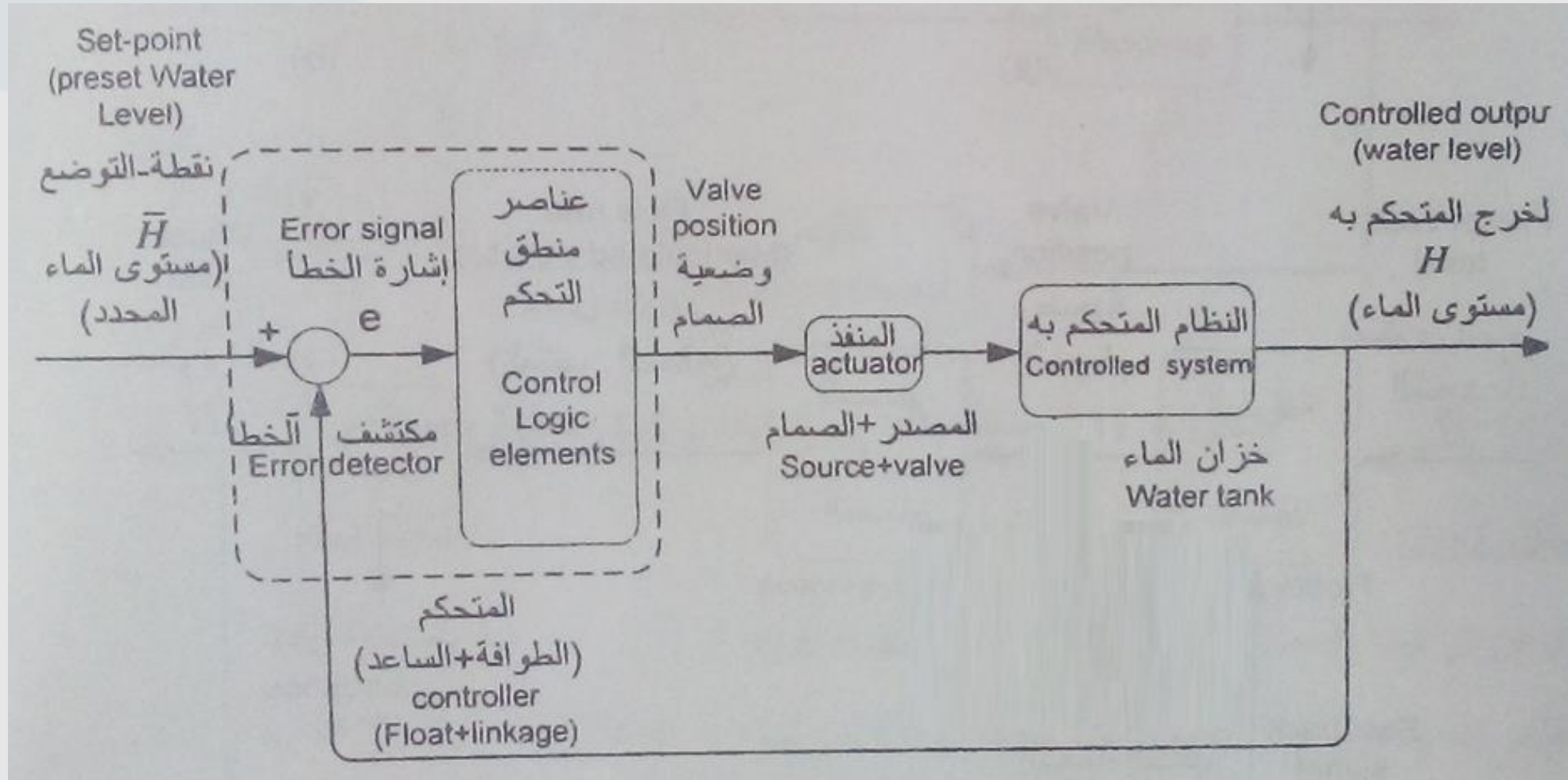


How do you manage mean arterial pressure? This is usually done with:

1- Intravenous fluids or blood transfusions to increase blood flow.

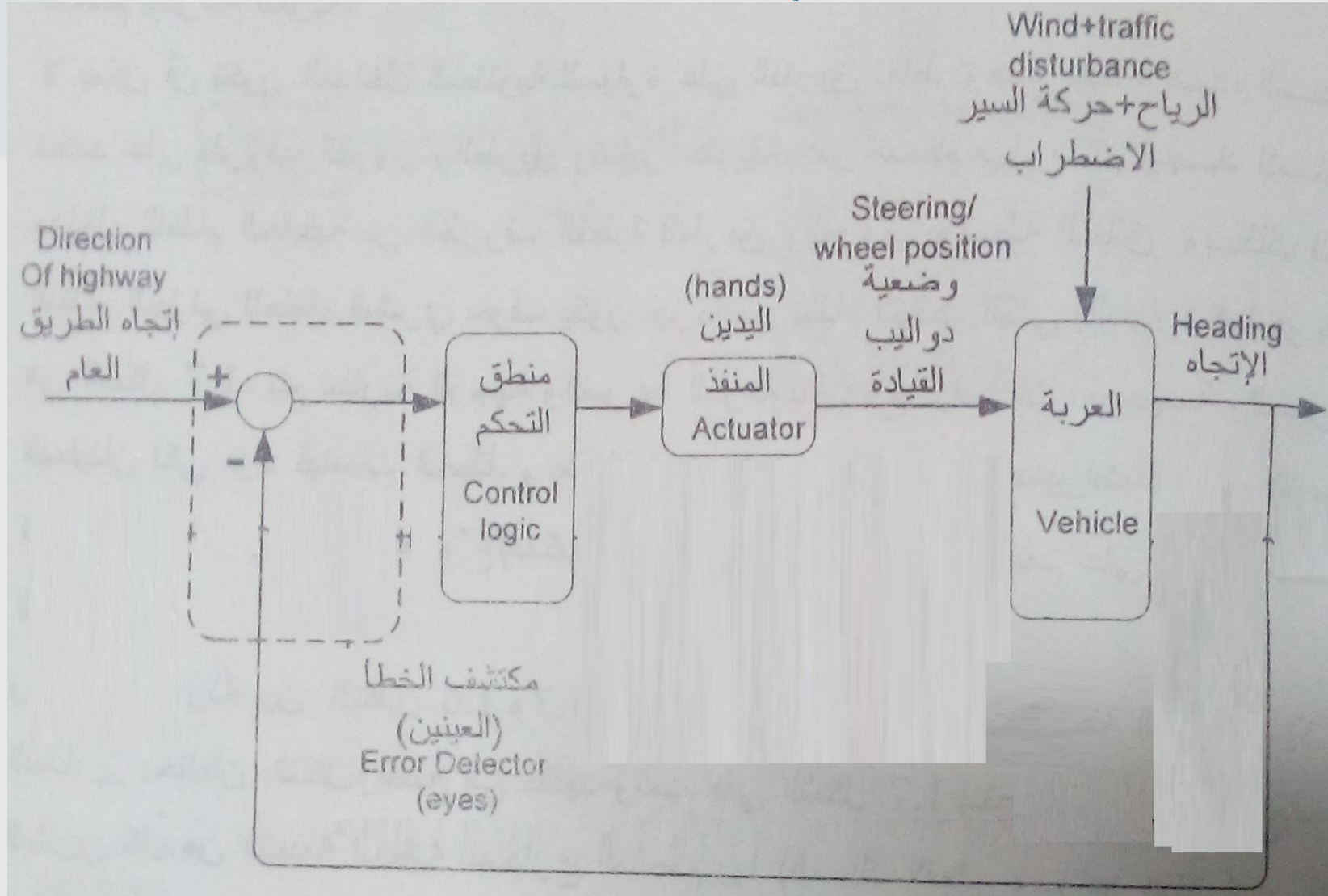
2- medications called “vasopressors” that tighten blood vessels, which can increase blood pressure and make the heart beat faster or pump harder.

# Example4: Water tank level control



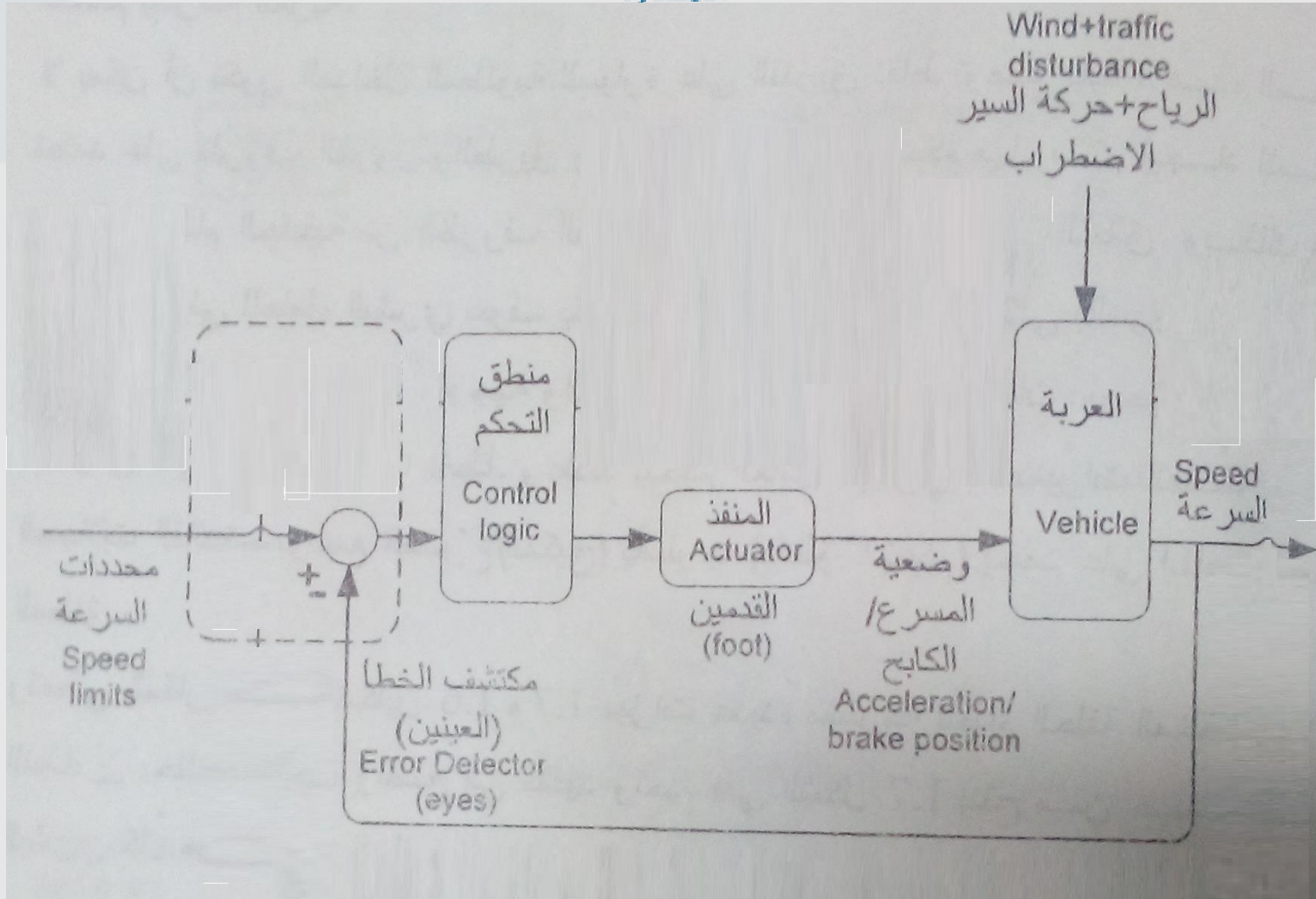
Water tank level control system

# Example 5: Car control system (Direction)



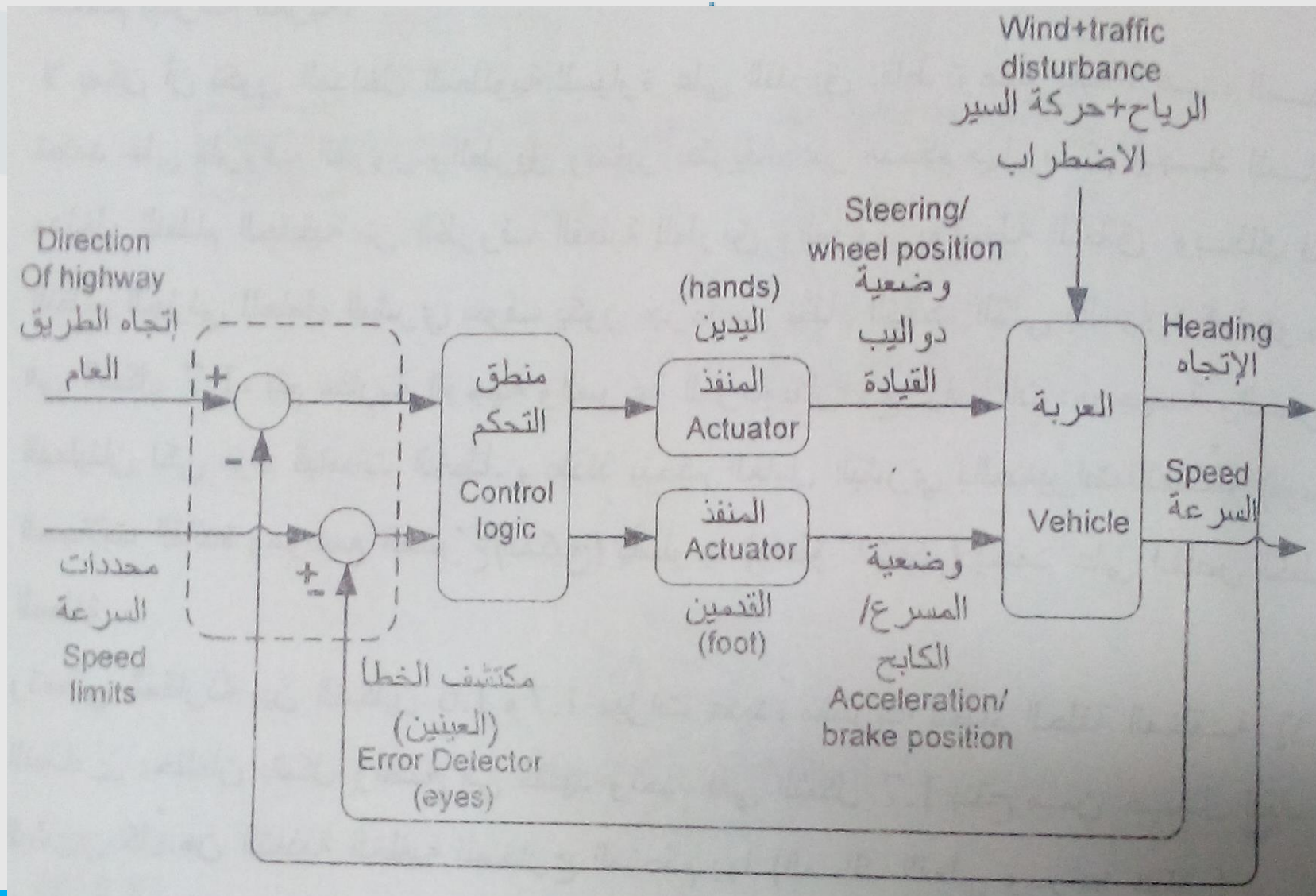
Car control system (Direction)

# Example6: Car control system (Speed)



Car control system (Speed)

# Example 7: Car control system (Direction + Speed)



Car control system (Direction + Speed)

## Example 7: Car control system (Direction + Speed)

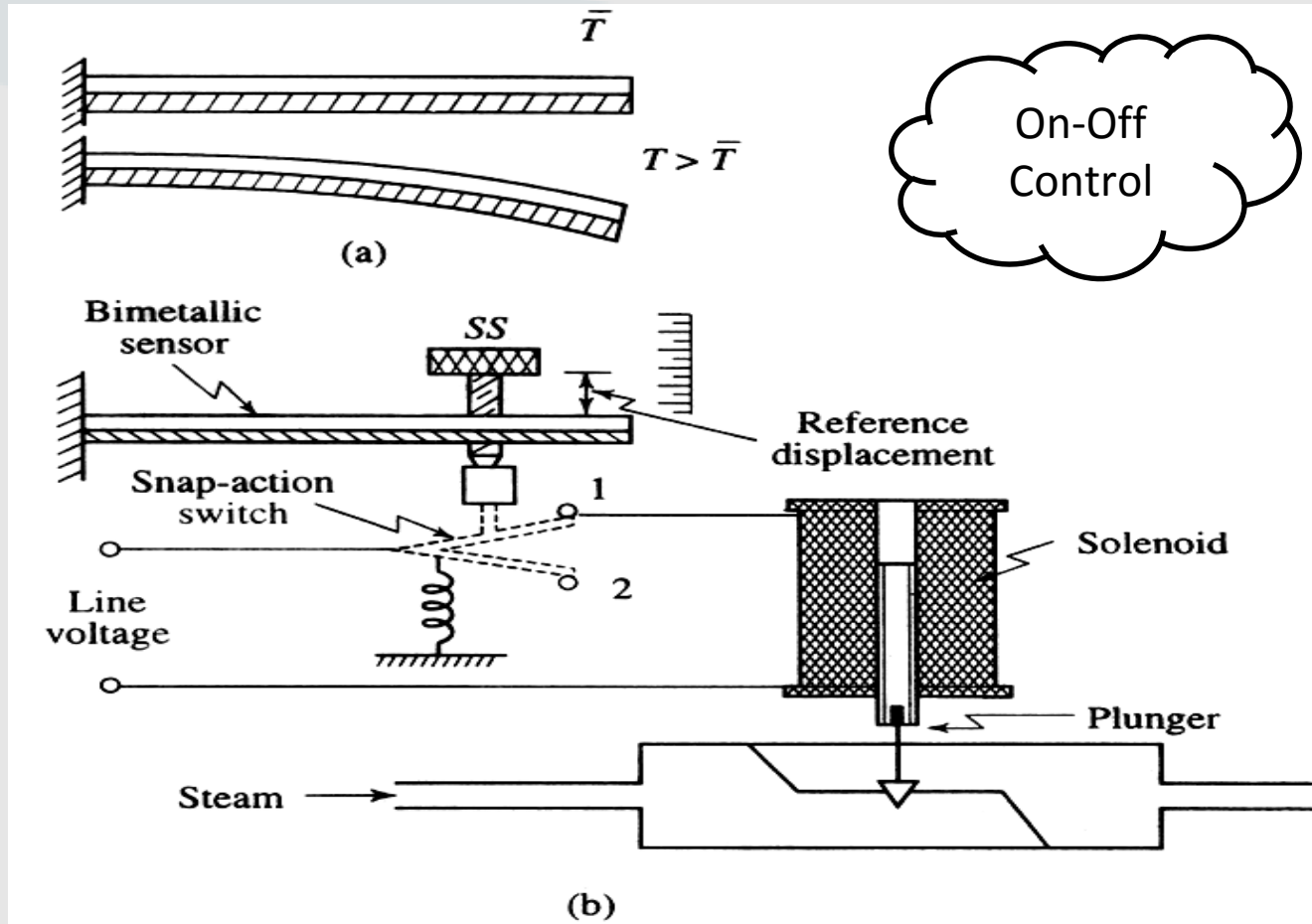
### Car control system (Direction) or Car control system (Speed) :

- Single-input single-output (SISO) control system.
- A single output is controlled according to a single input.

### Car control system (Direction + Speed):

- Multi-input Multi-output (MIMO) control system.
- Multivariable system
- One of the inputs is intended to control a specific output.
- In fact, each input can affect more than one output, and this is called coupling or interaction.
- The car's driving control system (Direction + Speed) can be divided into two SISO systems for design purposes, neglecting mutual interaction.

# Example 8: House automatic heating system:

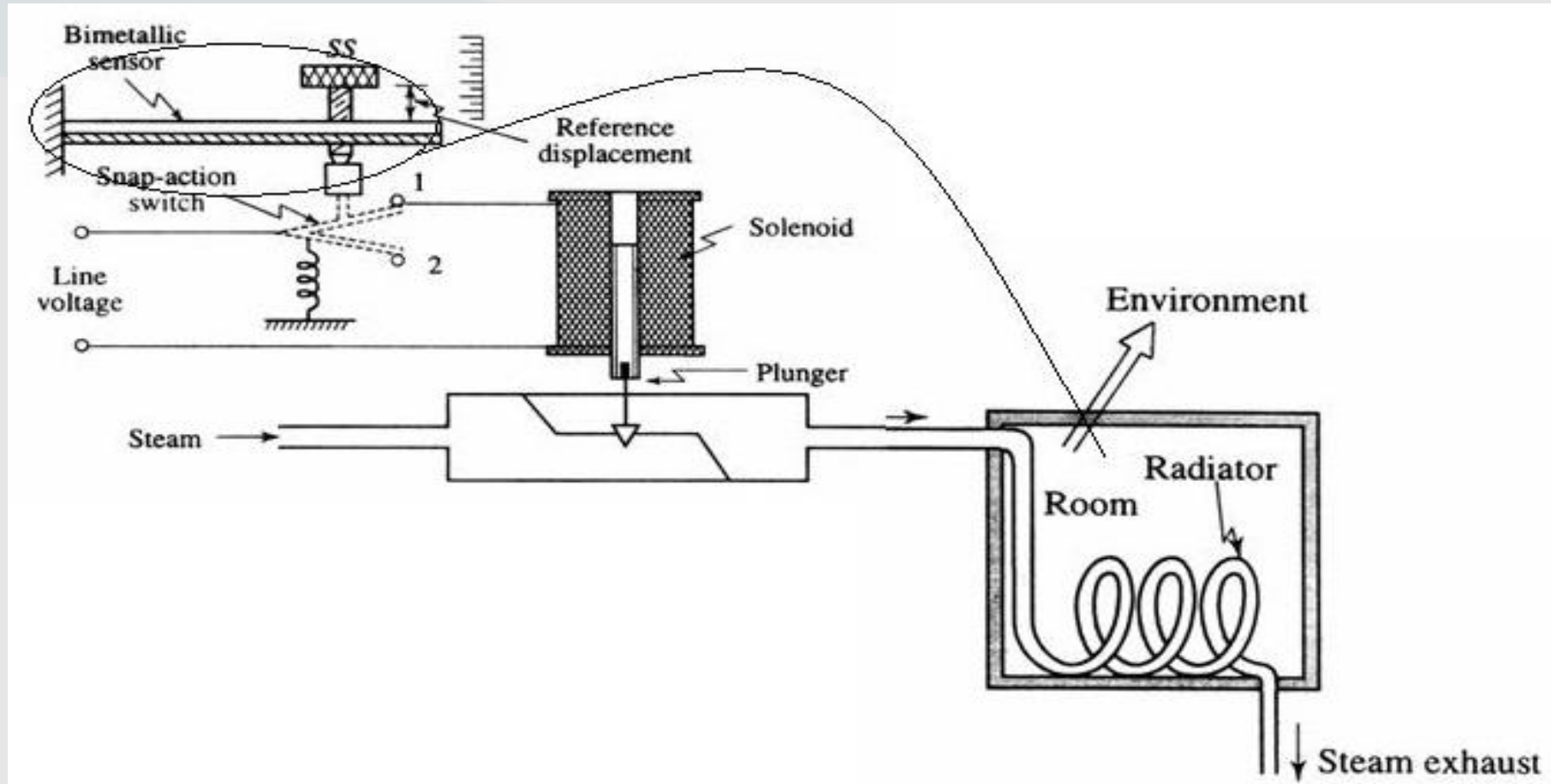


Baby incubator  
Egg incubator  
Heat sterilizers  
Heating/cooling devices

Parts of closed loop house automatic heating system

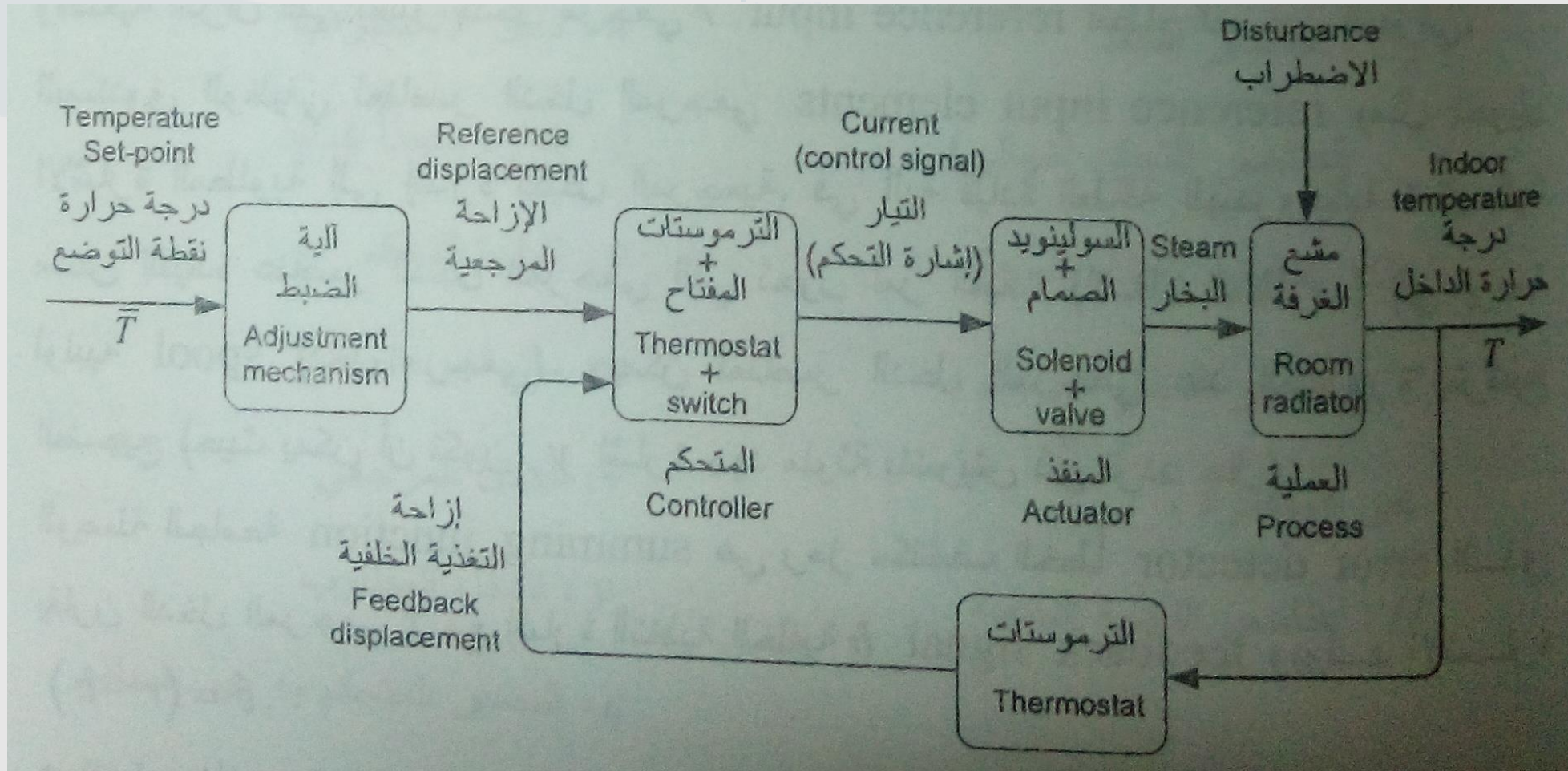


# Example 8: House automatic heating system:



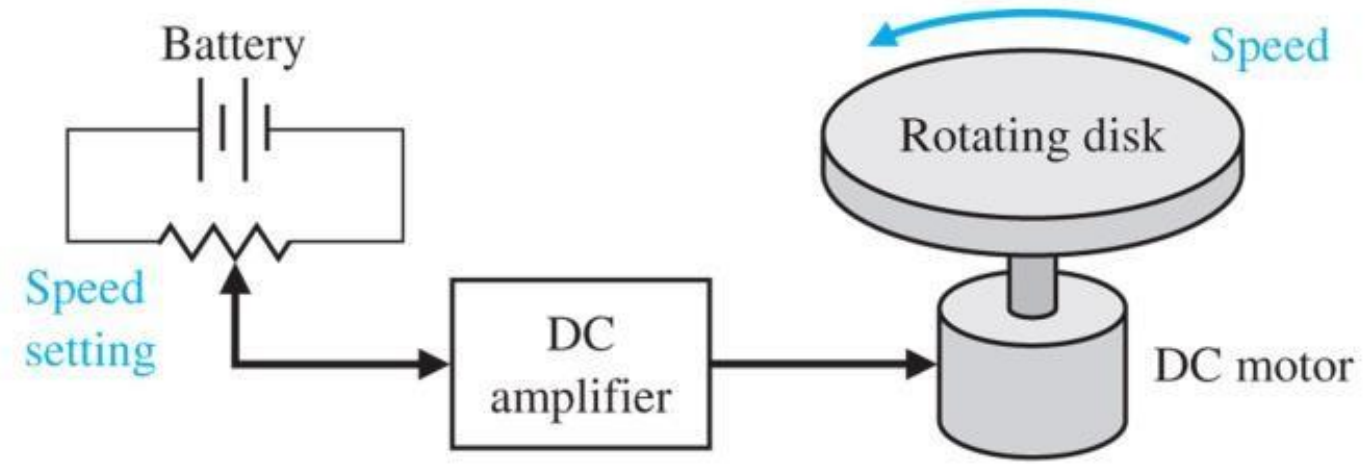
Parts of closed loop house automatic heating system

# Example 8: House automatic heating system:

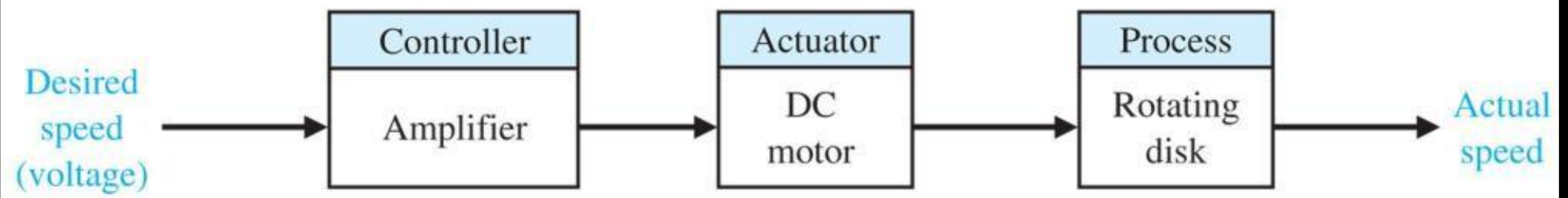


Closed loop house automatic heating system

# Example 9: DC motor speed control: Open-Loop



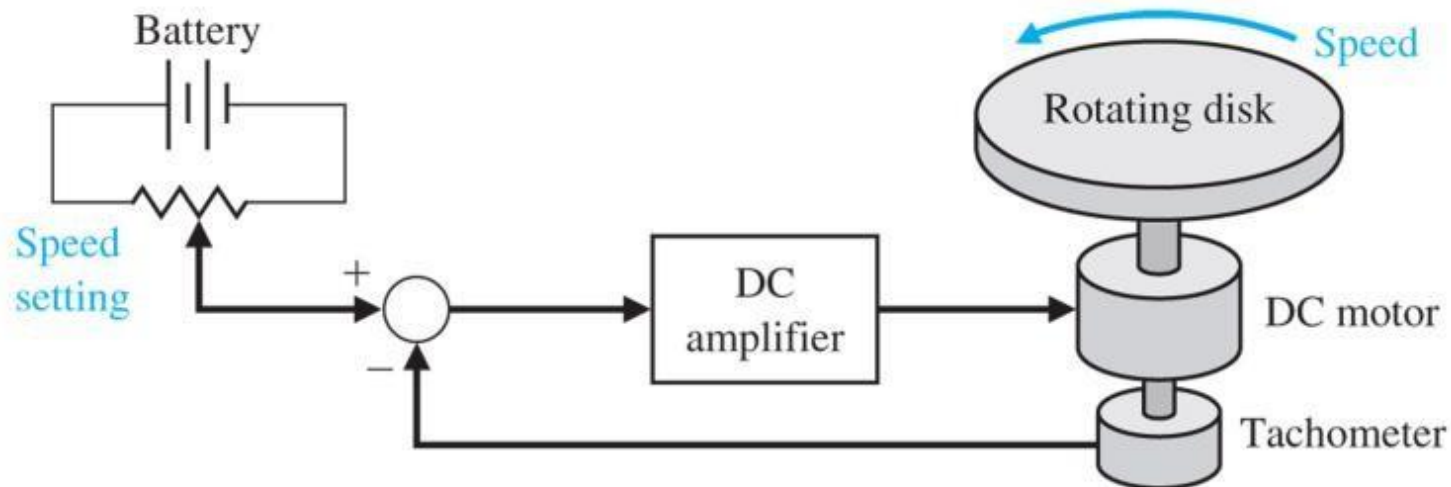
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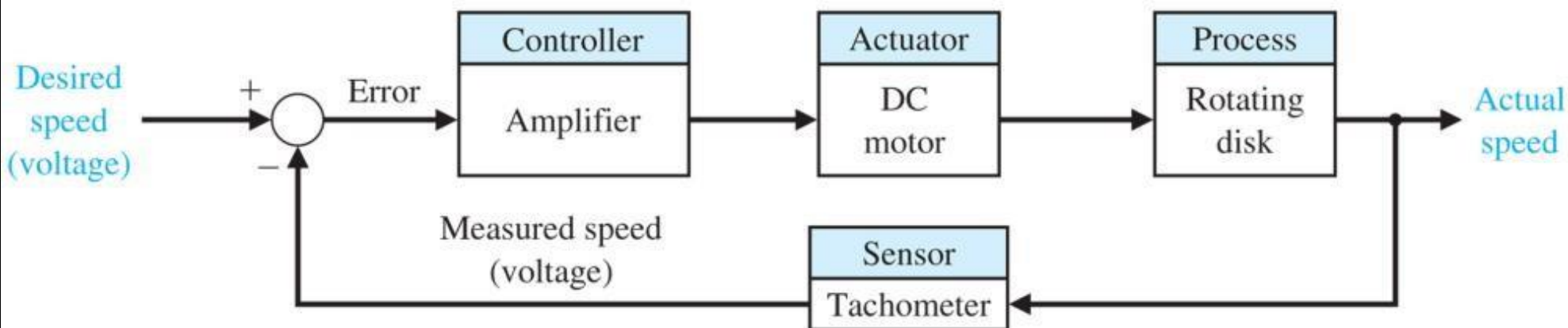
(b)

# Example 10: CD player speed control: Closed-Loop

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(a)



(b)

# Example11: Disturbance Rejection



Georgia Tech School of Electrical and Computer Engineering College of Engineering



<http://www.youtube.com/user/GRITSlab>

Agnes Egerstedt, Control of Mobile Robots, Georgia Institute of Technology

1.1.2

<https://www.youtube.com/watch?v=aSwCMK96NOw>

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