



كلية الهندسة المعلوماتية  
بنيان حواسيب 2  
الفصل الأول 2024-2025  
المحاضرة الأولى

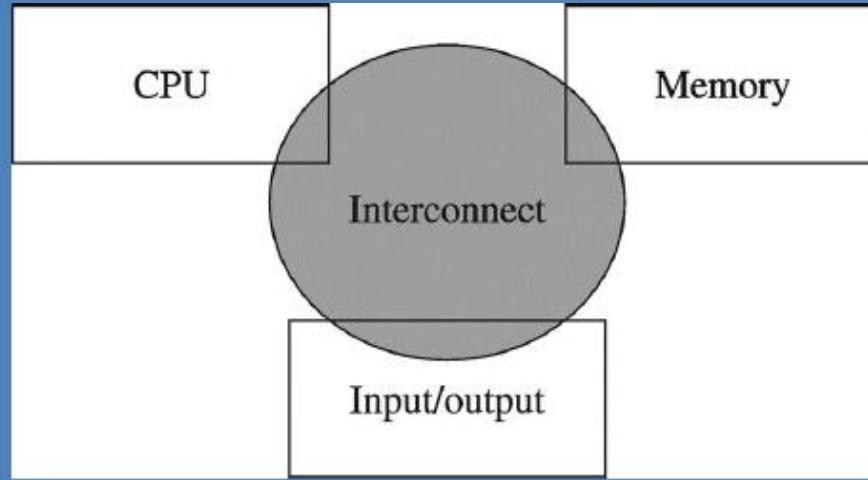
د كندة أبو فاسم

- المكونات الأساسية للحاسوب
- بنية المعالج 8086
- لغة التجميع assembly language
- مجموعة التعليمات Instruction Set
- أنماط العنونة addressing mode
- مجموعة تعليمات النقل
- مجموعة التعليمات الحسابية arithmetic Instruction Set
- العمليات المنطقية
- تعليمات الإزاحة Shift Instructions
- تعليمات التحكم بالعملية Conditional Jump
- تعليمات معالجة السلسل string instruction
- بوابات الدخل / الخرج I/O System Design
- أنماط المقاطعة interrupt mode

- Memory
  - \* Basic operations
  - \* Types of memory
  - \* Storing multibyte data
- Input/Output

- Basic components
- The processor
  - \* Execution cycle
  - \* System clock
- Number of addresses
  - \* 3-address machines
  - \* 2-address machines
  - \* 1-address machines
  - \* 0-address machines
  - \* Load/store architecture

- Basic components of a computer system
  - \* Processor
  - \* Memory
  - \* I/O
  - \* System bus
    - » Address bus
    - » Data bus
    - » Control bus

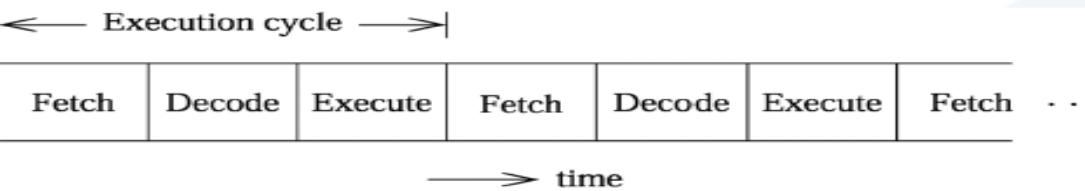


\* المعالج  
\* الذاكر  
\* وحدات الدخل / خرج  
\* خطوط النقل .. خطوط العنونة .. خطوط المعطيات .. خطوط التحكم

## processor عمل المعالج

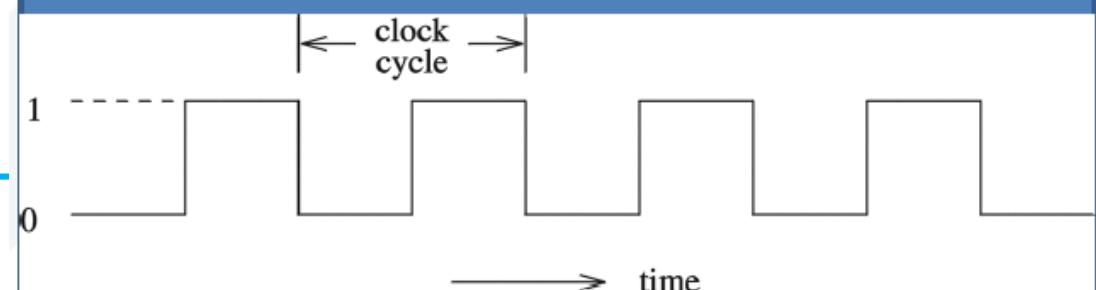
يقوم المعالج خلال دورة تنفيذ التعليمة بما يلي:

- Fetch cycle • مرحلة البحث عن التعليمة  
Decode • مرحلة فك ترميز  
Execution • مرحلة تنفيذ

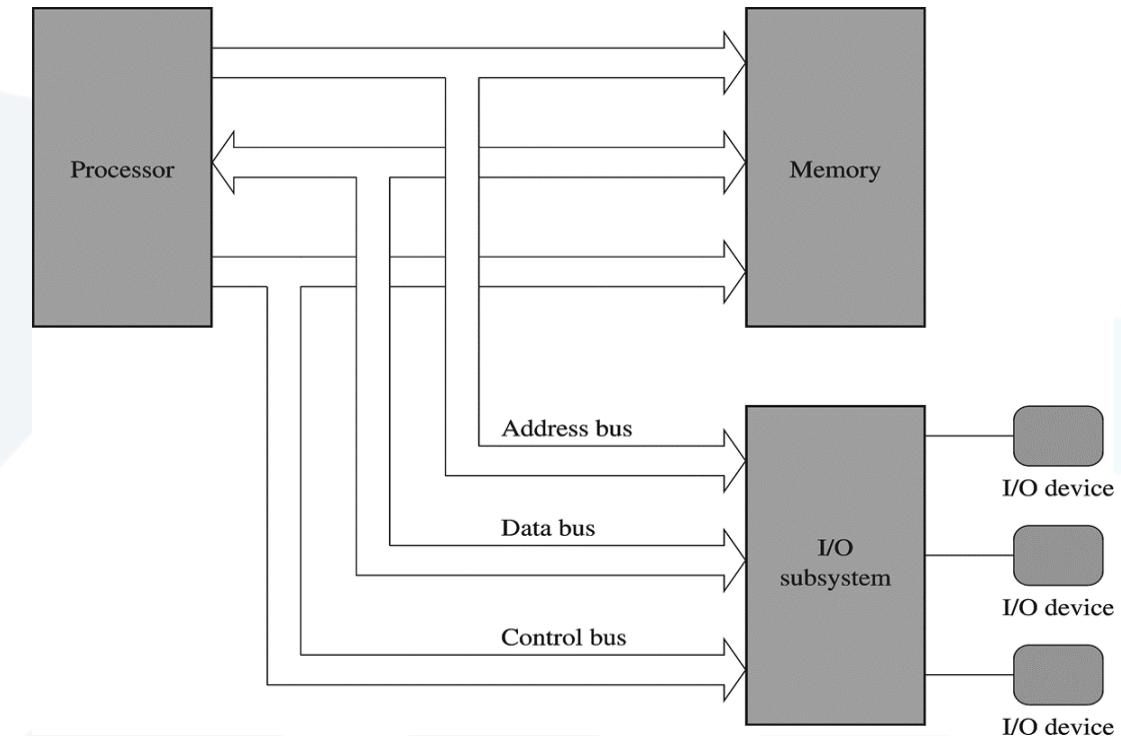


- System clock
  - \* Provides timing signal

$$* \text{Clock period} = \frac{1}{\text{Clock frequency}}$$

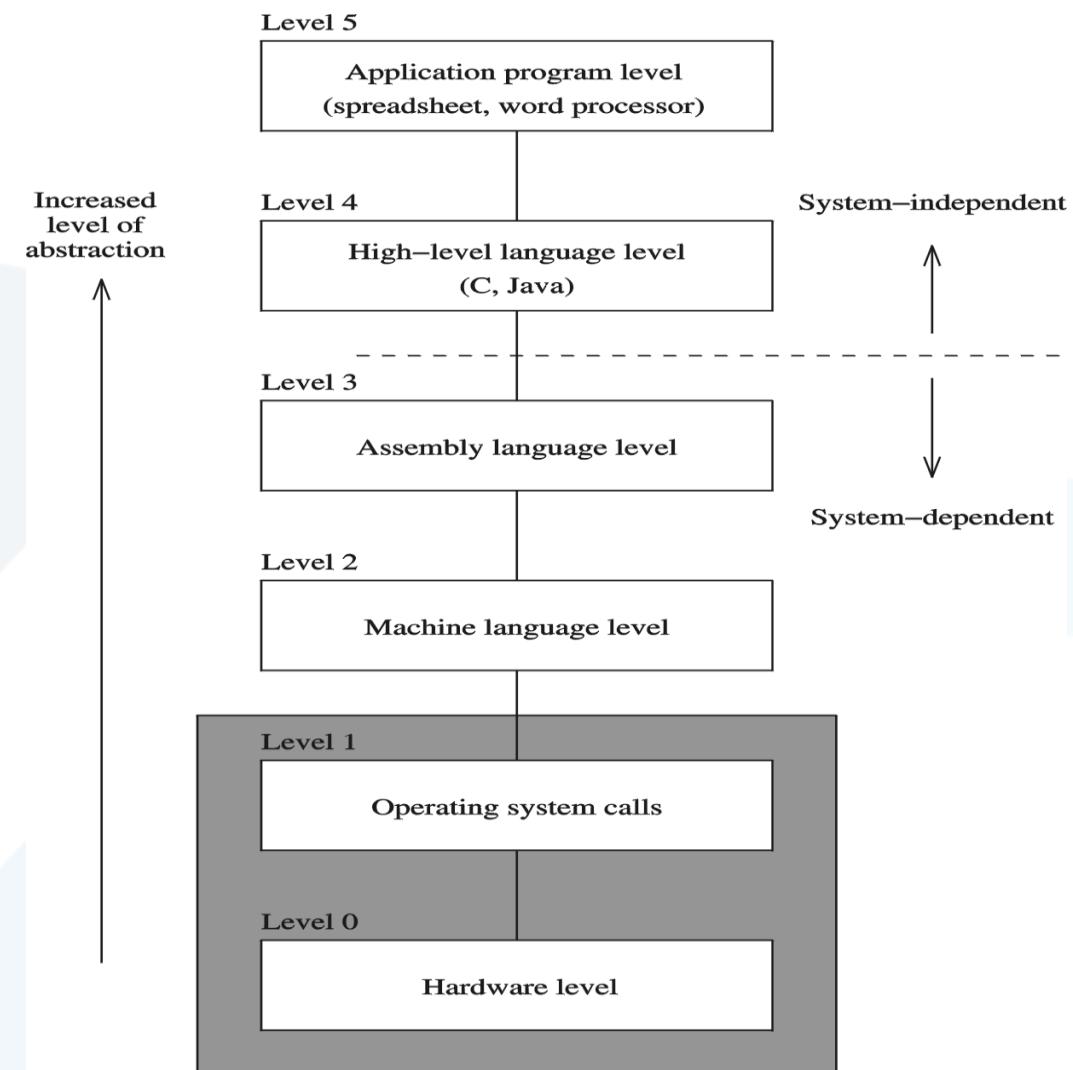


## المكونات الأساسية



## Why Program in Assembly Language?

- Two main reasons:
  - \* Efficiency
    - » Space-efficiency
    - » Time-efficiency
  - \* Accessibility to system hardware
- Space-efficiency
  - \* Assembly code tends to be compact
- Time-efficiency
  - \* Assembly language programs tend to run faster
    - » Only a well-written assembly language program runs faster
    - Easy to write an assembly program that runs slower than its high-level language equivalent



# Typical Applications



- Accessibility to system hardware
  - \* System software typically requires direct control of the system hardware devices
    - » Assemblers, linkers, compilers
    - » Network interfaces, device drivers
    - » Video games
- Space-efficiency
  - \* Not a big plus point for most applications
  - \* Code compactness is important in some cases
    - Portable and hand-held device software
    - Spacecraft control software

- Application that need one of the three advantages of the assembly language
- Time-efficiency
  - \* Time-convenience
    - » Good to have but not required for functional correctness
      - Graphics
  - \* Time-critical
    - » Necessary to satisfy functionality
    - » Real-time applications
      - Aircraft navigational systems
      - Process control systems
      - Robot control software
      - Missile control software

- Four categories
  - \* 3-address machines
    - » 2 for the source operands and one for the result
  - \* 2-address machines
    - » One address doubles as source and result
  - \* 1-address machine
    - » Accumulator machines
    - » Accumulator is used for one source and result
  - \* 0-address machines
    - » Stack machines
    - » Operands are taken from the stack
    - » Result goes onto the stack

- Example

- \* C statement

```
A = B + C * D - E + F + A
```

- \* Equivalent code:

```
mult T,C,D ;T = C*D
```

```
add T,T,B ;T = B+C*D
```

```
sub T,T,E ;T = B+C*D-E
```

```
add T,T,F ;T = B+C*D-E+F
```

```
add A,T,A ;A = B+C*D-E+F+A
```

- Three-address machines

- \* Two for the source operands, one for the result

- \* RISC processors use three addresses

- \* Sample instructions

```
add dest,src1,src2
```

```
; M(dest)=[src1]+[src2]
```

```
sub dest,src1,src2
```

```
; M(dest)=[src1]-[src2]
```

```
mult dest,src1,src2
```

```
; M(dest)=[src1]*[src2]
```

## Two-Address Machines

- Example
  - \* C statement  
 $A = B + C * D - E + F + A$
  - \* Equivalent code:

```
load  T,C ;T = C
mult  T,D ;T = C*D
add   T,B ;T = B+C*D
sub   T,E ;T = B+C*D-E
add   T,F ;T = B+C*D-E+F
add   A,T ;A = B+C*D-E+F+A
```

- Two-address machines
  - \* One address doubles (for source operand & result)
  - \* Last example makes a case for it
    - » Address T is used twice
  - \* Sample instructions

```
load  dest,src ; M(dest)=[src]
add   dest,src ; M(dest)=[dest]+[src]
sub   dest,src ; M(dest)=[dest]-[src]
mult  dest,src ; M(dest)=[dest]*[src]
```

# One-Address Machines



- Example
- C statement

**A = B + C \* D - E + F + A**

- Equivalent code:

```
load  C ;load C into accum
mult  D ;accum = C*D
add   B ;accum = C*D+B
sub   E ;accum = B+C*D-E
add   F ;accum = B+C*D-E+F
add   A ;accum = B+C*D-E+F+A
store A ;store accum contents in A
```

- One-address machines

- \* Uses special set of registers called accumulators
  - » Specify one source operand & receive the result
- \* Called accumulator machines
- \* Sample instructions

```
load  addr ; accum = [addr]
store addr ; M[addr] = accum
add   addr ; accum = accum + [addr]
sub   addr ; accum = accum - [addr]
mult  addr ; accum = accum * [addr]
```

- Example

- \* C statement

**A = B + C \* D - E + F + A**

- \* Equivalent code:

**push E**  
**push C**  
**push D**  
**Mult**  
**push B**  
**add**

**sub**  
**push F**  
**add**  
**push A**  
**add**  
**pop A**

- Zero-address machines

- \* Stack supplies operands and receives the result
    - » Special instructions to load and store use an address

\* Called stack machines (Ex: HP3000, Burroughs B5500)

- \* Sample instructions

**push addr ; push([addr])**

**pop addr ; pop([addr])**

**add ; push(pop + pop)**

**sub ; push(pop - pop)**

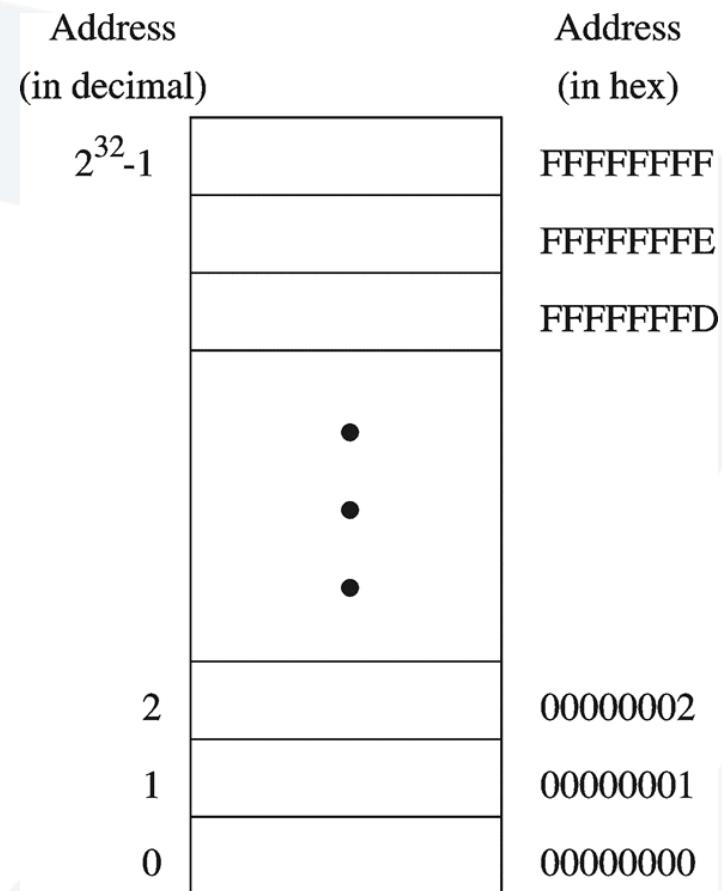
**mult ; push(pop \* pop)**

# الذواكر Memory



الذواكر  
تبعد الذاكرة كنسق من البايت المتتالية  
لكل بايت عنوان  
مثال تعنون الذاكرة من  
 $0 \rightarrow 2^N - 1$

32 bit اذا كان عدد خطوط العنونة  
فيكون عدد مواقع الذاكرة  
 $2^N - 1 = 4 G\ byte$

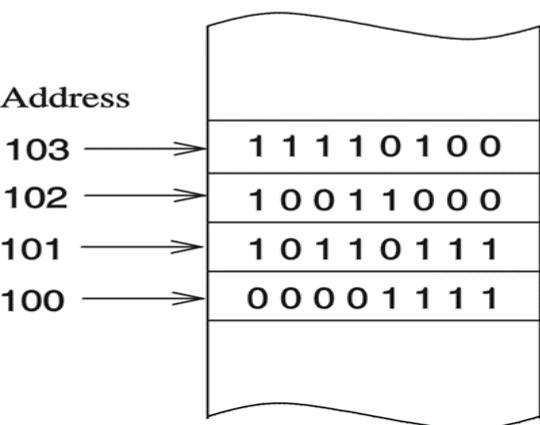


- Memory can be viewed as an ordered sequence of bytes
- Each byte of memory has an address
  - Memory address is essentially the sequence number of the byte
  - Such memories are called *byte addressable*
  - Number of address lines determine the memory address space of a processor

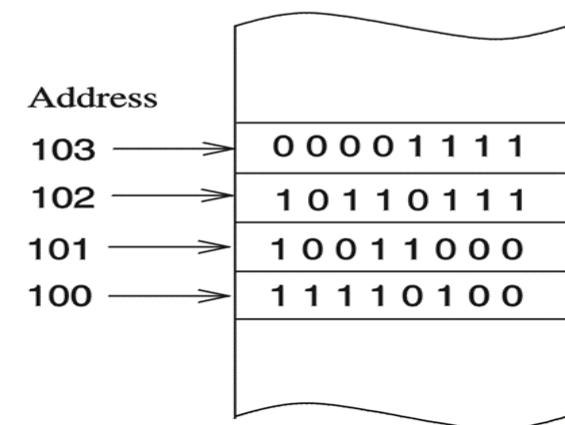
## تخزين multibyte

MSB	1 1 1 1 0 1 0 0	1 0 0 1 1 0 0 0	1 0 1 1 0 1 1 1	0 0 0 0 1 1 1 1	LSB
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(a) 32-bit data



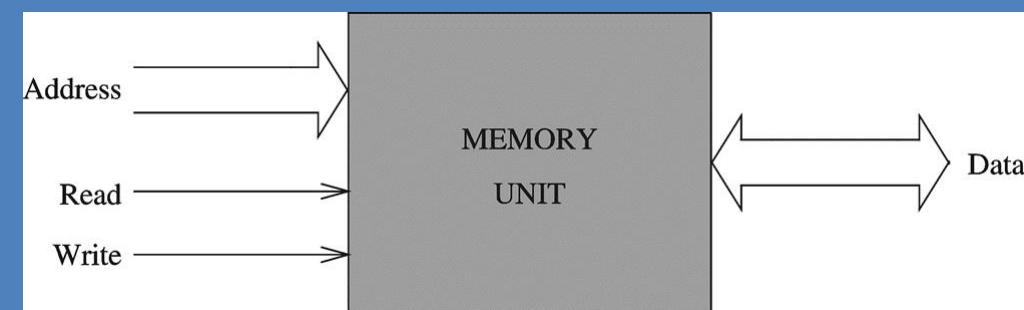
(b) Little-endian byte ordering



(c) Big-endian byte ordering

- **Little endian**
  - » Used by Intel IA-32 processors
- **Big endian**
  - » Used most processors by default

- Two basic memory operations
  - \* Read operation (read from memory)
  - \* Write operation (write into memory)
- Access time
  - » Time needed to retrieve data at addressed location
- Cycle time
  - » Minimum time between successive operations



# الدخل والخرج input /output



## وحدات الادخال والإخراج I/O

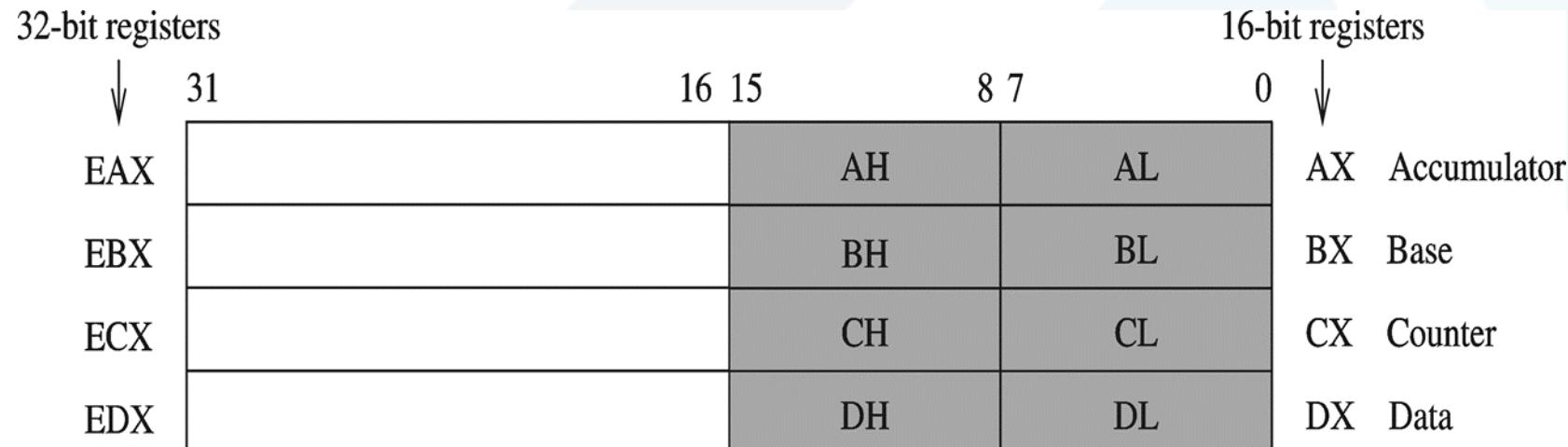
- تستخدم بوابات الإدخال والإخراج لتبادل المعلومات بين المعالج وبوابات الدخل / خرج يمكن تخطيط بوابات I/O كوحدة من الذاكرة
- \* تجز بوابات الدخل / خرج عنوانين من الذاكرة الرئيسية كما تقوم بعملية القراءة والكتابة كما في الذاكر
- \* بوابات دخل/خرج معزولة
- تستخدم فضاء عنوانين منفصلة
- تحتاج الى تعليمات خاصة للدخل والخرج
- في معالجات بنبيوم مثل `in , out`
- تدعم معالجات انتل 80x86 وحدات دخل/خرج منفصلة

- Processor and I/O interface points for exchanging data are called *I/O ports*
- Two ways of mapping I/O ports
  - \* Memory-mapped I/O
    - » I/O ports are mapped to the memory address space
      - Reading/writing I/O is similar to reading/writing memory
        - Can use memory read/write instructions
    - \* Isolated I/O
      - » Separate I/O address space
      - » Requires special I/O instructions (like `in` and `out` in Pentium)
      - » Intel 80x86 processors support isolated I/O

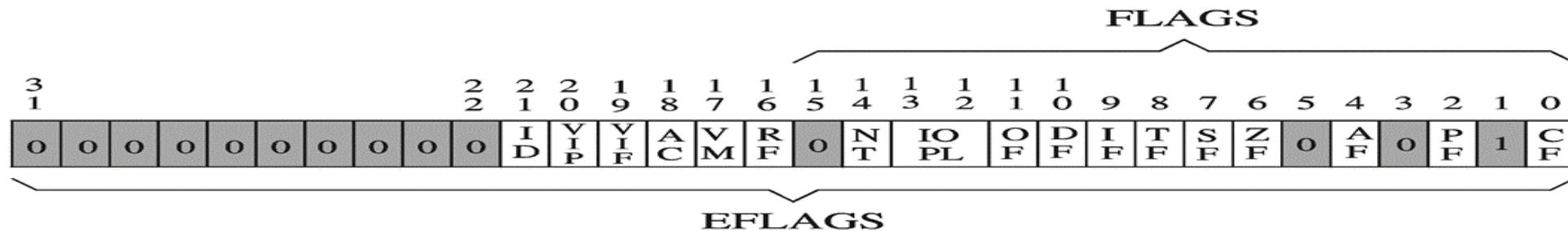
عنونة I/O في معالجات بنتيوم  
تستخدم معالجات بنتيوم فضاء العنوانين  
- تزود بفضاء عنوان 64 k byte  
- يمكن ان تستخدم بوابات من 8 أو 16 أو 32  
- تعليمات I/O لا تمر عبر المقاطع او الصفحات

- Pentium I/O address space
  - \* Provides 64 KB I/O address space
  - \* Can be used for 8-, 16-, and 32-bit I/O ports
  - \* Combination cannot exceed the total I/O address space
    - » can have 64 K 8-bit ports
    - » can have 32 K 16-bit ports
    - » can have 16 K 32-bit ports
    - » A combination of these for a total of 64 KB
  - \* I/O instructions do not go through segmentation or paging
    - » I/O address refers to the physical I/O address

- Four 32-bit registers can be used as
  - \* Four 32-bit register (EAX, EBX, ECX, EDX)
  - \* Four 16-bit register (AX, BX, CX, DX)
  - \* Eight 8-bit register (AH, AL, BH, BL, CH, CL, DH, DL)
- Some registers have special use
  - \* ECX for count in loop instructions



Flags register



### Status flags

CF = Carry flag

PF = Parity flag

AF = Auxiliary carry flag

ZF = Zero flag

SF = Sign flag

OF = Overflow flag

### Control flags

DF = Direction flag

### System flags

TF = Trap flag

IF = Interrupt flag

IOPL = I/O privilege level

NT = Nested task

RF = Resume flag

VM = Virtual 8086 mode

AC = Alignment check

VIF = Virtual interrupt flag

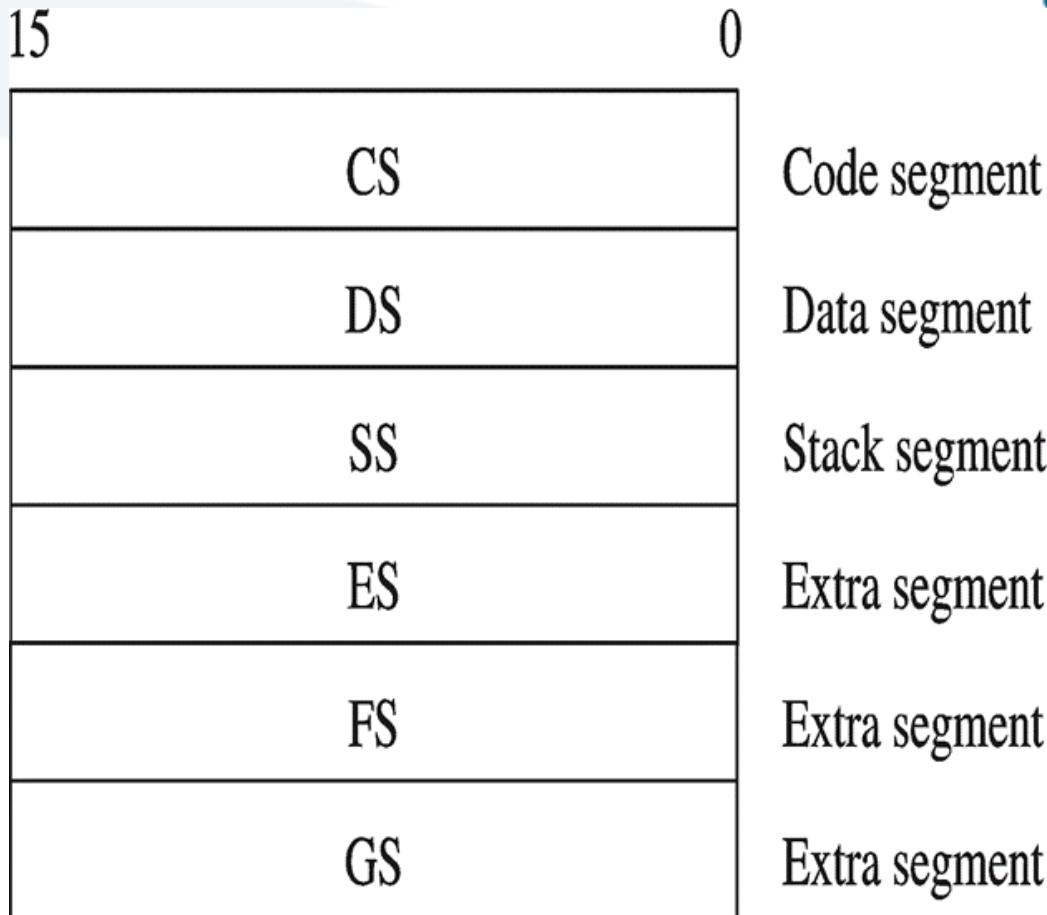
VIP = Virtual interrupt pending

ID = ID flag

Instruction pointer



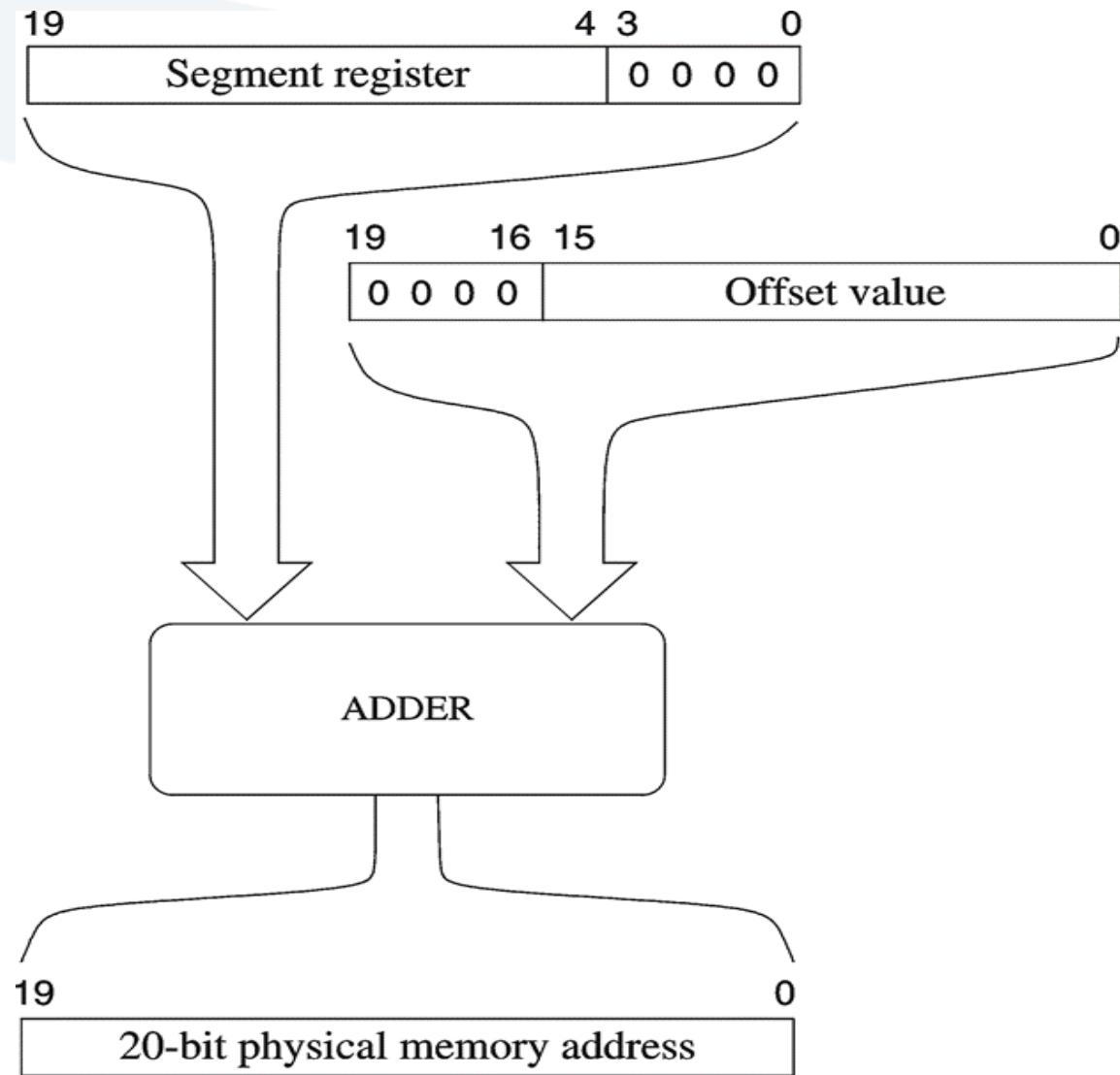
EIP



- Segment register
  - \* Six 16-bit registers
  - \* Support segmented memory architecture
  - \* At any time, only six segments are accessible
  - \* Segments contain distinct contents
    - » Code
    - » Data
    - » Stack

- Pentium supports two modes
  - \* Protected mode
    - » 32-bit mode
    - » Native mode of Pentium
    - » Supports segmentation and paging
  - \* Real mode
    - » Uses 16-bit addresses
    - » Runs 8086 programs
    - » Pentium acts as a faster 8086

# Real Mode نمط



## نمط Real Mode

- Programs can access up to six segments at any time
- Two of these are for
  - \* Data
  - \* Code
- Another segment is typically used for
  - \* Stack
- Other segments can be used for
  - \* data, code,..

