



Steel Structures 2 Sem. 1 2024-2025

أ.د. نايل محمد حسن

Lecture 6-7-8

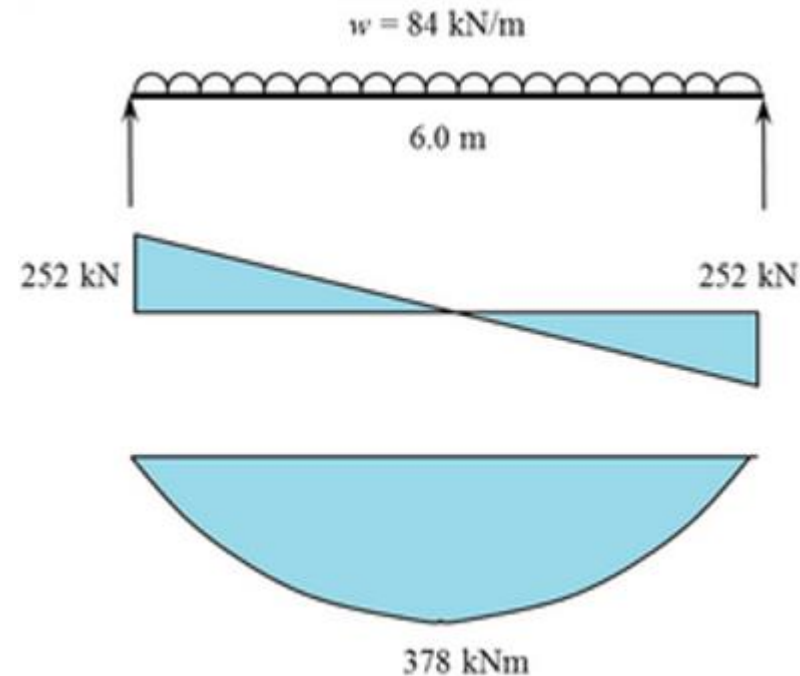
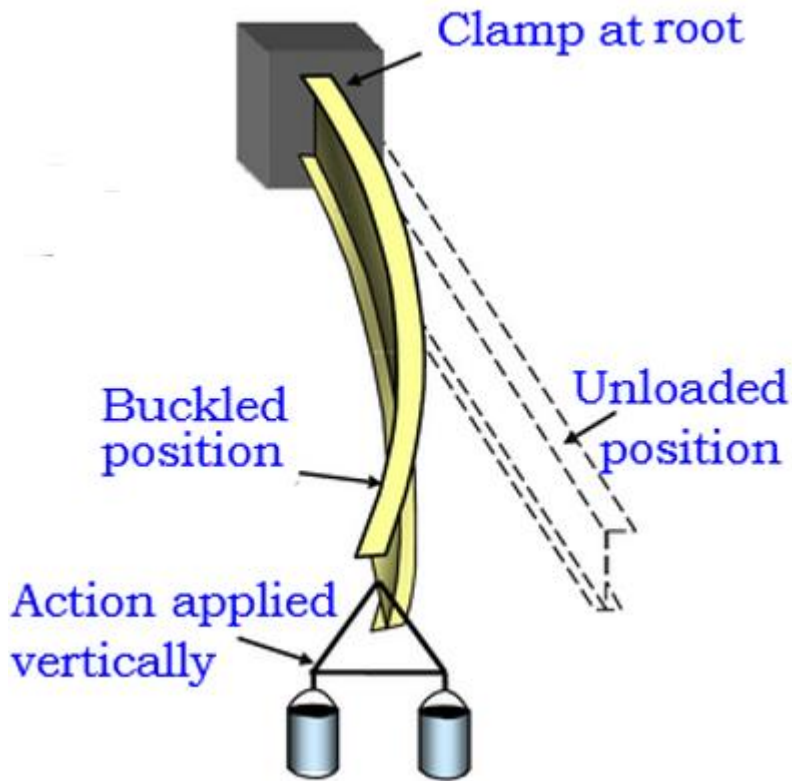
Flexural Members

- ✓ -I- Laterally Restrained Beams
- ✓ II- Laterally Unrestrained Beams



Introduction: Beams, Response to loads

A beam is a **structural member** which is subjected to **transverse** loads, and accordingly must be designed to withstand predominantly **shear and moment**, Generally, it will be bent about its major axis..



Slender structural elements loaded in a stiff plane tend to fail by buckling in a more flexible plane (out-of-plane buckling)

Introduction: Unrestrained Beams

- this lecture covers the **design of unrestrained beams** that are prone to **lateral torsional** buckling.
- Beams without continuous lateral restraint are **prone** to buckling about their major axis, this mode of buckling is called **lateral torsional buckling (LTB)**.

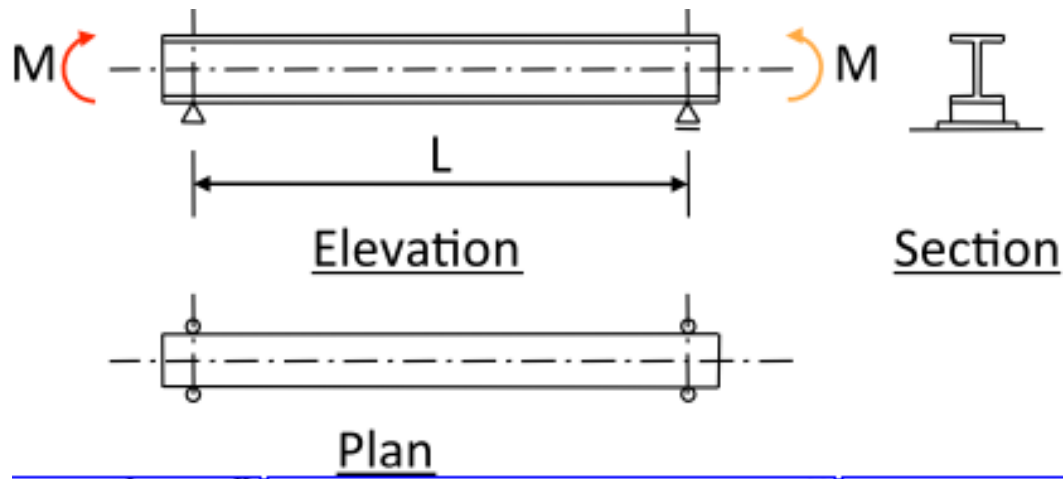
Lateral torsional buckling can be discounted when:

- The section is **bent about its minor axis**
- **Full lateral restraint** is provided
- **Closely spaced bracing** is provided making the slenderness of the weak axis low
- The **compressive flange** is restrained against torsion
- The section has a **high torsional and lateral** bending stiffness

Introduction: Unrestrained Beams

Behaviour

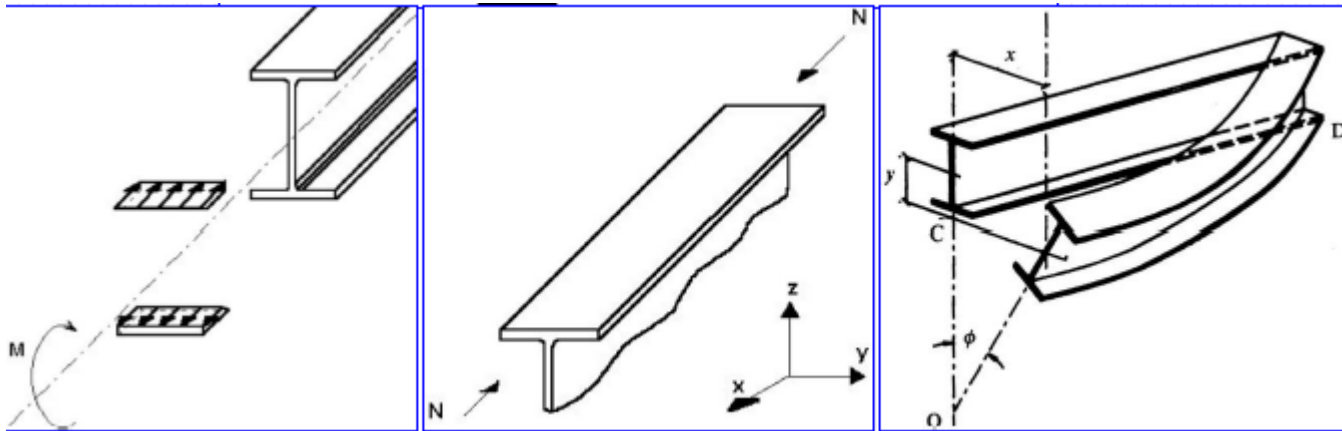
Beam is Perfectly elastic, initially straight, loaded by equal and opposite end moments about its major axis.



- ✓ Beam is **Unrestricted** along its length.
- ✓ End Supports
 - ✓ Twisting and lateral deflection prevented.
 - ✓ Free to rotate both in the plane of the web and on plan.

Introduction: Unrestrained Beams

Beam is Perfectly elastic, initially straight, loaded by equal and opposite end moments about its major axis.



Three components of displacement are observed i.e

- Vertical (**y**)
- Horizontal (**x**)
- and torsional (**ϕ**) displacement

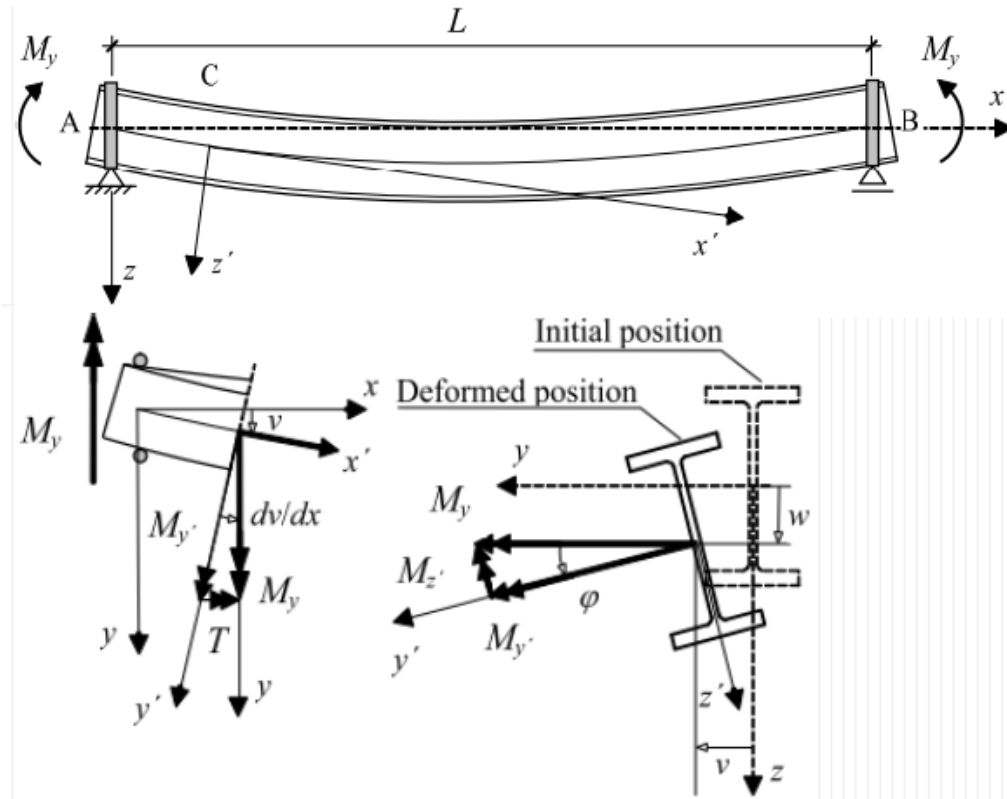
Introduction: Unrestrained Beams-Elastic Critical Moment

Elastic critical moment

Consider the following assumptions:

- **Perfect beam**, without any type of imperfections (geometrical or material);
- **Doubly symmetric cross section**;
- Material with **linear elastic** behavior;
- **Small displacements** ($\cos(\phi)=1$; $\sin(\phi) = \phi$)

The critical value of the moment about the major axis M_y , denoted as M_{cr}^E (critical moment of the "standard case") resulting in lateral torsional buckling is obtained:



Plant – segment A-C

Cross-section C

$$M_{cr}^E = \frac{\pi}{L} \sqrt{G I_T E I_z \left(1 + \frac{\pi^2 E I_w}{L^2 G I_T} \right)},$$

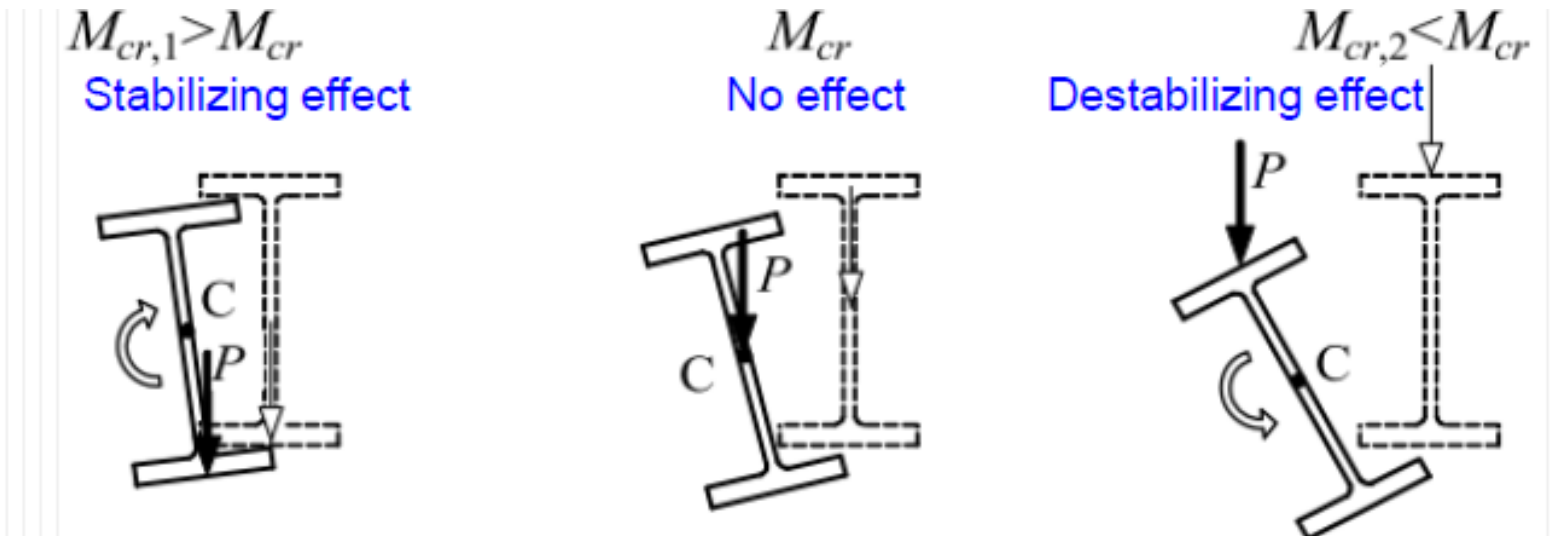
Introduction: Unrestrained Beams-Elastic Critical Moment

Elastic critical moment

It can be observed that the **critical moment** of a member under bending depends on several factors, such as:

- **loading** (shape of the bending moment diagram);
- **support** conditions;
- **length** of the member between laterally braced cross sections;
- lateral bending **stiffness**; torsion stiffness; warping stiffness.

Besides these factors, the point of application of the loading also has a direct influence on the elastic critical moment of a beam



Introduction: Unrestrained Beams- Behavior of Real Steel Beams

Real Steel Beams

- In reality beams are not **free from imperfection**, not purely **elastic**, not always simply supported, not always loaded with only a constant flexure and are not of a doubly **symmetric sections**, consequently, subject to different **bending moment diagrams**.
- The derivation of an **exact expression** for the critical moment for each case of real beams is not **practical**, as this implies the computation of differential equations of some **complexity**.
- Therefore, in practical applications **approximate formulae** are used, which are applicable to a wide set of situations.

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

Real Steel Beams

As an alternative to some of the expressions, the **elastic critical moment** can be estimated using **expression below** proposed by Clark and Hill (1960) and Galea (1981) . It is applicable to members subject to **bending about the strong axis**, with cross sections mono-symmetric about the weak z axis, for several support conditions and types of loading.

$$M_{cr} = C_1 \frac{\pi^2 E I_z}{(k_z L)^2} \left\{ \left[\left(\frac{k_z}{k_w} \right)^2 \frac{I_w}{I_z} + \frac{(k_z L)^2 G I_T}{\pi^2 E I_z} + (C_2 z_g - C_3 z_j)^2 \right]^{0.5} - (C_2 z_g - C_3 z_j) \right\}$$

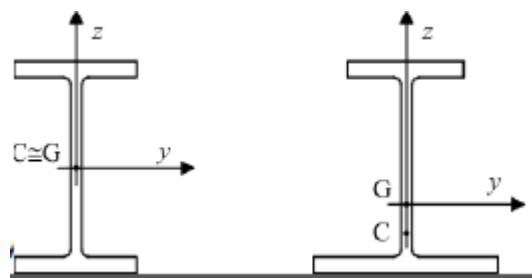
L	is the distance between points of lateral restraint (L_{cr})
E	is the Young's Modulus = 210000 N/mm ²
G	is the shear modulus = 80770 N/mm ²
I_z	is the second moment of area about the weak axis
I_t	is the torsion constant
I_w	is the warping constant
k_z	is an effective length factor related to rotations at the end section about the weak axis z (can be conservatively taken as 1.0)
k_w	is an effective length factor related to warping restriction in the same cross sections (can be conservatively taken as 1.0)

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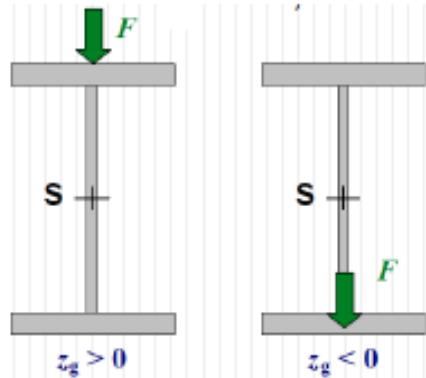


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Introduction: Unrestrained Beams- Behavior of Real Steel Beams

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z_j is a parameter that reflects degree of asymmetry of the cross section in relation to the y axis.

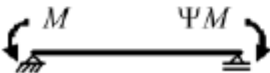






$$z_j = z_s - \left(0.5 \int_A (y^2 + z^2) (z/I_y) dA \right) z_g$$

z_g is the distance between the point of load application and the shear center. The value will be positive or negative depending on where the load is applied as shown in the figure.

$z_j = 0$ for beams with doubly symmetric cross section (such as I or H cross sections with equal flanges)

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

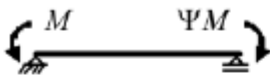
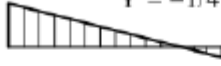
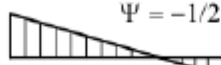

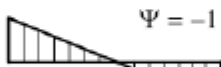
C_1 , C_2 , and C_3 are coefficients depending on the shape of the bending moment diagram and on support conditions,

Loading and support conditions	Diagram of moments	k_z	C_1	C_3	
				$\psi_f \leq 0$	$\psi_f > 0$
	$\Psi = +1$ 	1.0	1.00	1.000	
		0.5	1.05	1.019	
	$\Psi = +3/4$ 	1.0	1.14	1.000	
		0.5	1.19	1.017	
	$\Psi = +1/2$ 	1.0	1.31	1.000	
		0.5	1.37	1.000	
	$\Psi = +1/4$ 	1.0	1.52	1.000	
		0.5	1.60	1.000	
	$\Psi = 0$ 	1.0	1.77	1.000	
		0.5	1.86	1.000	
	$\Psi = -1/4$ 	1.0	2.06	1.000	0.850
		0.5	2.15	1.000	0.650



Introduction: Unrestrained Beams- Behavior of Real Steel Beams

C1, C2, and C3 are coefficients depending on the shape of the bending moment diagram and on support conditions,

Loading and support conditions	Diagram of moments	k_z	C_1	C_3	
				$\psi_f \leq 0$	$\psi_f > 0$
	 $\Psi = -1/4$	1.0	2.06	1.000	0.850
		0.5	2.15	1.000	0.650
	 $\Psi = -1/2$	1.0	2.35	1.000	$1.3 - 1.2\psi_f$
		0.5	2.42	0.950	$0.77 - \psi_f$
	 $\Psi = -3/4$	1.0	2.60	1.000	$0.55 - \psi_f$
		0.5	2.45	0.850	$0.35 - \psi_f$
	 $\Psi = -1$	1.0	2.60	$-\psi_f$	$-\psi_f$
		0.5	2.45	$-0.125 - 0.7\psi_f$	$-0.125 - 0.7\psi_f$

▪ In beams subject to end moments, by definition $C_2 z_g = 0$.

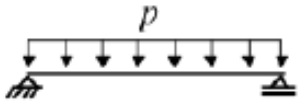

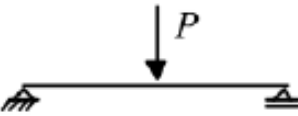

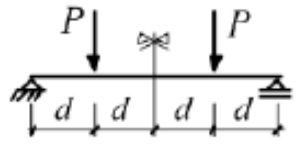

▪ $\psi_f = \frac{I_{fc} - I_{ft}}{I_{fc} + I_{ft}}$, where I_{fc} and I_{ft} are the second moments of area of the

compression and tension flanges respectively, relative to the weak axis of the section (z axis);

▪ C_1 must be divided by 1.05 when $\frac{\pi}{k_w L} \sqrt{\frac{EI_w}{GI_T}} \leq 1.0$, but $C_1 \geq 1.0$.

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

C_1 , C_2 , and C_3 are coefficients depending on the shape of the bending moment diagram and on support conditions,

Loading and support conditions	Diagram of moments	k_z	C_1	C_2	C_3
		1.0 0.5	1.12 0.97	0.45 0.36	0.525 0.478
		1.0 0.5	1.35 1.05	0.59 0.48	0.411 0.338
		1.0 0.5	1.04 0.95	0.42 0.31	0.562 0.539

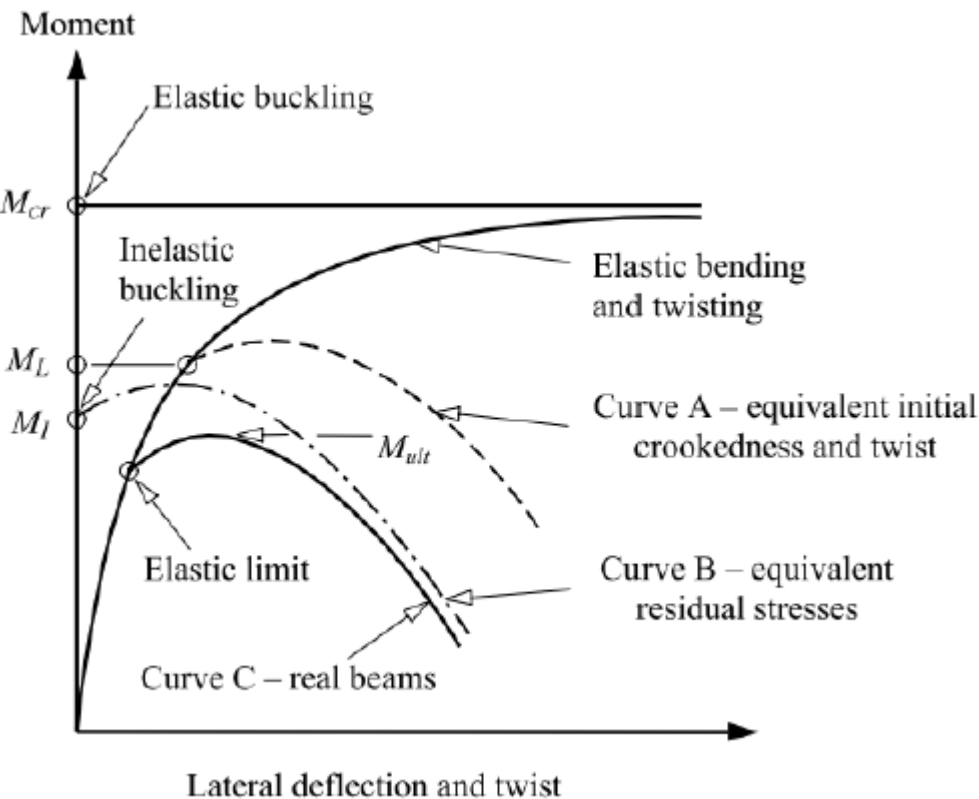
In case of **mono-symmetric I** or **H** cross sections, the tables can be used if the following condition is verified

$$-0.9 \leq \psi \leq 0.9$$

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

Resistance of Real Steel Beams

Real beams differ from an ideal beams in much the same way as do real compression members.



- Thus any small imperfections such as **initial** crookedness, twist, eccentricity of load, or **horizontal load** components cause the beam to behave as if it had an **equivalent initial crookedness and twist**, as shown by **curve A**
- **Imperfections** such as residual stresses or variations in material properties cause the beam to behave as shown by **curve B**.
- The behavior of **real beams** having both types of imperfection is indicated by **curve C**.
- **Curve C** shows a **transition** from the **elastic behaviour** of a beam with curvature and twist to the **inelastic post-buckling behaviour** of a beam with **residual stresses**.

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

The influence of Slenderness

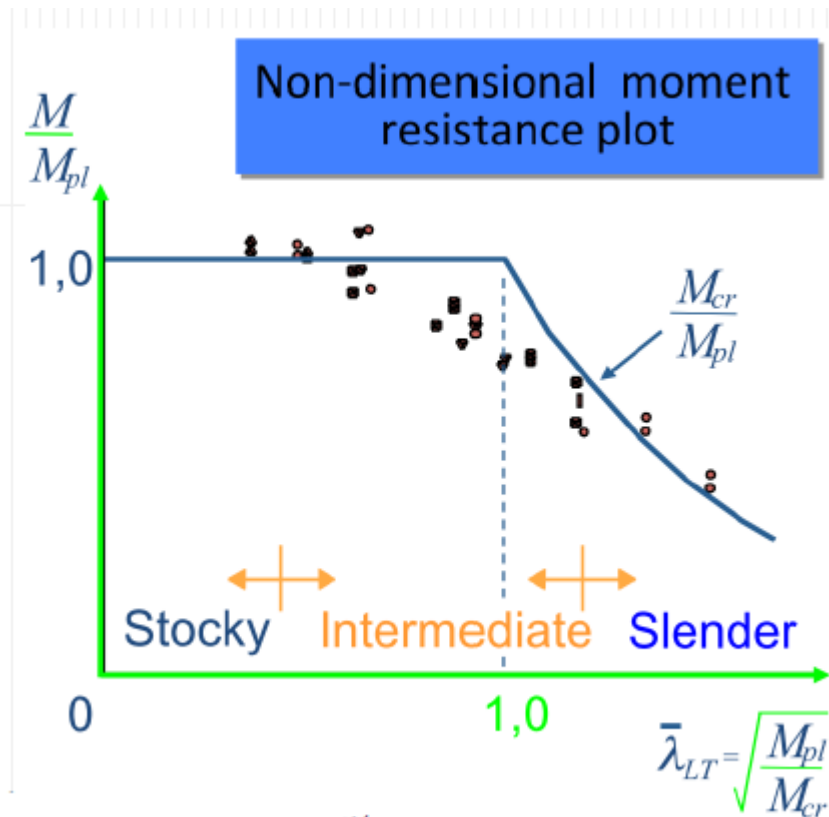
Considering the analogy between N_{cr} and M_{cr} , the lateral-torsional behavior of beams in bending is similar to a compressed column. Therefore:

- The resistance of **short/stocky** members depends on the value of the **cross section bending resistance** (plastic or elastic bending moment resistance, depending of its cross section class).
- The resistance of **slender members** depends on the value of **the critical moment (M_{cr})**, associated with lateral-torsional buckling.
- The resistance of members with **intermediate slenderness** depends on the interaction between **plasticity** and **instability**

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

The influence of Slenderness

Non-dimensional plot permits results from different test series to be compared.



- **Stocky beams** ($\lambda_{LT} < 0.4$) unaffected by lateral torsional buckling
- **Slender beams** ($\lambda_{LT} > 1.2$) resistance close to elastic critical moment M_{cr} .
- **Intermediate slenderness** adversely affected by inelasticity and geometric imperfections.
- **EC3 uses a reduction factor χ_{LT} on plastic resistance moment to cover the whole slenderness range..**

Introduction: Unrestrained Beams- Behavior of Real Steel Beams

The influence of Slenderness

Summary of factors to consider influence of Slenderness

Warping: is the distortion of the elements of a steel section out of the plane perpendicular to the axis of the member under twisting/torsion.

Restraining this effects will have a favorable impact in avoiding lateral torsional buckling

End Constraints: Restraints have a major influence on the occurrence of instability and can be utilized to enhance the load carrying capacity of the beam whenever instability is likely to occur.

The stiffness in the minor axis Vs stiffness in the major axis: Section with relatively equal stiffness about both axis are almost never likely to experience LTB.

Bracing: Lateral bracing of beams is the common measure to overcome the occurrence of LTB

Point of Load application: In relation to the shear center of the section the point of load application may have a favorable/stabilizing or unfavorable/destabilizing effect

Design According to EC3: Unrestrained Beams

Lateral-Torsional Buckling Resistance

The verification of resistance to lateral-torsional buckling of a prismatic member consists of the verification of the following condition (clause 6.3.2.1(1)):

$$\frac{M_{Ed}}{M_{b,Rd}} \leq 1.0,$$

$M_{b,Rd}$ is the design buckling resistance, given by (clause 6.3.2.1(3))

where :

- $W_y = W_{pl,y}$ for class 1 and 2 cross sections;
- $W_y = W_{el,y}$ for class 3 cross sections;
- $W_y = W_{eff,y}$ for class 4 cross sections;
- χ_{LT} is the reduction factor for lateral-torsional buckling.

In EC3-1-1 **two methods** for the calculation of the reduction coefficient χ_{LT} in prismatic members are proposed:

A General Method that can be applied to any type of cross section (more conservative)

Alternative Method that can be applied to rolled cross sections or equivalent welded sections.

Design According to EC3: Unrestrained Beams

A General Method-Any section

$$\chi_{LT} = \frac{1}{\phi_{LT} + (\phi_{LT}^2 - \bar{\lambda}_{LT}^2)^{0.5}}, \quad \text{but } \chi_{LT} \leq 1.0,$$

$$\phi_{LT} = 0.5 \left[1 + \alpha_{LT} (\bar{\lambda}_{LT} - 0.2) + \bar{\lambda}_{LT}^2 \right];$$

$$\bar{\lambda}_{LT} = \left[W_y f_y / M_{cr} \right]^{0.5}$$

α_{LT} is the imperfection factor, which depends on the buckling curve

0.21, 0.34, 0.49 and 0.76 for curves
a, b, c and d

M_{cr} is the elastic critical moment.

The buckling curves to be adopted depend on the geometry of the cross section of the member

Section	Limits	Buckling curve
I or H sections rolled	$h/b \leq 2$	a
	$h/b > 2$	b
I or H sections welded	$h/b \leq 2$	c
	$h/b > 2$	d
Other sections	---	d

Design According to EC3: Unrestrained Beams

Alternative Method-Rolled or equivalent welded sections

Students are highly advised to read more on this topic. The discussion of this method presented in “*Design of Steel Structures Eurocode 3, 2010, by da Silva L.S.*” is recommended as a starting literature.

Deflection Resistance

- Deflections of flexural members must be **limited to avoid** damage to finishes, ceilings and partitions, and should be calculated under SLS loads.
- EC3 states that **limits for vertical deflections** should be specified for each project and agreed with the client. The UK National Annex to EC3 suggests:

NA.2.23 Vertical deflections [BS EN 1993-1-1:2005, 7.2.1(1)B]

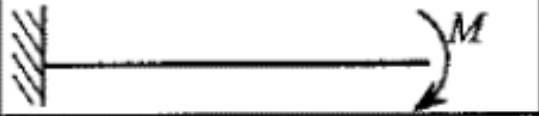
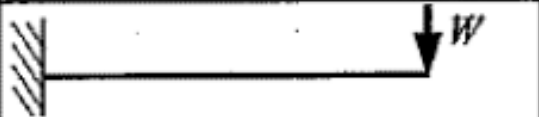
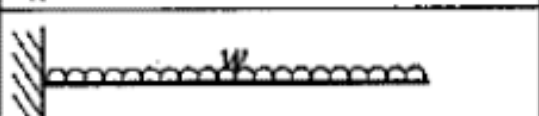
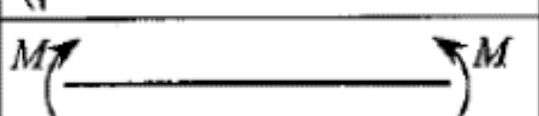
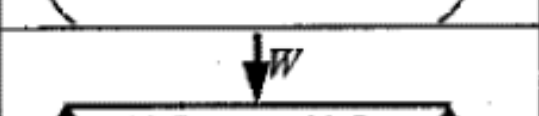
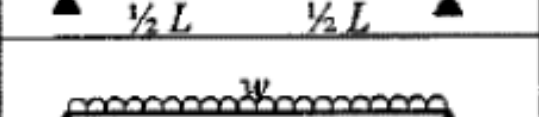
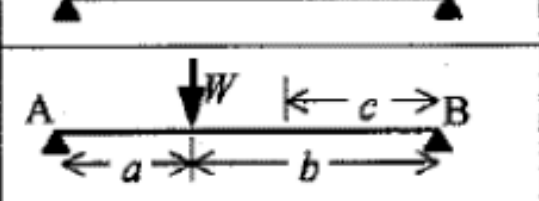
The following table gives suggested limits for calculated vertical deflections of certain members under the characteristic load combination due to variable loads and should not include permanent loads. Circumstances may arise where greater or lesser values would be more appropriate. Other members may also need deflection limits.

On low pitch and flat roofs the possibility of ponding should be investigated.

Vertical deflection	
Cantilevers	Length/180
Beams carrying plaster or other brittle finish	Span/360
Other beams (except purlins and sheeting rails)	Span/200
Purlins and sheeting rails	To suit the characteristics of particular cladding

Standard rules for maximum deflection:

BEAM BENDING

L = overall length W = point load, M = moment w = load per unit length	End Slope	Max Deflection	Max bending moment
	$\frac{ML}{EI}$	$\frac{ML^2}{2EI}$	M
	$\frac{WL^2}{2EI}$	$\frac{WL^3}{3EI}$	WL
	$\frac{wL^3}{6EI}$	$\frac{wL^4}{8EI}$	$\frac{wL^2}{2}$
	$\frac{ML}{2EI}$	$\frac{ML^2}{8EI}$	M
	$\frac{WL^2}{16EI}$	$\frac{WL^3}{48EI}$	$\frac{WL}{4}$
	$\frac{wL^3}{24EI}$	$\frac{5wL^4}{384EI}$	$\frac{wL^2}{8}$
 $a \leq b, c = \sqrt{\frac{1}{3}b(L+a)}$	$\theta_B = \frac{Wac^2}{2LEI}$ $\theta_A = \frac{L+b}{L+a} \theta_B$	$\frac{Wac^3}{3LEI}$ (at position c)	$\frac{Wab}{L}$ (under load)

Deflection Resistance Summary

1. Define Service loads (Actions)
2. Define Section and beam prosperities
3. Draw the bending moment diagram
4. Determine **Maximum deflection of beam**
5. Determine **Deflection limits**
6. Compare **Maximum deflection of beam** with **Deflection limits**

Design According to EC3: Unrestrained Beams

Conditions for ignoring the lateral-torsional buckling verification

The verification of lateral-torsional buckling for a member in bending may be ignored if at least **one of the following conditions** is verified:

$$\bar{\lambda}_{LT} \leq \bar{\lambda}_{LT,0} \text{ or } M_{Ed} / M_{cr} \leq \bar{\lambda}_{LT,0}^2$$

Where; $\bar{\lambda}_{LT,0} = 0,4$ (maximum value)

Improving the lateral torsional buckling resistance

In practical situations, for **given geometrical conditions**, **support conditions** and assumed loading, the lateral-torsional buckling behaviour of a member can be **improved** in two ways:

- **by increasing the lateral bending and/or torsional stiffness**, by increasing the **section or changing** from IPE profiles to HEA or HEB or to closed hollow sections (square, rectangular or circular);
- **by laterally bracing along the member the compressed part of the section** (the compressed flange in the case of I or H sections). This is more economical, although sometimes it **is not feasible**.

Design According to EC3: Unrestrained Beams

Bending Moment Resistance Summary:

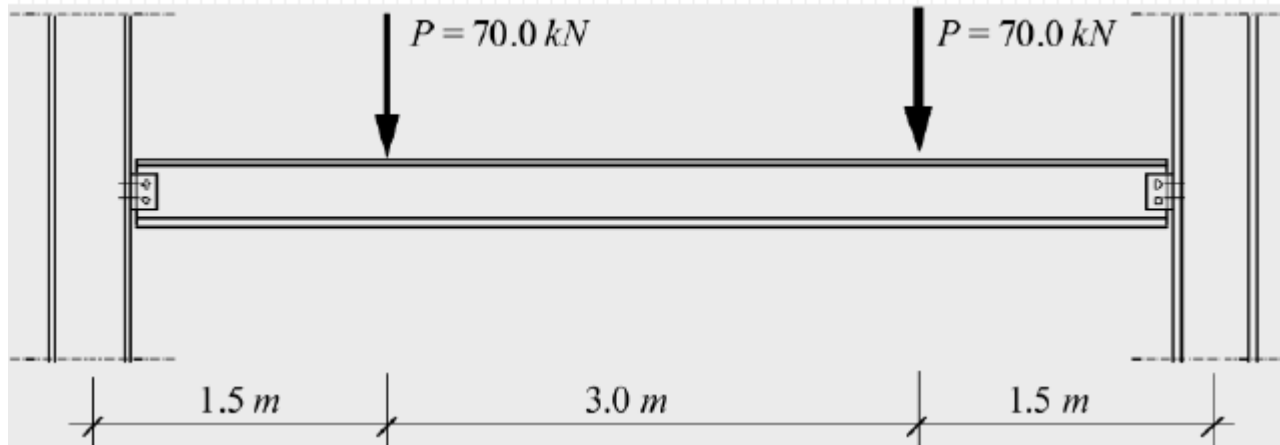
1. Draw the bending moment diagram to obtain the value of the maximum bending moment, M_{Ed} .
2. Determine f_y and calculate the **class of the section**. Once you know the class of the section then you will know which value of the **section modulus** you will need to use in the equation for $M_{b,Rd}$.
3. Work out the effective length, L_{cr} .
4. Work out the value of M_{cr} , the critical moment.
5. Work out the **lateral torsional slenderness ratio** using either the general case or alternative expression.
6. Work out Φ_{LT} using either the general case or alternative expression.
7. Work out χ_{LT} using either the general case or alternative expression.
8. Calculate the design buckling resistance $M_{c,Rd}$.
9. Carry out the buckling resistance $M_{c,Rd} > M_{Ed}$.

Worked Example: Example on cross-section resistance in bending

Example 4.4.

Consider the beam, supported by web cleats and loaded by two concentrated loads, $P=70.0\text{ kN}$ (design loads). Design the beam using a HEA profile, in S235 steel ($E=210\text{ GPa}$ and $G=81\text{ GPa}$), according to EC3-1-1. Consider free rotation at the supports with respect to the y-axis and the z-axis. Also assume free warping at the supports but consider that the web cleats do not allow rotation around the axis of the beam (x axis). Assume:

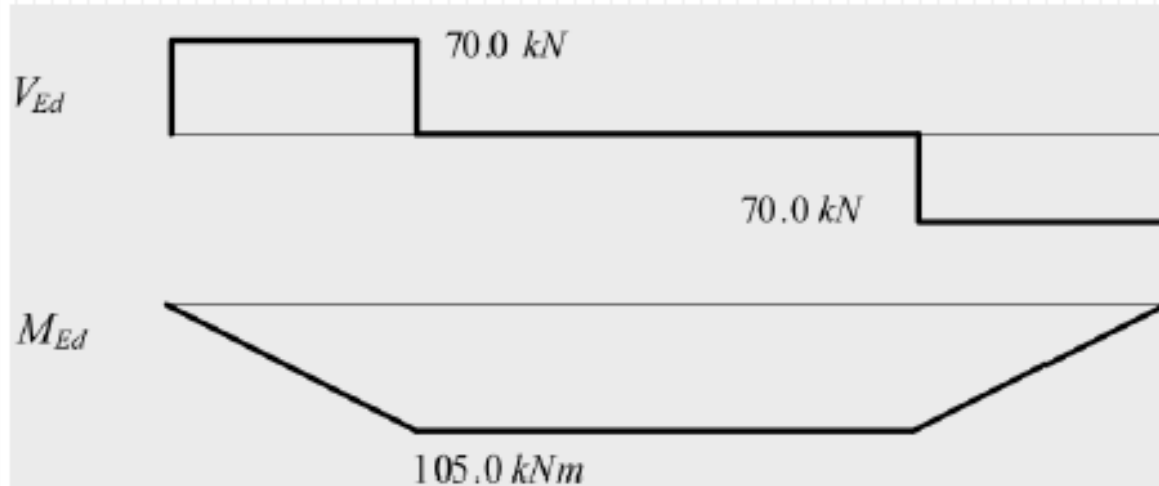
- Unbraced beam;
- Beam is braced at points of application of the concentrated loads.



Worked Example: Example on cross-section resistance in bending

Solution :a

Step1: Draw the internal action diagrams to get M_{Ed} & V_{Ed} .



Step2: Select a trial section and carryout the section classification.

Considering a HEA 240 profile.

Worked Example: Example on cross-section resistance in bending

The cross section class of a HEA 240 is obtained as follows

Web in bending, $\frac{c}{t} = \frac{164}{7.5} = 21.9 < 72 \varepsilon = 72 \times 1 = 72.0$

Flange in compression,

$$\frac{c}{t} = \frac{240/2 - 7.5/2 - 21}{12} = 7.9 < 9 \varepsilon = 9 \times 1 = 9$$

The HEA 240 is class 1,
confirming the use of $W_{pl,y}$

S 235 for $t \leq 16\text{mm}$

Material Properties:

HEA 240

- ▶ $W_{pl,y} = 744.6 \text{ cm}^3$
- ▶ $I_y = 7763 \text{ cm}^4$
- ▶ $I_z = 2769 \text{ cm}^4$
- ▶ $I_T = 41.55 \text{ cm}^4$
- ▶ $I_w = 328.5 \times 10^3 \text{ cm}^6$

- ▶ $f_y = 235 \text{ MPa}$
- ▶ $f_u = 390 \text{ MPa}$
- ▶ $E = 210 \text{ GPa}$
- ▶ $G = 81 \text{ GPa}$

Step3: Check for Lateral-torsional buckling without intermediate bracing [a].

$$\frac{M_{Ed}}{M_{b,Rd}} \leq 1.0,$$

Step3.1: Compute the buckling resistance

$$M_{b,Rd} = \chi_{LT} W_y f_y / \gamma_{M1},$$

$$W_y = W_{pl,y} \text{ for class 1} = 744.6 \text{ cm}^3$$

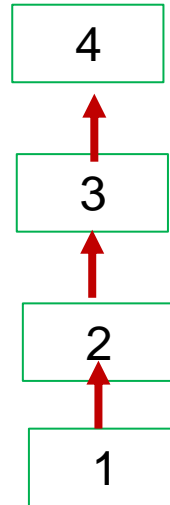
Worked Example: Example on cross-section resistance in bending

$$\chi_{LT} = \frac{1}{\phi_{LT} + \left(\phi_{LT}^2 - \bar{\lambda}_{LT}^2\right)^{0.5}}, \quad \text{but } \chi_{LT} \leq 1.0,$$

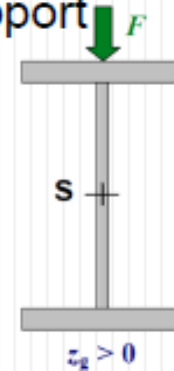
$$\phi_{LT} = 0.5 \left[1 + \alpha_{LT} (\bar{\lambda}_{LT} - 0.2) + \bar{\lambda}_{LT}^2 \right];$$

$$\bar{\lambda}_{LT} = \left[W_y f_y / M_{cr} \right]^{0.5}$$

$$M_{cr} = C_1 \frac{\pi^2 E I_z}{(k_z L)^2} \left\{ \left[\left(\frac{k_z}{k_w} \right)^2 \frac{I_w}{I_z} + \frac{(k_z L)^2 G I_T}{\pi^2 E I_z} + (C_2 z_g - C_3 z_j)^2 \right]^{0.5} - (C_2 z_g - C_3 z_j) \right\},$$



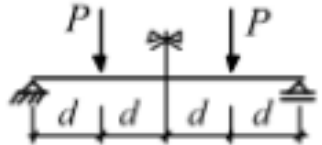

$L = 6.00 \text{ m}$
 $k_z = k_w = 1.0$, as the standard case support
 $z_g = 115 \text{ mm}$



Worked Example: Example on cross-section resistance in bending

$z_j = 0$ for beams with doubly symmetric cross section (such as I or H cross sections with equal flanges)

$C_1 = 1.04$, $C_2 = 0.42$ and $C_3 = 0.562$

Loading and support conditions	Diagram of moments	k_z	C_1	C_2	C_3
		1.0 0.5	1.04 0.95	0.42 0.31	0.562 0.539

1 $M_{cr} = 231.5 \text{ kNm} \Rightarrow \bar{\lambda}_{LT} = 0.87.$

2

Since $\alpha_{LT} = 0.21$ (H rolled section, with $h/b \leq 2$)

3 $\phi_{LT} = 0.95 \Rightarrow \chi_{LT} = 0.75.$

4

Compute the buckling resistance

$$M_{b,Rd} = \chi_{LT} W_y f_y / \gamma_{M1},$$

$$M_{b,Rd} = 0.75 \times 744.6 \times 10^{-6} \times \frac{235 \times 10^3}{1.0} = 131.2 \text{ kNm} > M_{Ed} = 105.0 \text{ kNm}$$

O.K.

Worked Example: Example on cross-section resistance in bending

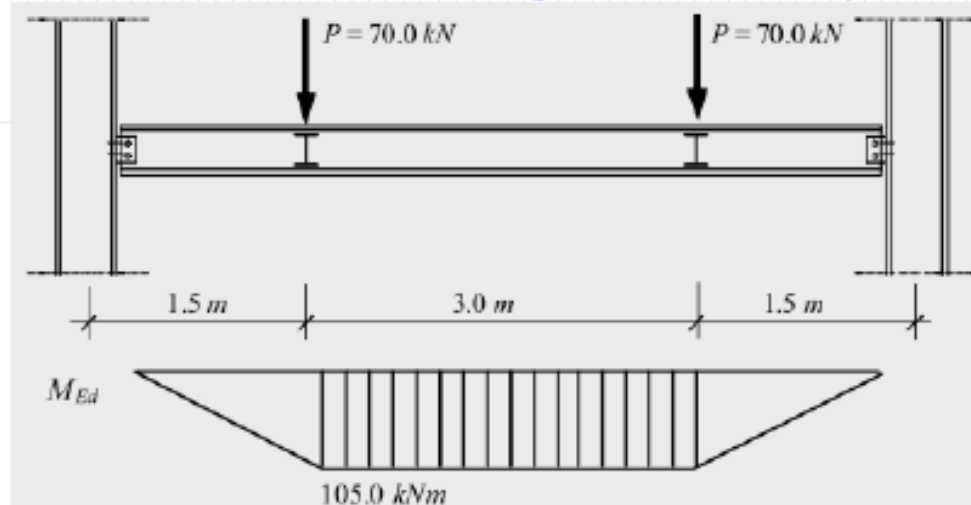
solution :b

Step4: Check for Lateral-torsional buckling with intermediate restraints [b].

Step4.1: Compute the buckling resistance

If the beam is laterally braced at the points of application of the loads, the lateral-torsional buckling behavior is improved.

$$\frac{M_{Ed}}{M_{b,Rd}} \leq 1.0 ,$$



Here a lesser profile of HEA 240 is selected which is checked to be of class 1, confirming the use of $W_{pl,y}$

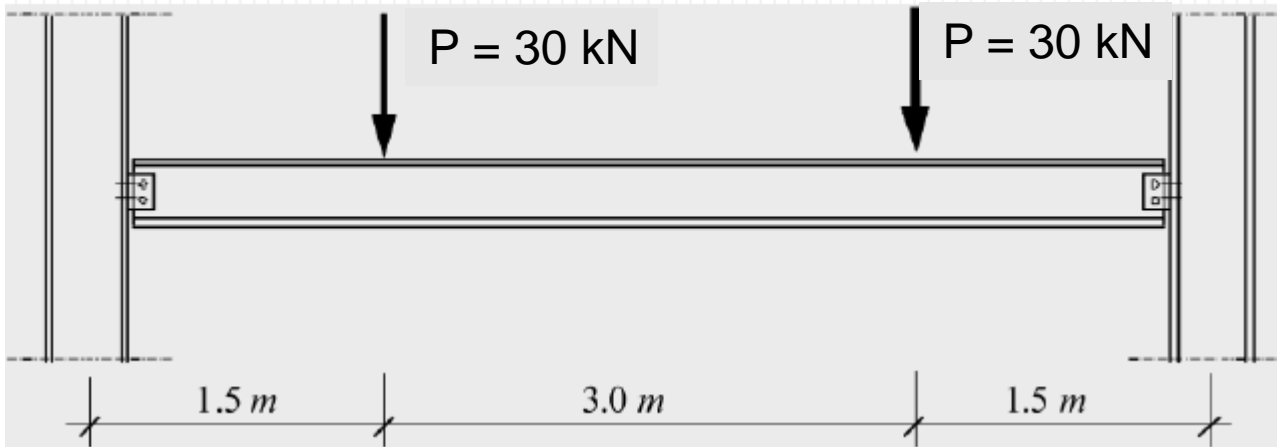
HEA 220

- ▶ $W_{pl,y} = 568.5 \text{ cm}^3$
- ▶ $I_T = 28.46 \text{ cm}^4$
- ▶ $I_z = 1955 \text{ cm}^4$
- ▶ $I_w = 193.3 \times 10^3 \text{ cm}^6$

Worked Example: Example on cross-section resistance in bending

Deflection Verification: SLS unfactored imposed actions.

Unfactored variable loads are shown below



Consider max deflection $\delta = \frac{waL^2}{12EI}$

$W = 30 \text{ kN}, a=1.5 \text{ m}, L=6\text{m}, E= 210000 \text{ N/mm}^2, I=7763 \cdot 10^4 \text{ mm}^4$

$$\delta = \frac{waL^2}{12EI} = \frac{30000 \times 1500 \times 6000^2}{12 \times 210000 \times 77630000} = 8.28 \text{ mm}$$

Vertical deflection limit:

$$\frac{L}{360} = \frac{6000}{360} = 16.7 \text{ mm} \quad \rightarrow \rightarrow 16.67 \text{ mm} > 8.28 \text{ mm} \text{ O.K.}$$

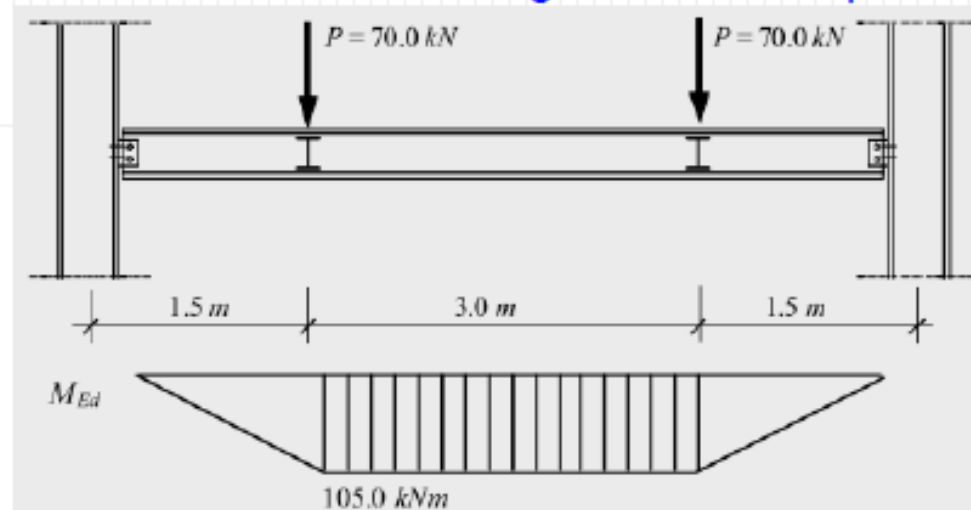
Worked Example: Example on cross-section resistance in bending

Step4: Check for Lateral-torsional buckling with intermediate restraints [b].

Step4.1: Compute the buckling resistance

If the beam is laterally braced at the points of application of the loads, the lateral-torsional buckling behavior is improved.

$$\frac{M_{Ed}}{M_{b,Rd}} \leq 1.0 ,$$



Here a lesser profile of HEA 240 is selected which is checked to be of class 1, confirming the use of $W_{pl,y}$

HEA 220

- ▶ $W_{pl,y} = 568.5 \text{ cm}^3$
- ▶ $I_T = 28.46 \text{ cm}^4$
- ▶ $I_z = 1955 \text{ cm}^4$
- ▶ $I_w = 193.3 \times 10^3 \text{ cm}^6$

Worked Example: Example on cross-section resistance in bending

$$\chi_{LT} = \frac{1}{\phi_{LT} + \left(\phi_{LT}^2 - \bar{\lambda}_{LT}^2\right)^{0.5}}, \quad \text{but } \chi_{LT} \leq 1.0,$$

$$\phi_{LT} = 0.5 \left[1 + \alpha_{LT} \left(\bar{\lambda}_{LT} - 0.2 \right) + \bar{\lambda}_{LT}^2 \right];$$

$$\bar{\lambda}_{LT} = \left[W_y f_y / M_{cr} \right]^{0.5}$$

$$M_{cr} = C_1 \frac{\pi^2 E I_z}{(k_z L)^2} \left\{ \left[\left(\frac{k_z}{k_w} \right)^2 \frac{I_w}{I_z} + \frac{(k_z L)^2 G I_T}{\pi^2 E I_z} + (C_2 z_g - C_3 z_j)^2 \right]^{0.5} \right. \\ \left. - (C_2 z_g - C_3 z_j) \right\},$$

$$L = \underline{3.00 \text{ m}}$$

$$k_z = k_w = 1.0, \text{ as the standard case support}$$



$z_g = 0$, The elastic critical moment of the beam is not aggravated by the fact that the loads are applied at the upper flange, because these are applied at sections that are laterally restrained.

$$W_v = W_{pl,v} \text{ for class 1} = \underline{568.5 \text{ cm}^3}$$

Worked Example: Example on cross-section resistance in bending

$z_j = 0$ for beams with doubly symmetric cross section (such as I or H cross sections with equal flanges)

$C_1 = 1.00$, $C_2 =$ not important as $Z_g=0$ and $C_3 = 1.0$

Loading and support conditions	Diagram of moments	k_z	C_1	C_3	
				$\psi_f \leq 0$	$\psi_f > 0$
		1.0	1.00	1.000	
		0.5	1.05	1.019	

$$M_{cr} = 551.3 \text{ kNm} \Rightarrow \lambda_{LT} = 0.49.$$

As $\alpha_{LT} = 0.21$ (rolled H section, with $h/b \leq 2$),

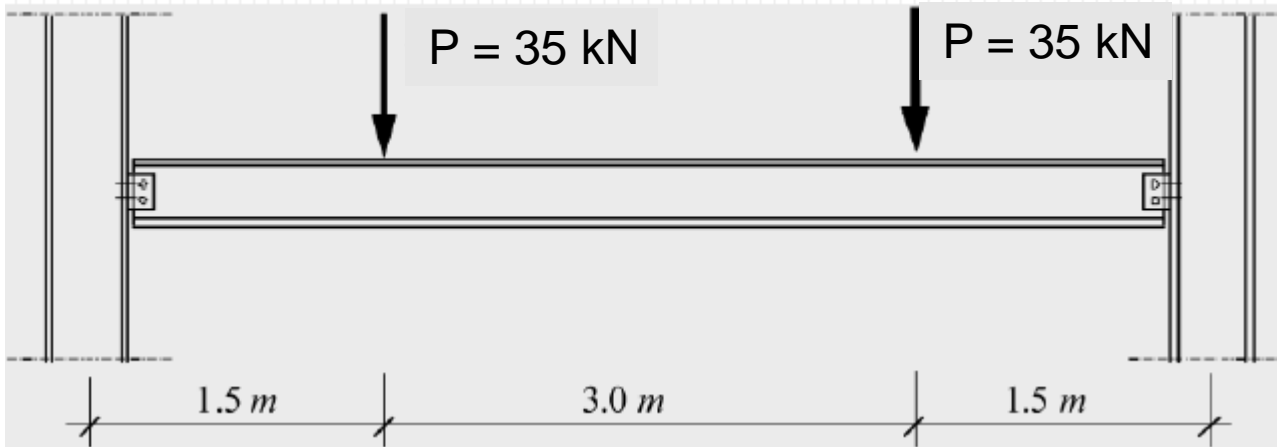
$$\phi_{LT} = 0.65 \Rightarrow \chi_{LT} = 0.93.$$

$$M_{b,Rd} = 0.93 \times 568.5 \times 10^{-6} \times \frac{235 \times 10^3}{1.0} = 124.2 \text{ kNm} > M_{Ed} = 105.0 \text{ kNm} \quad \text{O.K.}$$

Worked Example: Example on cross-section resistance in bending

Deflection Verification: SLS unfactored imposed actions.

Unfactored variable loads are shown below



Notes:

- Imposed (variable) Loads must be determined
- Max deflection must be calculated.

Consider max deflection $\delta = \frac{waL^2}{12EI}$

$W = 35 \text{ kN}$, $a=1.5 \text{ m}$, $L=6\text{m}$, $E = 210000 \text{ N/mm}^2$, $I=54100000 \text{ } 10^4 \text{ mm}^4$

$$\delta = \frac{waL^2}{12EI} = \frac{35000 \times 1500 \times 6000^2}{12 \times 210000 \times 54100000} = 13.86 \text{ mm}$$

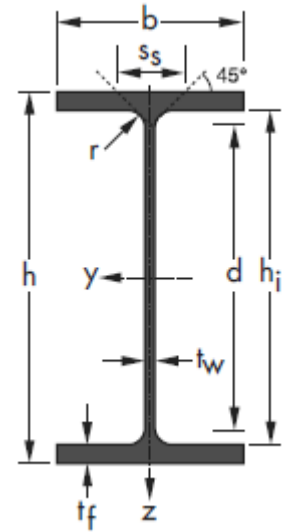
Vertical deflection limit:

$$\frac{L}{360} = \frac{6000}{360} = 16.7 \text{ mm} \quad \rightarrow \rightarrow 16.67 \text{ mm} > 13.86 \text{ mm} \text{ O.K.}$$

Worked Example: Example on cross-section resistance in bending

Summary

Criteria	Unbraced beam	Braced beam
LTB (General method)	HEA 240	HEA 220



G kg/m	h mm	b mm	tw mm	tf mm	r mm	A mm ²	hi mm	d mm
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						x 10 ²			
HE 240 AA*	47,4	224	240	6,5	9	21	60,4	206	164
HE 240 A	60,3	230	240	7,5	12	21	76,8	206	164

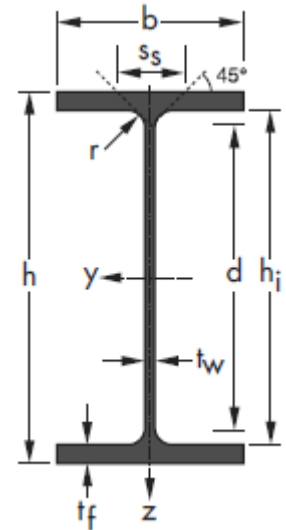
G kg/m	Iy mm ⁴	W _{el.y} mm ³	W _{pl.y} ♦ mm ³	iy mm	A _{vz} mm ²	Iz mm ⁴	W _{el.z} mm ³	W _{pl.z} ♦ mm ³	iz mm	ss mm	I _t mm ⁴	I _w mm ⁶
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	x 10 ⁴	x 10 ³	x 10 ³	x 10	x 10 ²	x 10 ⁴	x 10 ³	x 10 ³	x 10		x 10 ⁴	x 10 ⁹	
HE 240 AA	47,4	5835	521,0	570,6	9,83	21,54	2077	173,1	264,4	5,87	49,10	22,98	239,6
HE 240 A	60,3	7763	675,1	744,6	10,05	25,18	2769	230,7	351,7	6,00	56,10	41,55	328,5

Worked Example: Example on cross-section resistance in bending

Summary

Criteria	Unbraced beam	Braced beam
LTB (General method)	HEA 240	HEA 220



	G kg/m	h mm	b mm	t_w mm	t_f mm	r mm	A mm ²	h_i mm	d mm
HE 220 A	50,5	210	220	7	11	18	64,3	188	152

	G kg/m	I_y mm ⁴	$W_{el,y}$ mm ³	$W_{pl,y} \blacklozenge$ mm ³	i_y mm	A_{vz} mm ²	I_z mm ⁴	$W_{el,z}$ mm ³	$W_{pl,z} \blacklozenge$ mm ³	i_z mm	s_s mm	I_t mm ⁴	I_w mm ⁶
		$\times 10^4$	$\times 10^3$	$\times 10^3$	$\times 10$	$\times 10^2$	$\times 10^4$	$\times 10^3$	$\times 10^3$	$\times 10$		$\times 10^4$	$\times 10^9$
HE 220 A	50,5	5410	515,2	568,5	9,17	20,67	1955	177,7	270,6	5,51	50,09	28,46	193,3